

# Three Parts

1. What are Artificial Intelligence, Machine Learning, and Deep Learning?
2. Deep Learning
3. Probabilistic Circuits and the Automated Scientist

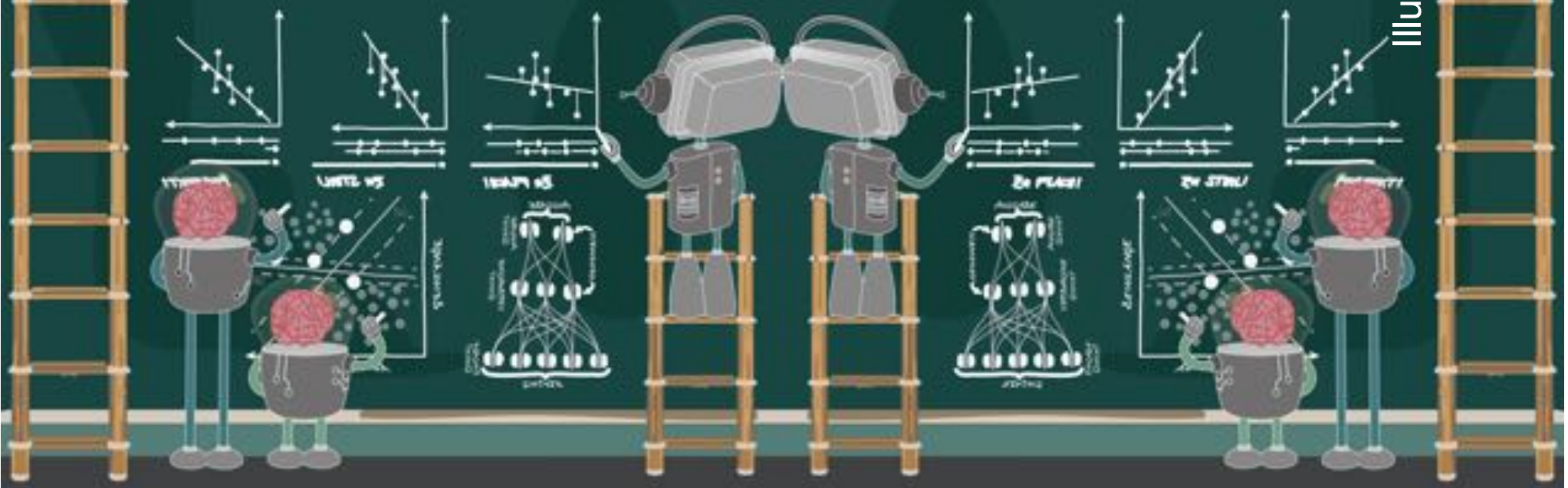


Kristian Kersting

# A Short History of Time Artificial Intelligence, Machine Learning, and Deep Learning

Thanks to Christoph Lampert and Constantin Rothkopf for some of the slides

Illustration Nanina Föhr



# Solving Rubik's Cube?



[OpenAI: https://www.youtube.com/watch?v=x4O8pojMF0w](https://www.youtube.com/watch?v=x4O8pojMF0w)

# **Your turn!**

**What do you think? Is this AI? Is this just Machine Learning? Is this at the level of humans? Is this overselling?**

**You have 5 minutes!**

# The dream of an artificially intelligent entity is not new



Talos, an ancient mythical automaton with artificial intelligence

# The dream of an artificially intelligent entity is not new



Leibniz „philosophises about ‘artificial intelligence’ (AI). In order to prove the impossibility of thinking machines, Leibniz imagines of ‘a machine from whose structure certain thoughts, sensations, perceptions emerge’“ — Gero von Randow, ZEIT 44/2016

# AI today

**the INQUIRER**

Artificial Intelligence Internet of Things Open Source Hardware Software Security

## Artificial intelligence will create the next industrial revolution, experts claim

Recent computer systems will replace the need for human-  
responsible for the next industrial revolution.  
computer systems replace certain

## Artificial intelligence better than scientists at choosing successful embryos

'We won't waste time on treatments that won't work, so the patient should get says clinic director

lane Kirby | 22 hours ago | 0 comments



**BBC** Sign in

**NEWS** Technology

News Sport Weather Shop

## Stephen Hawking warns artificial intelligence could end mankind



"Humans, who are limited by slow biological evolution, couldn't compete and would be

**Telegraph** HOME NEWS

Lifestyle · Cars · News

## Self-driving Tesla 'saved' by steering him to hos

share



**Elon Musk** @elonmusk

I've talked to Mark about this. His understanding of the subject is limited.



SCIENTIFIC AMERICAN DECEMBER 2016

## Computers Now Recognize Patterns Better Than Humans Can

An approach to artificial intelligence that enables computers to recognize visual patterns better than humans are able to do

# AI today

## THE ECONOMIC IMPACT OF ARTIFICIAL INTELLIGENCE



Projected Global  
Economic Effects  
of AI by 2030

Source: PwC



# So, AI has many faces

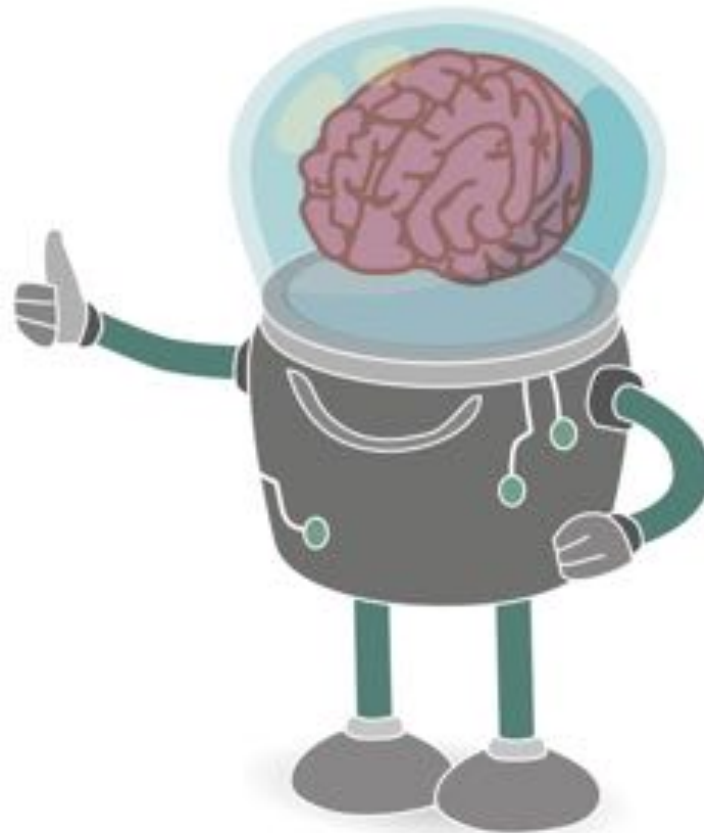
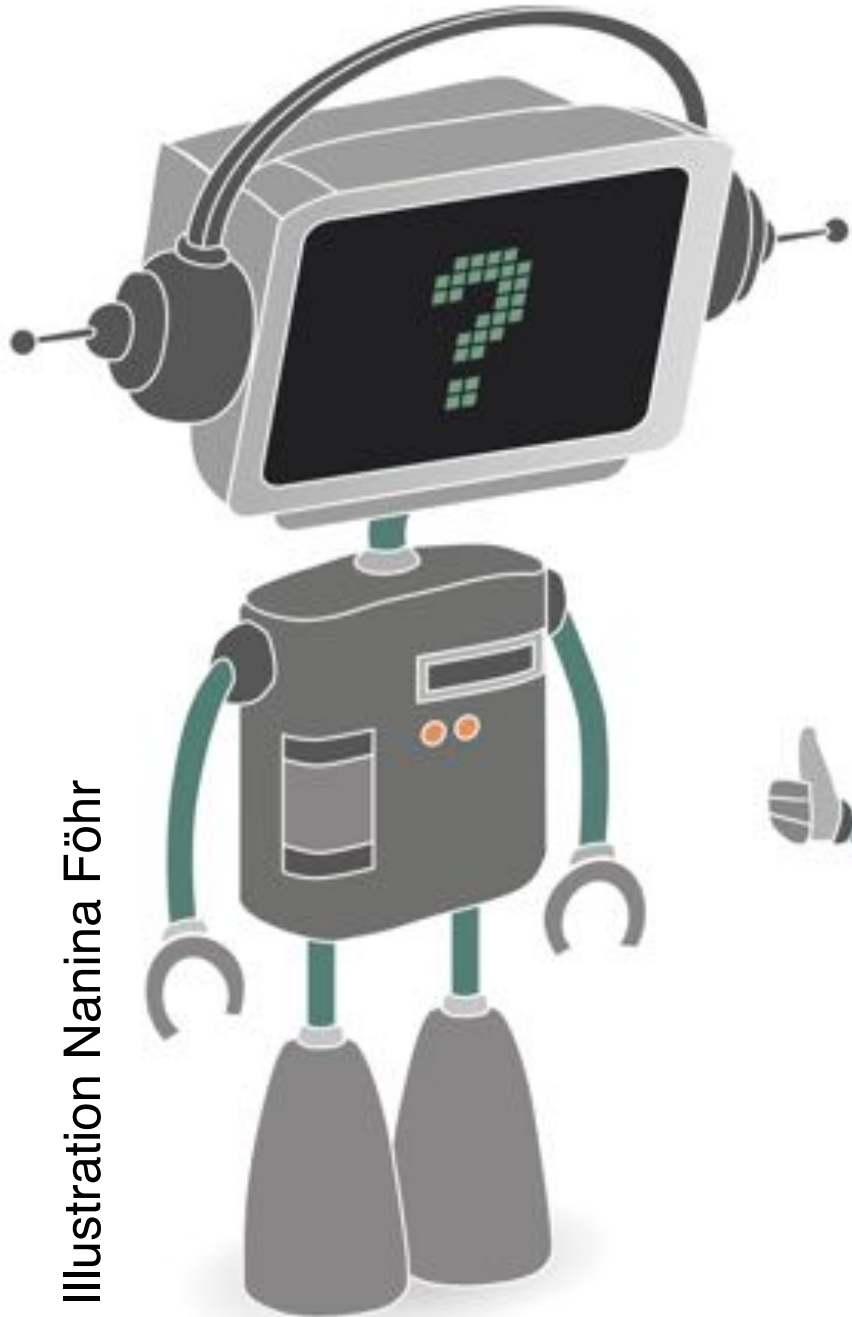


**Saviour of  
the world**



**Downfall of  
humanity**

**But, what  
exactly is AI?**



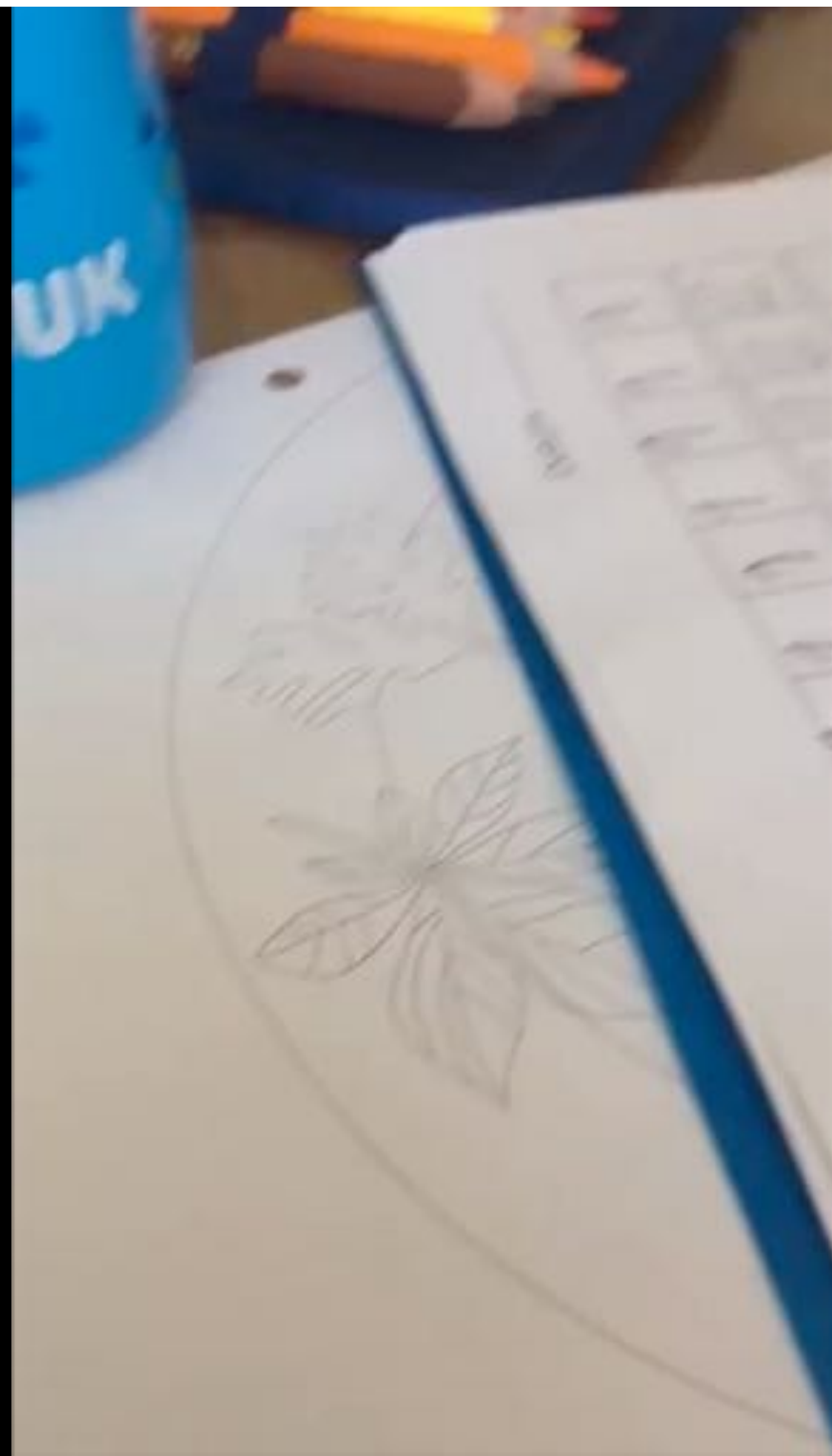
**Your turn!**


**What do you think is AI?**

**You have 5 minutes!**

**Humans are  
considered  
to be smart**

<https://www.youtube.com/watch?v=XQ79UUIOeWc>



A large window with a dark frame and a grid pattern of panes. The window is looking out onto a bright, hazy outdoor scene with trees. The text "Are flies smart?" is overlaid on the bottom half of the image.

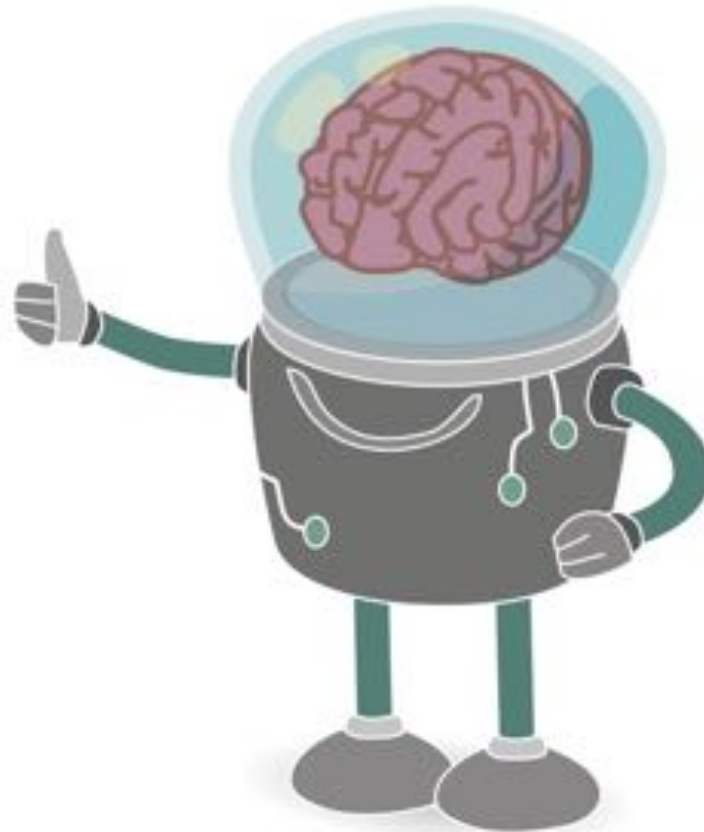
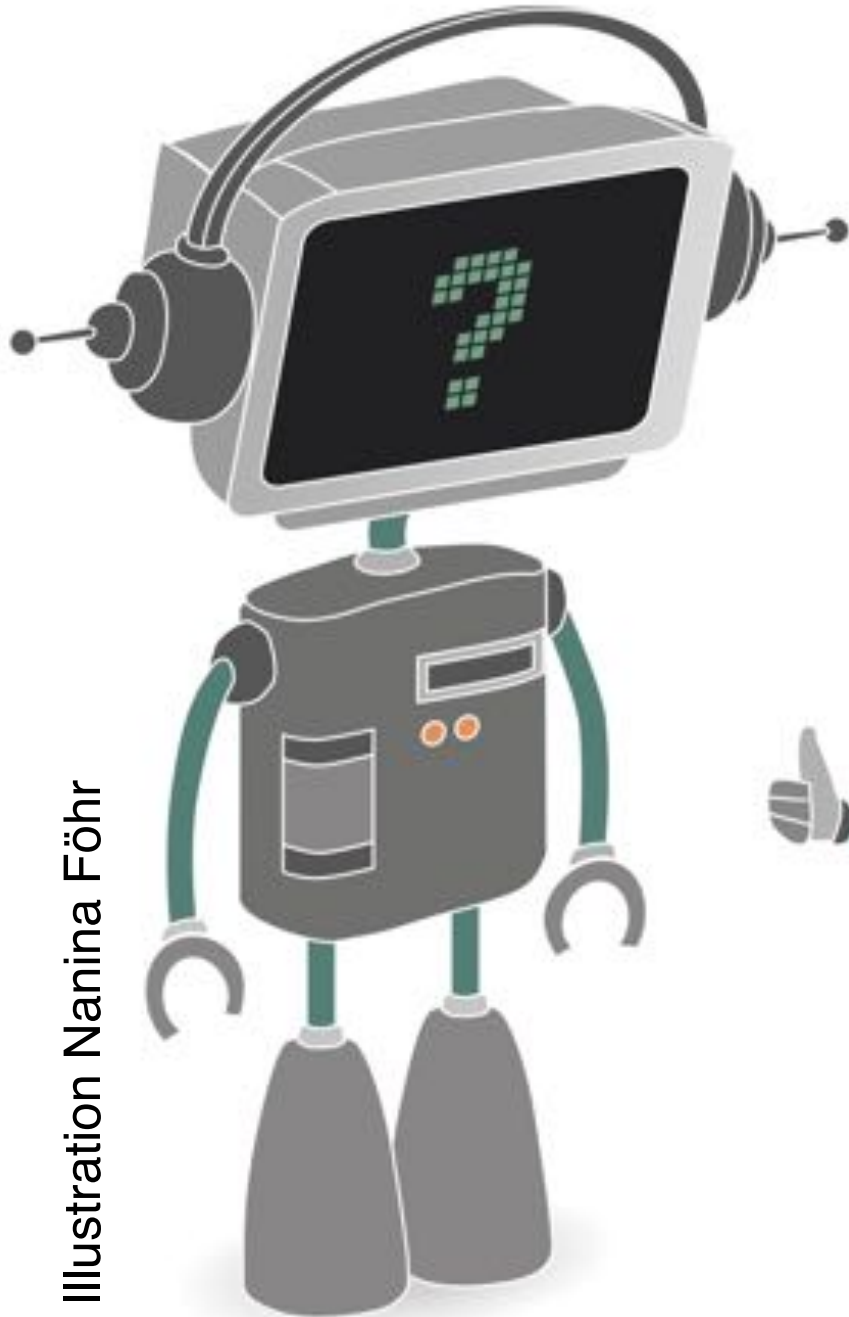
**Are flies smart?**



**What about orangutans?**

Intelligence has many qualities.

It is difficult to directly capture/measure it.

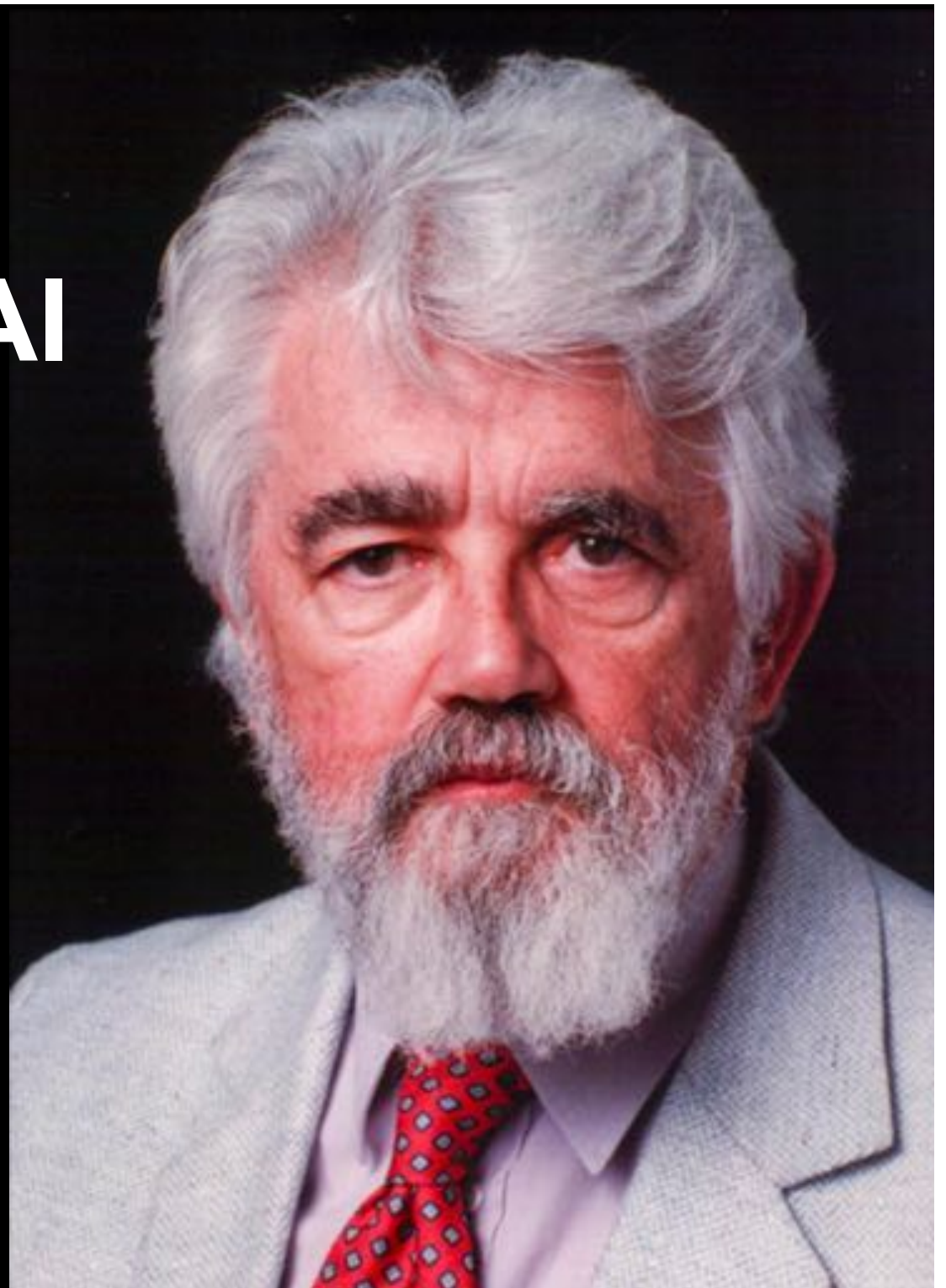


# The Definition of AI

*„the science and engineering of making intelligent machines, especially intelligent computer programs.*

*It is related to the similar task of using computers to understand human intelligence, but AI does not have to confine itself to methods that are biologically observable.“*

- John McCarthy, Stanford (1956),  
coined the term AI, Turing Awardee

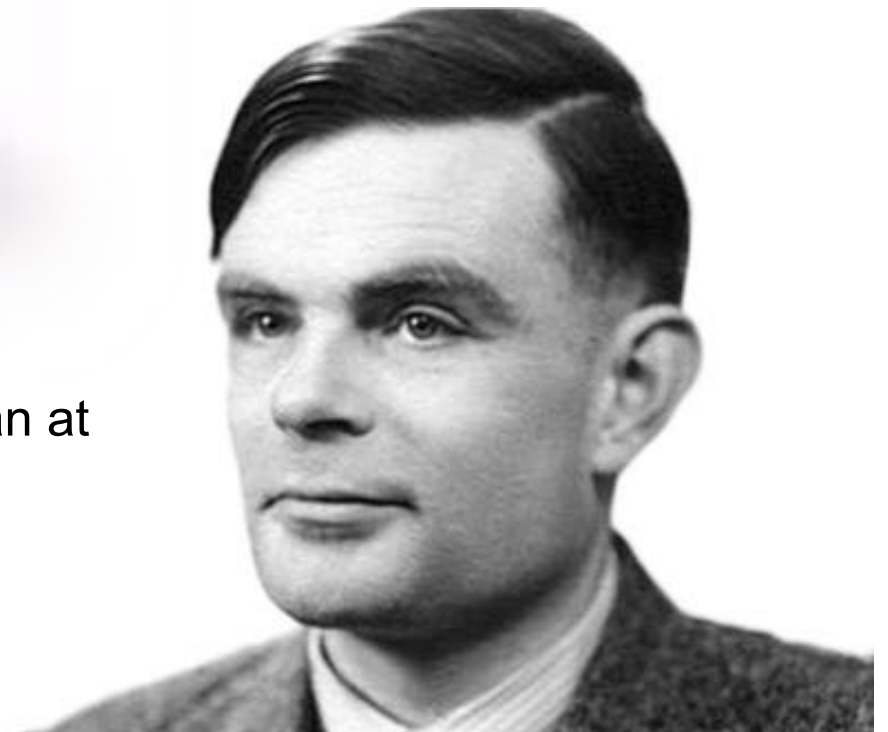




# Turing Award = Nobel Prize for Computing



Named after Alan Turing, a British mathematician at the University of Manchester. Turing is often credited as being the key founder of theoretical computer science and AI.

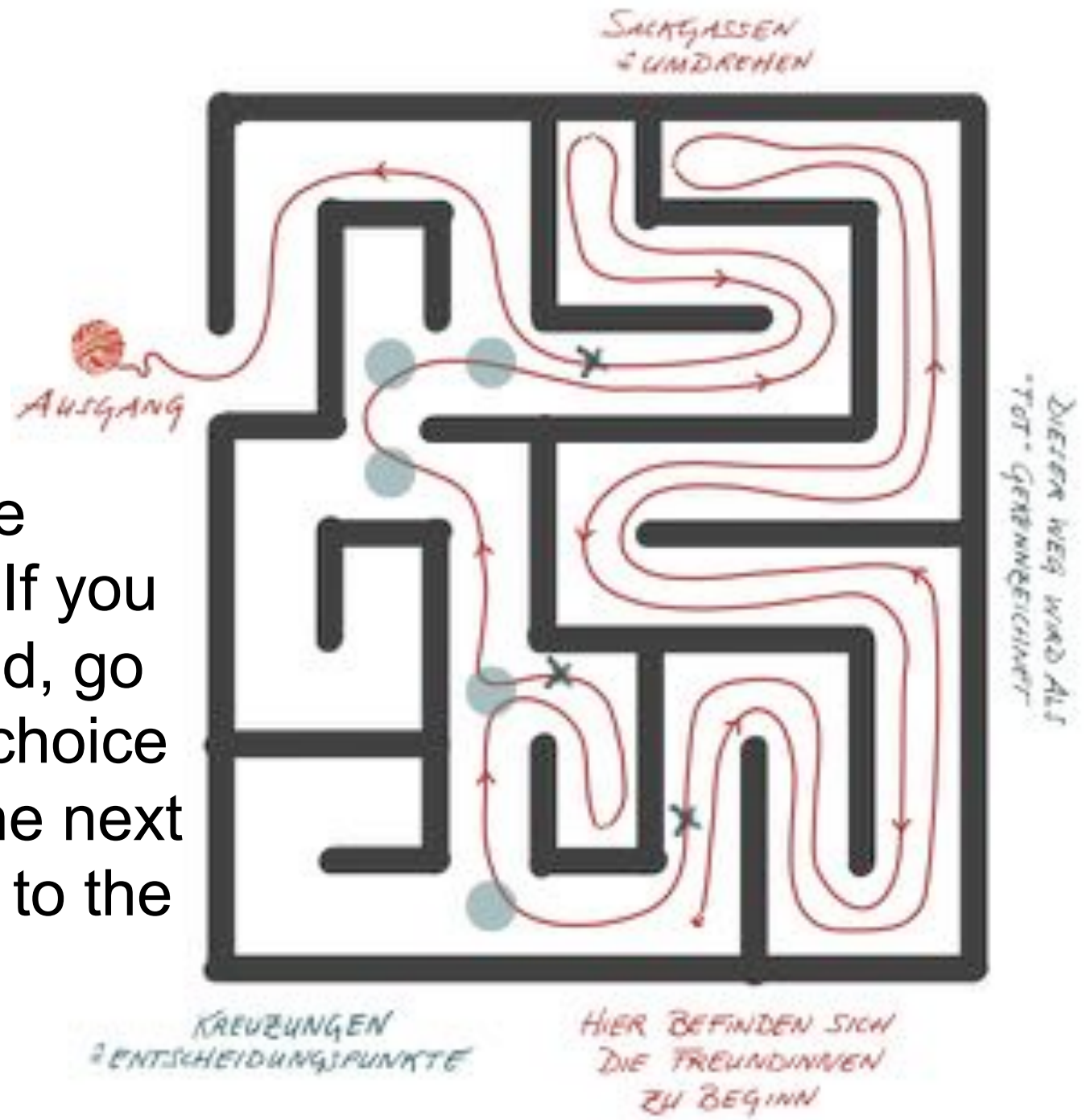


**AI wants to build intelligent computer programs. How do we do this?**

**We use algorithms:**  
unambiguous specifications  
of how to solve a class of  
problems – in finite time.



Always follow the right-hand path. If you reach a dead-end, go back to the last choice point and take the next unexplored path to the right.





**Think of it as a recipe!**

Learning

Thinking

Planning

**AI = Algorithms for ...**

Vision

Behaviour


Reading

# Machine Learning

the science "concerned with the question of how to construct computer programs that automatically improve with experience"

- Tom Mitchell (1997) CMU





# Deep Learning

a form of machine learning that makes use of artificial neural networks



Geoffrey Hinton  
Google  
Univ. Toronto (CAN)



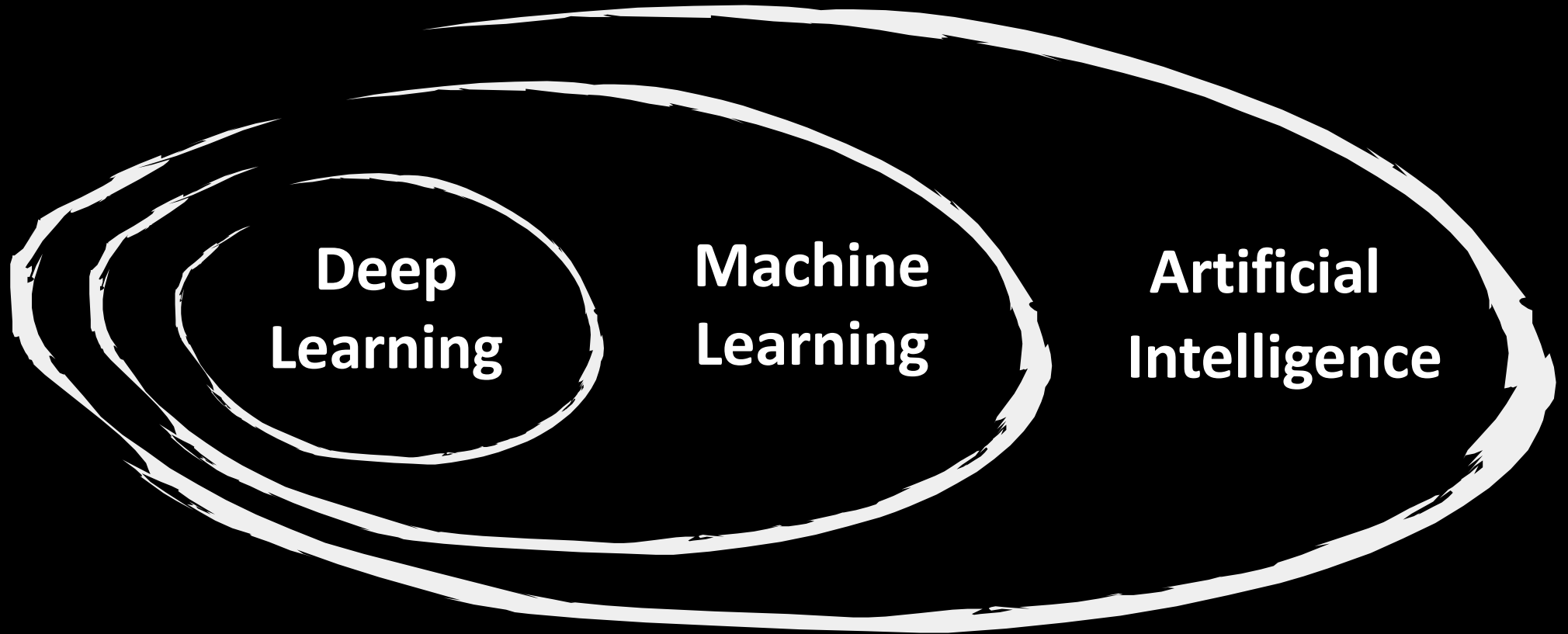
Yann LeCun  
Facebook (USA)



Yoshua Bengio  
Univ. Montreal (CAN)

Turing Awardees 2019

# Overall Picture



**Deep  
Learning**

**Machine  
Learning**

**Artificial  
Intelligence**



# **Your turn?**

**Which examples for AI do you know?  
Where do you think ML is used? Do  
you know an example for ML that is  
not DL?**

**You have 5 minutes!**

A closer look at  
**the history of AI**

ONCE  
UPON A TIME

# 1956 Birth of AI

A Proposal for the  
DARTMOUTH SUMMER RESEARCH PROJECT ON ARTIFICIAL INTELLIGENCE

We propose that a 2 month, 10 man study of artificial intelligence be carried out during the summer of 1956 at Dartmouth College in Hanover, New Hampshire. The study is to proceed on the basis of the conjecture that every aspect of learning or any other feature of intelligence can in principle be so precisely described that a machine can be made to simulate it. An attempt will be made to find how to make machines use language, form abstractions and concepts, solve kinds of problems now reserved for humans, and improve themselves. We think that a significant advance can be made in one or more of these problems if a carefully selected group of scientists work on it together for a summer.



**John McCarthy**  
Turing Award 1971



**Marvin Minsky**  
Turing Award 1969



**Allen Newell**  
Turing Award 1975



**Herbert A. Simon**  
Turing Award 1975  
Nobel Prize 1978

**... and of  
Cognitive Science**

# Artificial Neural Networks

COGNITIVE SCIENCE **14**, 179–211 (1990)

## Learning representations by back-propagating errors

David E. Rumelhart\*, Geoffrey E. Hinton†  
& Ronald J. Williams\*

\* Institute for Cognitive Science, C-015, University of California,  
San Diego, La Jolla, California 92093, USA

† Department of Computer Science, Carnegie-Mellon University,  
Pittsburgh, Philadelphia 15213, USA

## Finding Structure in Time

JEFFREY L. ELMAN

*University of California, San Diego*

COGNITIVE SCIENCE **9**, 147–169 (1985)

## A Learning Algorithm for Boltzmann Machines\*

DAVID H. ACKLEY  
GEOFFREY E. HINTON

*Computer Science Department  
Carnegie-Mellon University*

TERRENCE J. SEJNOWSKI

*Biophysics Department  
The Johns Hopkins University*

## Biological Cybernetics

© by Springer-Verlag 1980

Biol. Cybernetics **36**, 193–202 (1980)

## Neocognitron: A Self-organizing Neural Network Model for a Mechanism of Pattern Recognition Unaffected by Shift in Position

Kunihiko Fukushima

NHK Broadcasting Science Research Laboratories, Kinuta, Setagaya, Tokyo, Japan

*Psychological Review*  
1981, Vol. **88**, No. 2, 135–170

Copyright 1981 by the American Psychological Association, Inc.  
0033-295X/81/8802-0135\$00.75

*Psychological Review*  
Vol. **65**, No. **6**, 1958

## THE PERCEPTRON: A PROBABILISTIC MODEL FOR INFORMATION STORAGE AND ORGANIZATION IN THE BRAIN<sup>1</sup>

F. ROSENBLATT

*Cornell Aeronautical Laboratory*

## Toward a Modern Theory of Adaptive Networks: Expectation and Prediction

Richard S. Sutton and Andrew G. Barto  
Computer and Information Science Department  
University of Massachusetts—Amherst

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*Computer and Information Science Department  
University of Massachusetts—Amherst*

slide after C. Rothkopf (TUD), after J. Tenenbaum (MIT)

# Algorithms of intelligent behaviour teach us a lot about ourselves

## The twin science: cognitive science

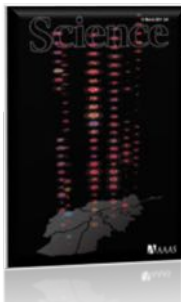
"How do we humans get so much from so little?" and by that I mean how do we acquire our understanding of the world given what is clearly by today's engineering standards so little data, so little time, and so little energy.

### Centre for Cognitive Science at TU Darmstadt

Establishing cognitive science at the Technische Universität Darmstadt is a long-term commitment across multiple departments (see [Members](#) to get an impression on the interdisciplinary of the supporting groups and departments). The TU offers a strong foundation including several established top engineering groups in Germany, a prominent computer science department (which is among the top four in Germany), a



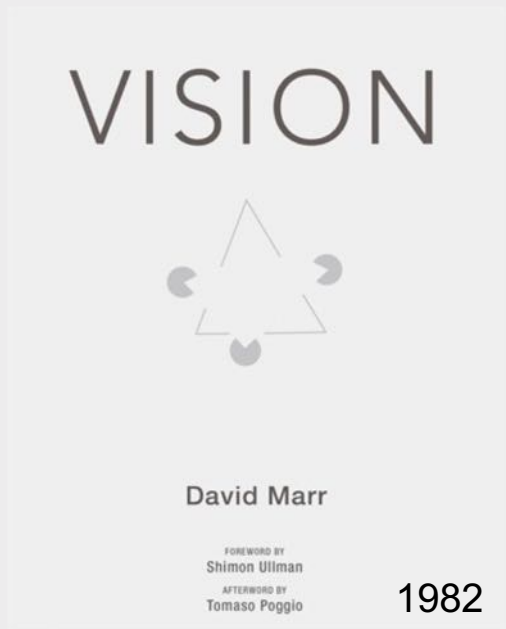
Josh Tenenbaum, MIT



Lake, Salakhutdinov, Tenenbaum, Science 350 (6266), 1332-1338, 2015

Tenenbaum, Kemp, Griffiths, Goodman, Science 331 (6022), 1279-1285, 2011

# Three levels of description



## Computational

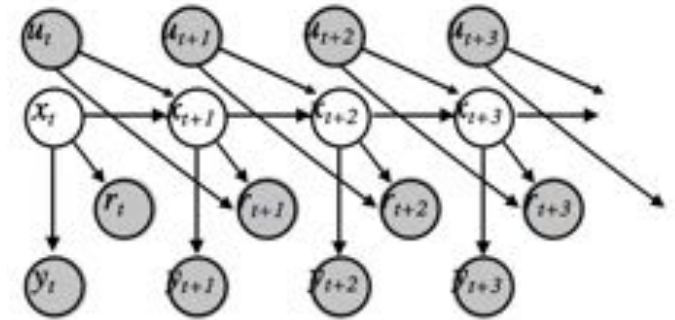
Why do things work the way they work? What is the goal of the computation? What are the unifying principles?

maximize:

$$R_t = r_{t+1} + r_{t+2} + \dots + r_T$$

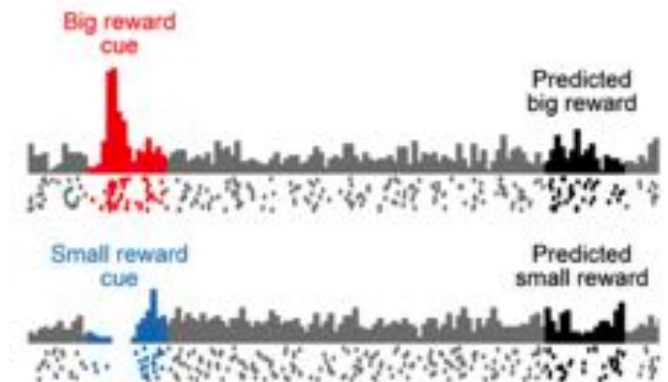
## Algorithmic

What representation can implement such computations? How does the choice of the representation determine the algorithm



## Implementational

How can such a system be built in hardware?  
How can neurons carry out the computations?



slide after C. Rothkopf (TUD)

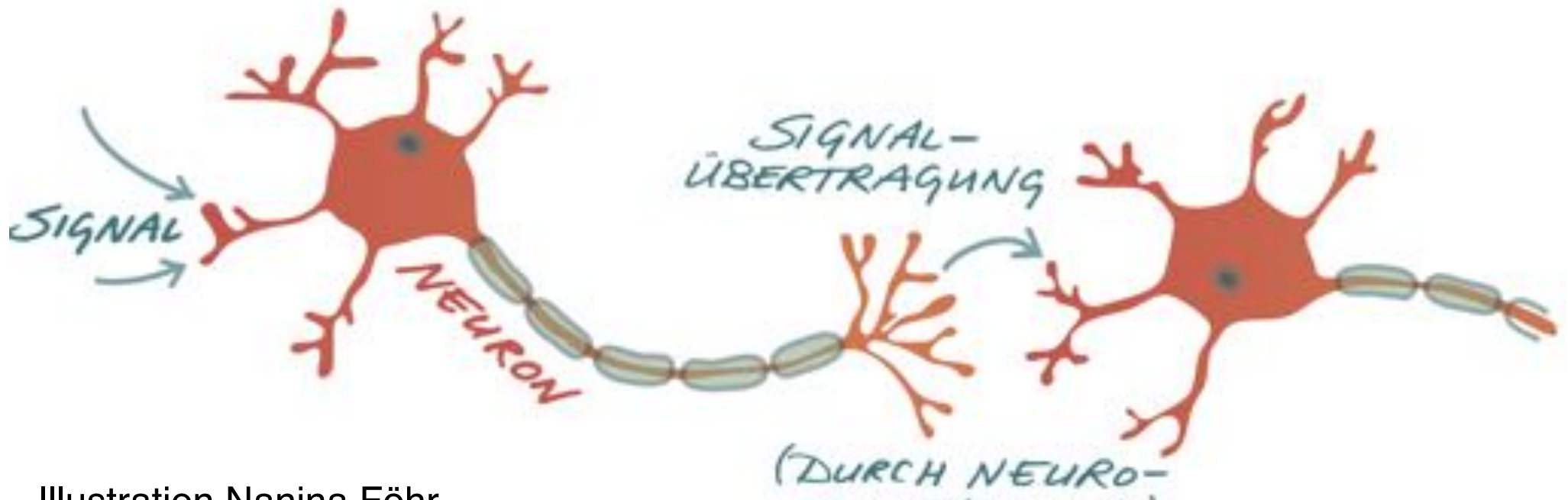
# Artificial Neural Networks

Inspiration from the brain:

- many small interconnected units (neurons)
- learning happens by changing the strength of connections (synapses)
- behavior of the whole is more than the sum of the parts



Frank  
Rosenblatt  
(1928-1971)





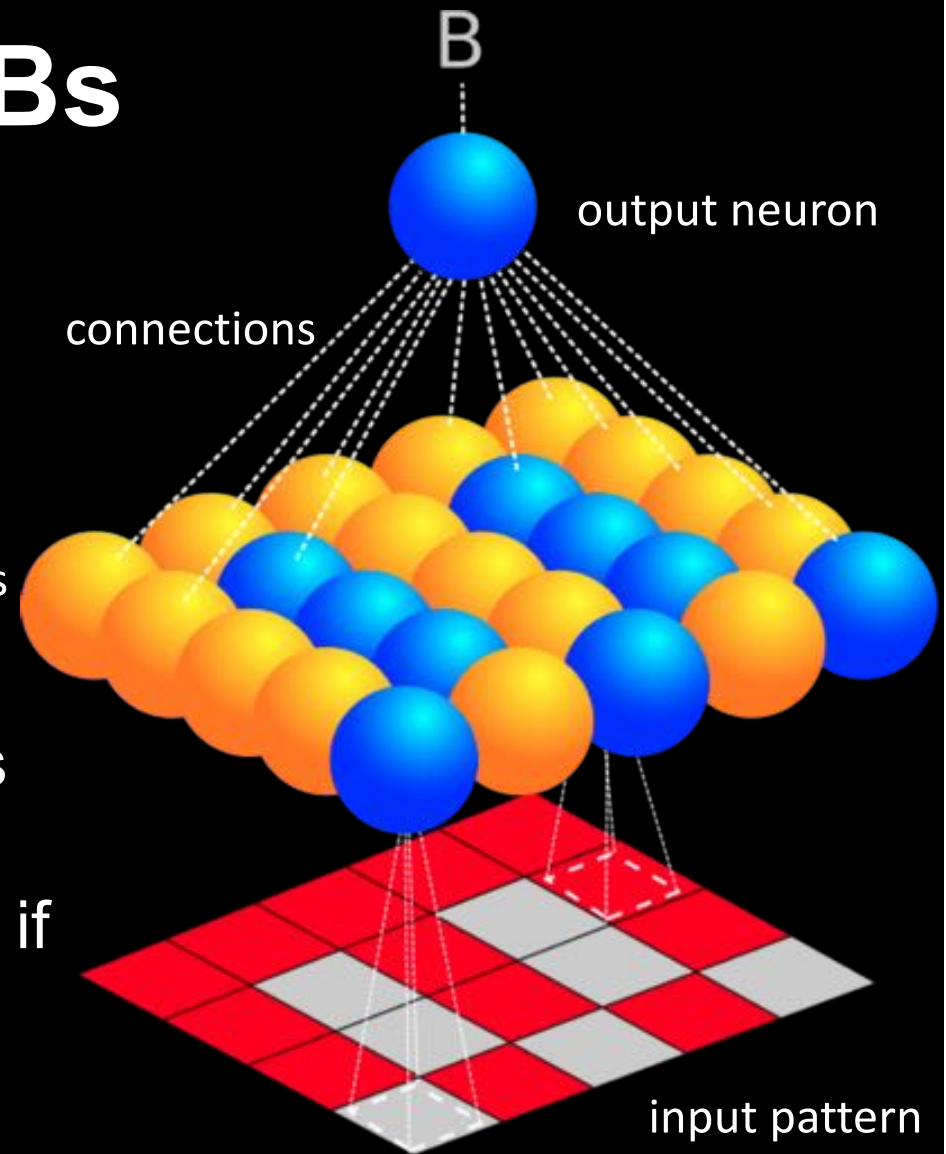
# The Perceptron to distinguish As and Bs

1) present pattern

2) some first layer neurons spike

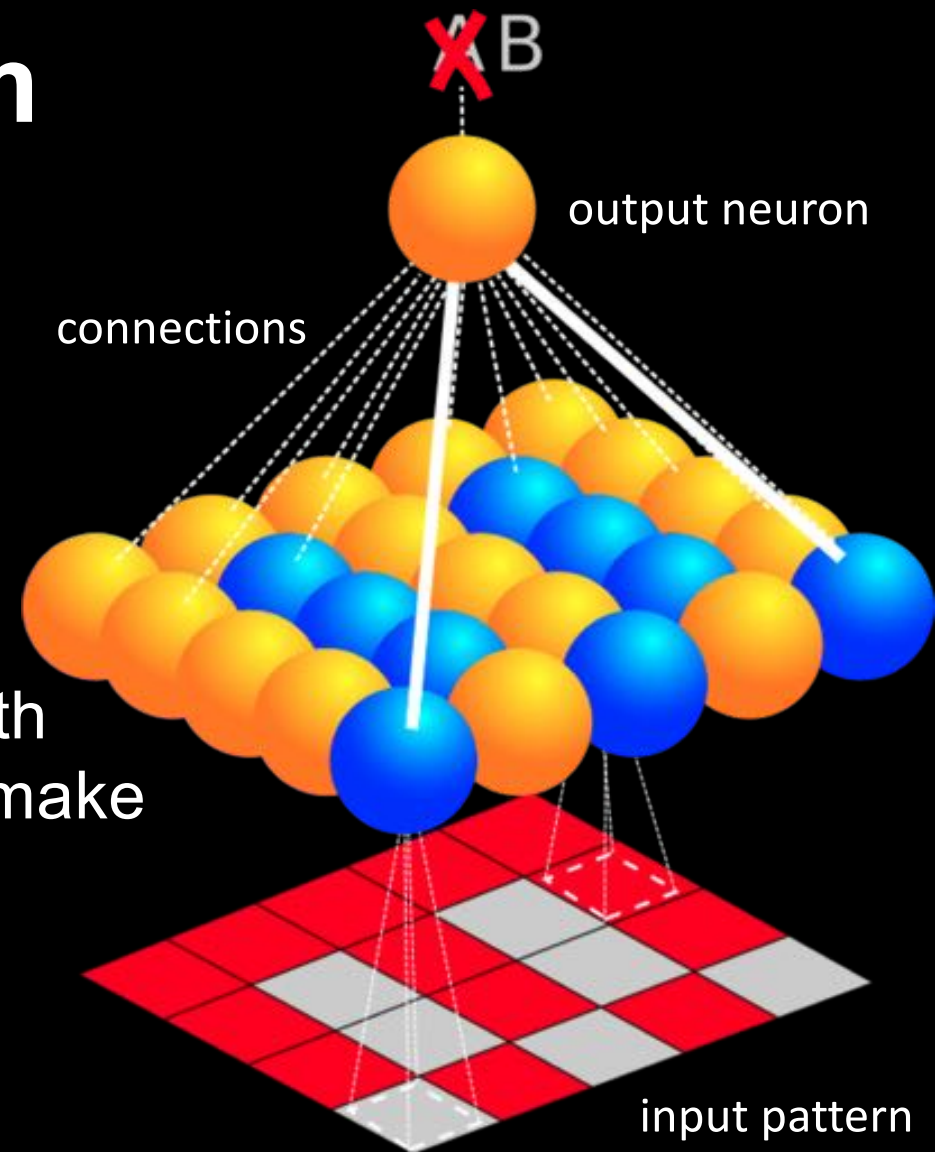
3) output neuron accumulates signals from previous layer; if it is above a threshold, the output neuron spikes and predicts an A; if not, then it does not spike and predicts a b

4) prediction is "B"



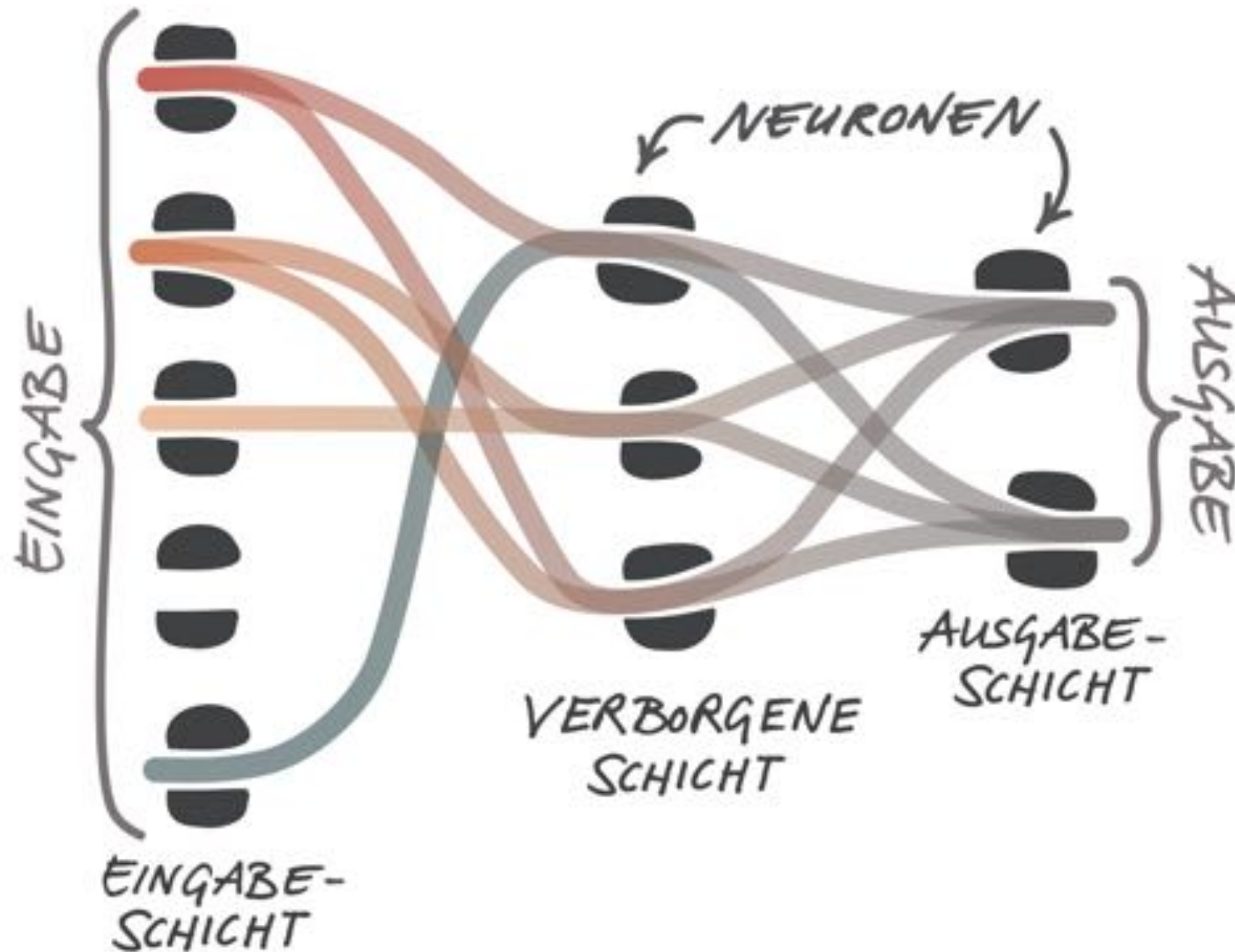
# The Perceptron Learning Algorithm

- 1) present pattern
- 2) wait for output to be produced
- 3) if output correct
  - change nothing
- 4) if output incorrect:
  - adjust connection strength (positive or negative) to make the pattern be classified correctly
- 5) repeat until no more errors

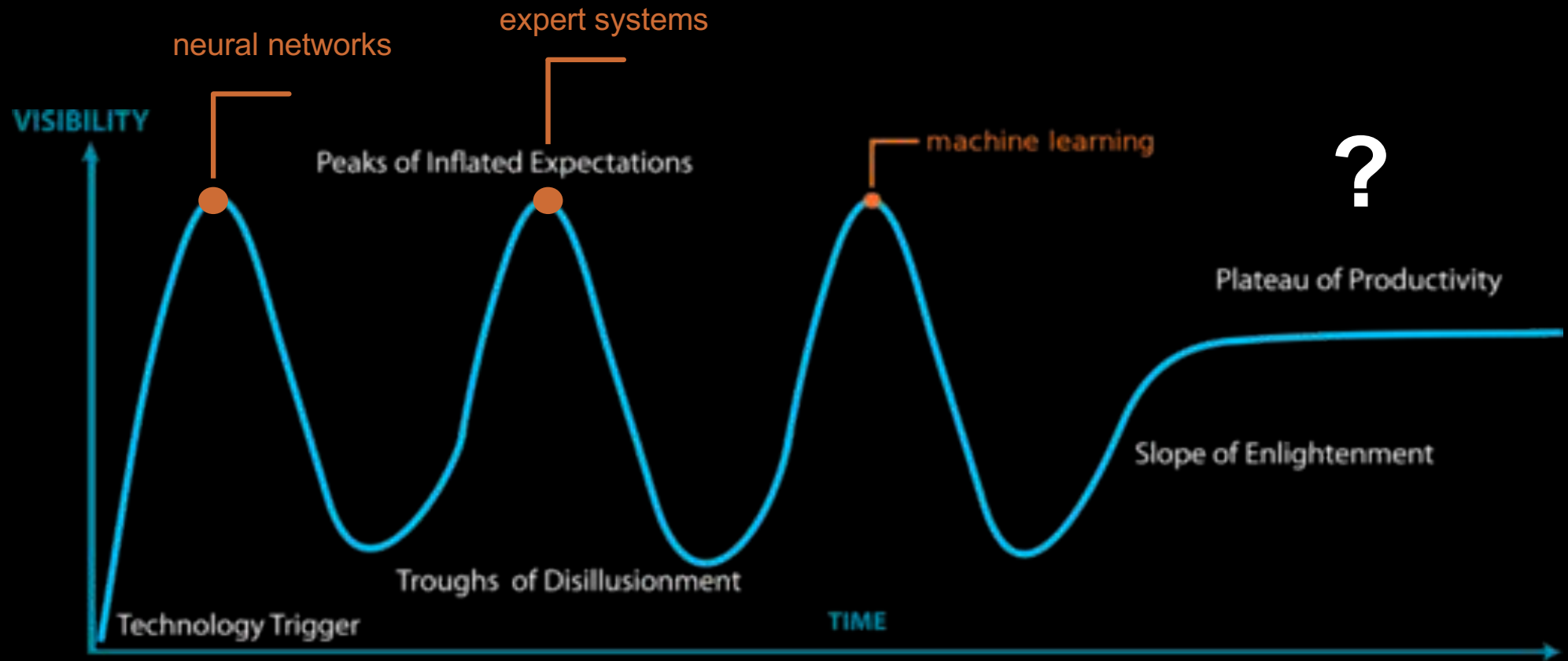


# Artificial Neural Networks

= Stacking of many artificial neurons



# The history of AI in a nutshell



1956

2019

**What's different  
now than it  
used to be?**

**#1 models are bigger**

**#2 we have more data**

**#3 we have more compute power**

**#4 the systems actually work for several tasks**



# AI drives cars





**AI does the  
laundry**

# AI knows a lot

SPIEGEL TV WISSEN







**AI is an Artist**






### Schachmatt durch „CrazyAra“

**Künstliche Intelligenz schlägt mehrfachen Weltmeister im Einsetzschach**

Der von den TU-Studierenden Johannes Czech, Moritz Willig und Alena Beyer entwickelte Bot „CrazyAra“ hat den Schachprofi Justin Tan in einem Online-Match der Schach-Variante „Crazyhouse“ mit 4:1 geschlagen. Gelernt hat der Bot mittels künstlicher neuronaler Netze, was ihm erlaubt, vorausschauend Entscheidungen zu treffen. Das Besondere: Die Studierenden konnten damit einen Erfolg auf einem Feld feiern, das sonst von Giganten wie Google dominiert wird.

# AI plays chess and GO



 CrazyAra vs JannLee (Man vs Machine - Crazyhouse Chess on Lichess.org) · 2 days ago  
Category: Chess

# AI assists you



# **Your turn!**

**What do you think? Are we done? Is  
a AI just a success?**

**You have 5 minutes!**

The New York Times

Opinion



# A.I. Is Harder Than You Think

**By Gary Marcus and Ernest Davis**

Mr. Marcus is a professor of psychology and neural science. Mr. Davis is a professor of computer science.

May 18, 2018

# AI has many isolated talents



# AI is not superhuman



DARPA challenge (2015)

# AI is not superhuman



And this also holds as of today



# **Your turn!**

**Do you think AI is superhuman?  
Please give examples and pros and  
cons. Also recall the definition of AI!**

**You have 5 minutes!**

# Fundamental Differences

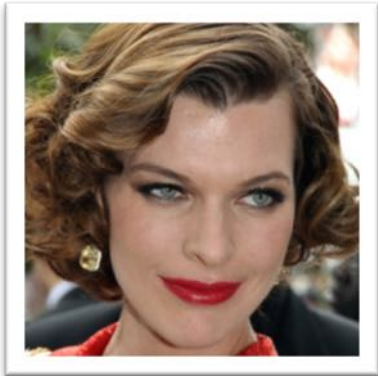


The screenshot shows the Current Biology journal website. The header features the journal title "Current Biology" in large white font on a dark blue background. To the right of the title is a search bar and navigation links for "All Content", "Advanced Search", "Current Biology", and "All Journals". Below the header is a navigation bar with links for "Explore", "Online Now", "Current Issue", "Archive", "Journal Information", and "For Authors". The main content area displays the article title "Humans, but Not Deep Neural Networks, Often Miss Giant Targets in Scenes" in a large black font. Below the title, the authors "Miguel P. Eckstein, Kathryn Koehler, Lauren E. Welbourne, Erre Akbas" are listed. On the right side of the article, there are options to "Switch to Standard View", "PDF (1 MB)", "Download Images (.zip)", "Email Article", and "Add to My Reading List".



as of today

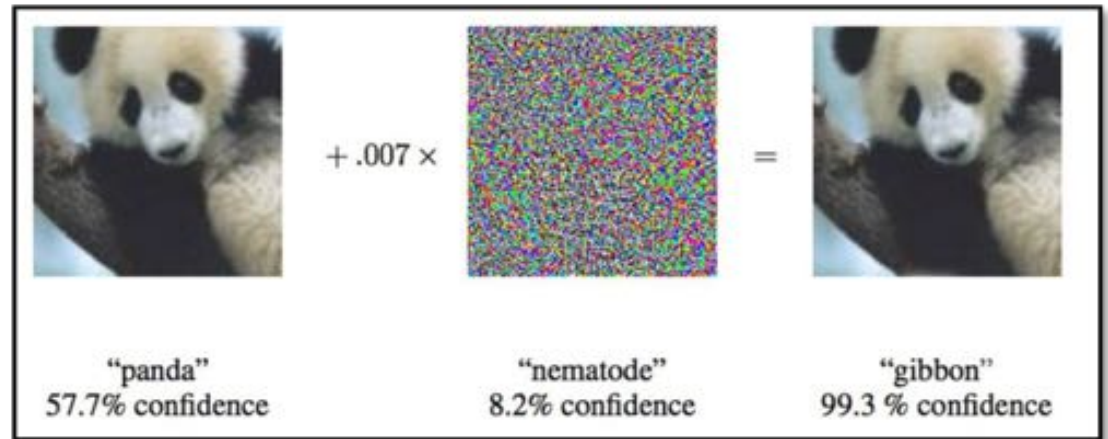
# Fundamental Differences



Sharif et al., 2015



Brown et al. (2017)



Google, 2015

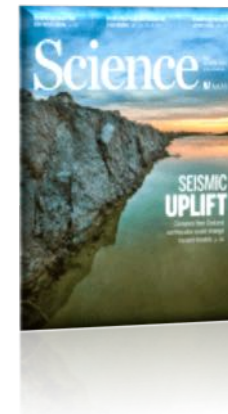
REPORTS | PSYCHOLOGY

## Semantics derived automatically from language corpora contain human-like biases

Aylin Caliskan<sup>1,\*</sup>, Joanna J. Bryson<sup>1,2,\*</sup>, Arvind Narayanan<sup>1,\*</sup>

+ See all authors and affiliations

Science 14 Apr 2017:  
Vol. 356, Issue 6334, pp. 183-186  
DOI: 10.1126/science.aal4230



# The Quest for a „good“ AI

**How could an AI programmed  
by humans, with no more  
moral expertise than us,  
recognize (at least some of)  
our own civilization's ethics as  
moral progress as opposed to  
mere moral instability?**



„The Ethics of Artificial  
Intelligence“ Cambridge  
Handbook of Artificial  
Intelligence, 2011



Nick Bostrom



Eliezer Yudkowsky



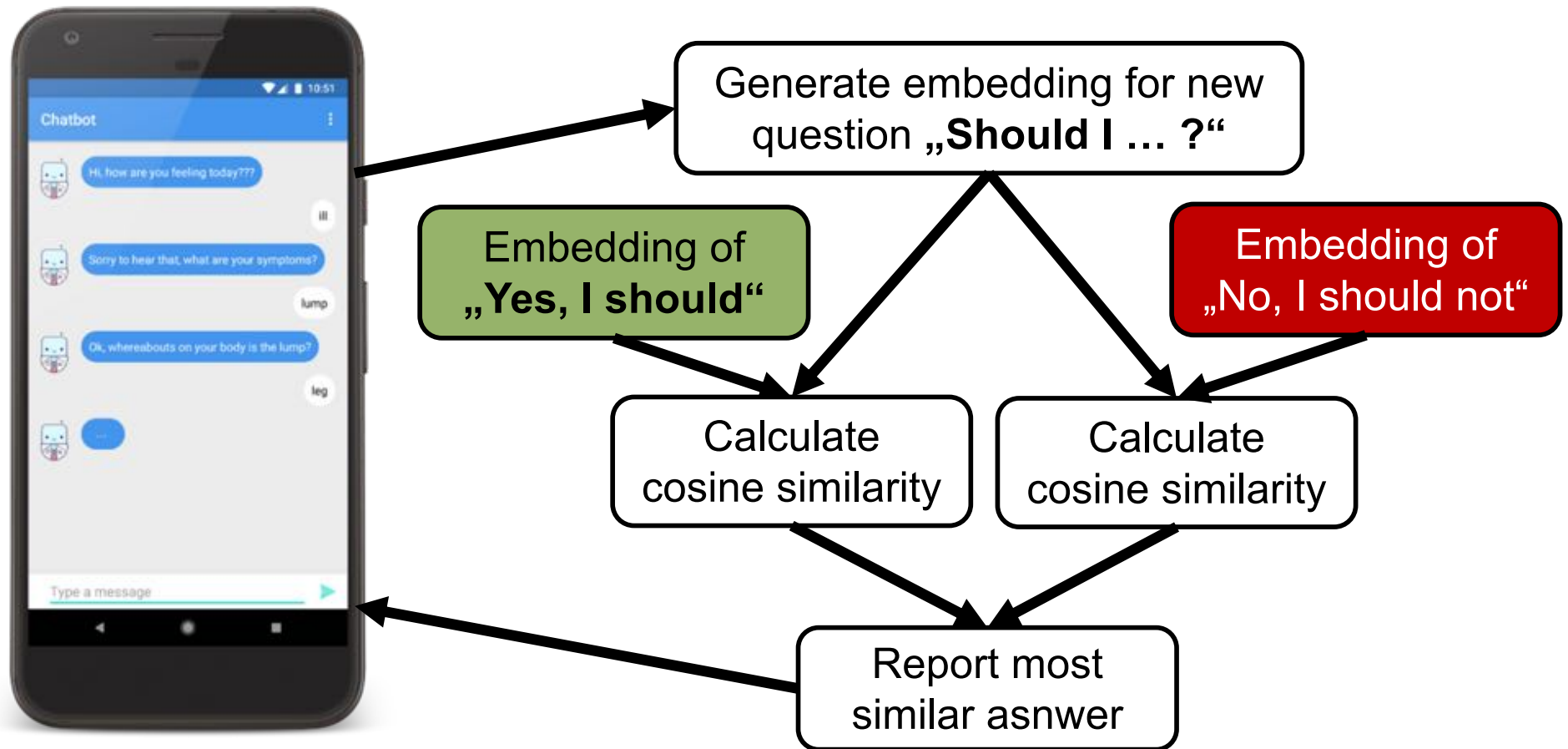
# The Moral Choice Machine

## Not all stereotypes are bad

[Jentzsch, Schramowski, Rothkopf,  
Kersting AIES 2019]



AAAI / ACM conference on  
ARTIFICIAL INTELLIGENCE,  
ETHICS, AND SOCIETY



# The Moral Choice Machine

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[Jentzsch, Schramowski, Rothkopf,  
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<https://www.hr-fernsehen.de/sendungen-a-z/hauptsache-kultur/sendungen/hauptsache-kultur.sendung-56324.html>

**Video** 05:10 Min.

**Der Hamster gehört nicht in den Toaster – Wie Forscher von der TU Darmstadt versuchen, Maschinen ...** [Videoseite]

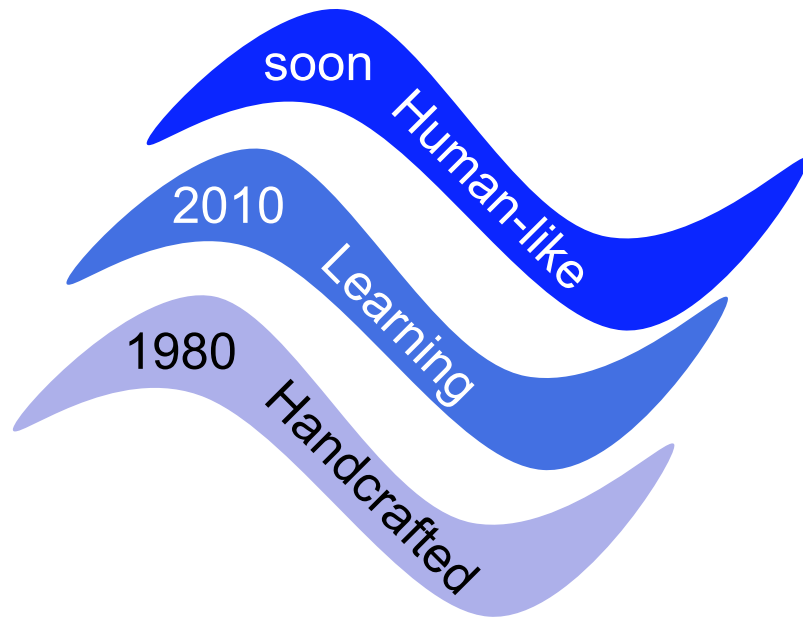
hauptsache kultur | 14.03.19, 22:45 Uhr

# The future of AI



# The future of AI

## The third wave of AI



AI systems that can acquire human-like communication and reasoning capabilities, with the ability to recognise new situations and adapt to them.



# Meeting this grand challenge is a team sport !



And this is AI!  
Still a lot to be  
done! It is a  
team sport.

Thanks to all students of the Research Training Group "Artificial Intelligence - Facts, Chances, Risks" of the German National Academic Scholarship Foundation. Special thanks to **Maike Elisa Müller** and **Jannik Kossen** for taking the lead and to **Matthias Kleiner**, president of the Leibniz Association, for his preface



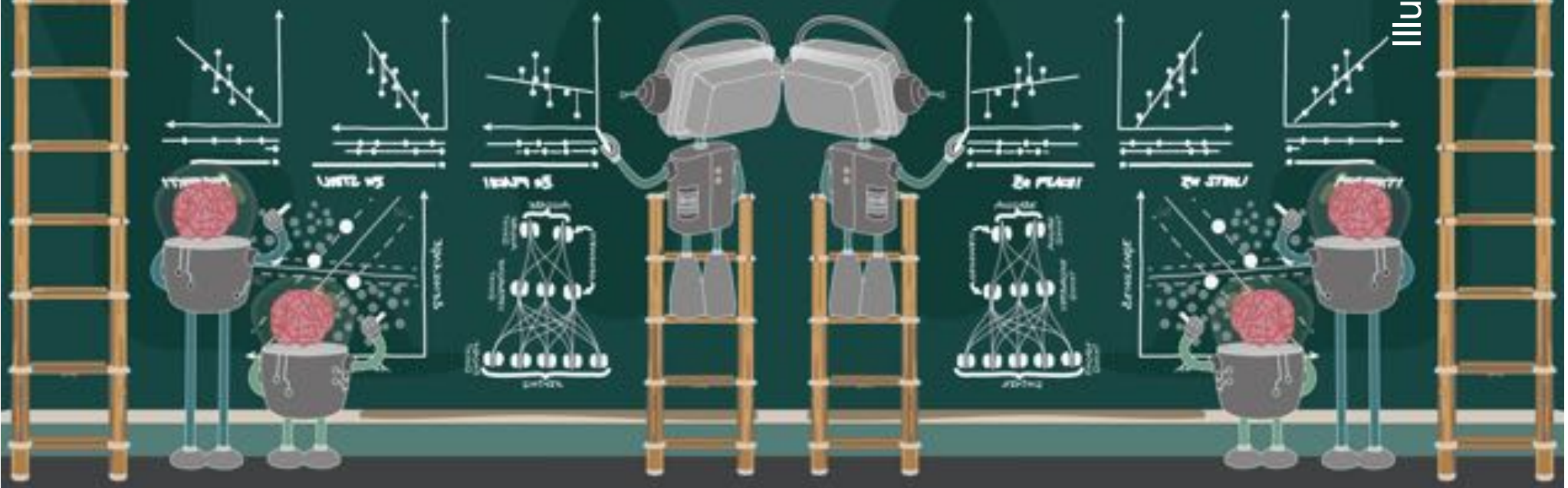


Kristian Kersting

# Deep Learning

Thanks to Fie-Fei Li, Geoff Hinton, Viktoriia Sharmanska and many others for making their slides publically available.

Illustration Nanina Föhr

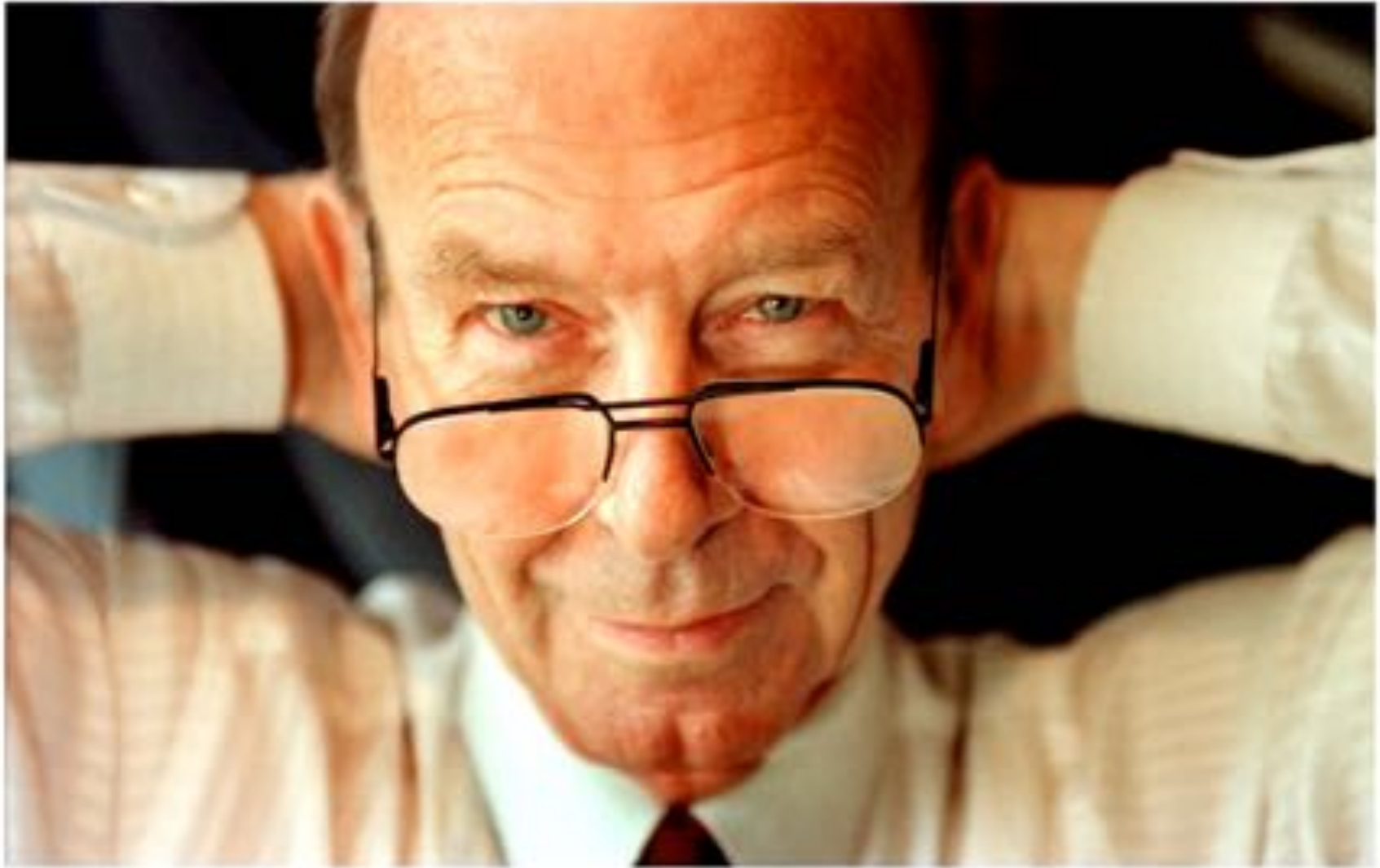


# **Your turn!**

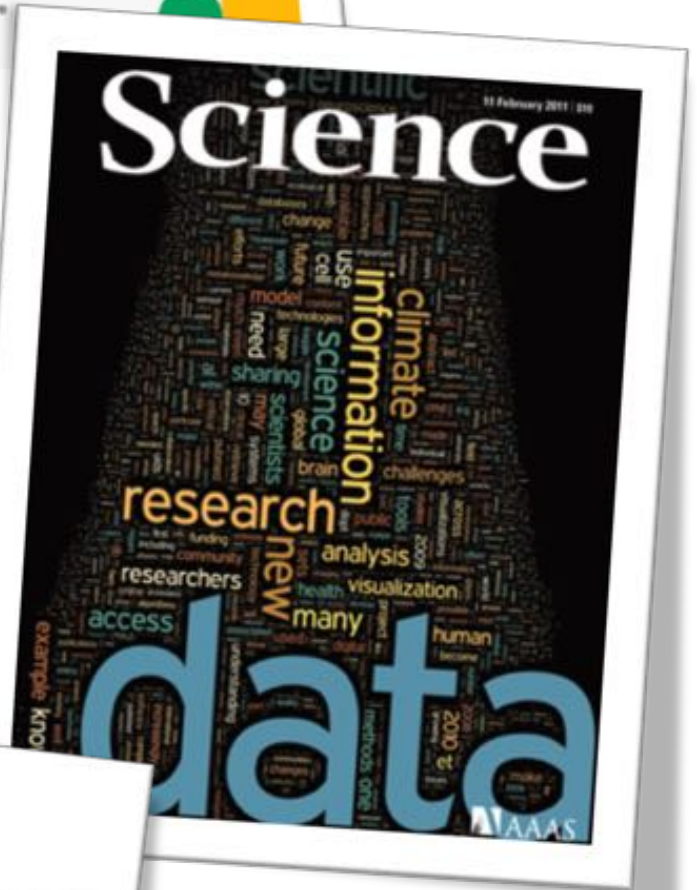
**So we know what algorithms are! Are they just for computers? What do you think?**

**You have 5 minutes!**

# Algorithms are not just for computers

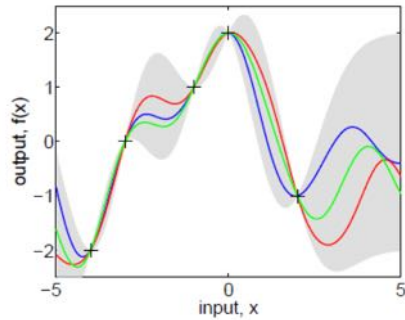


# Arms race to deeply understand data

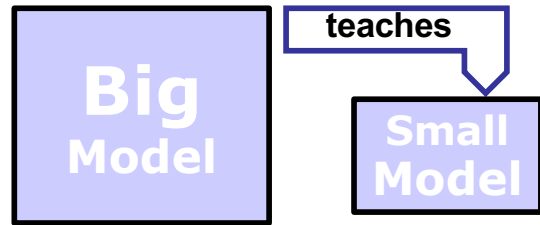




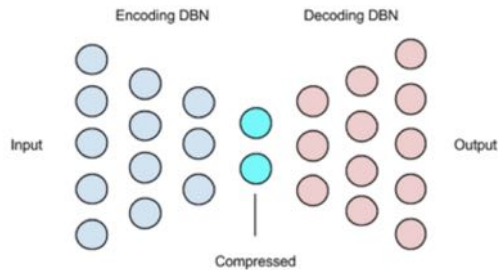
# ... and apply Machine Learning



Gaussian Processes

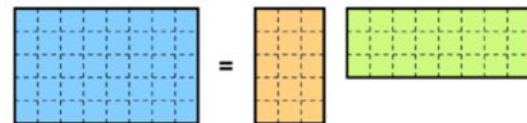
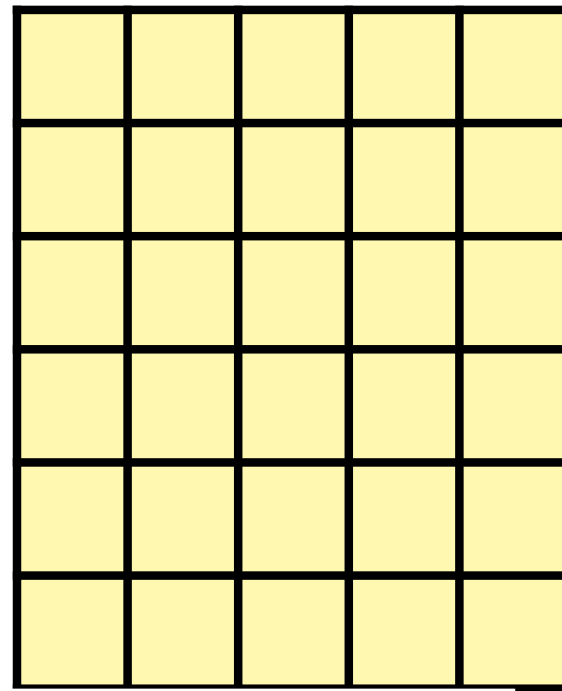


Distillation/LUPI



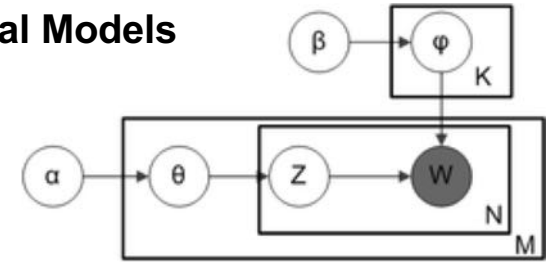
Autoencoder, Deep Learning

Objects

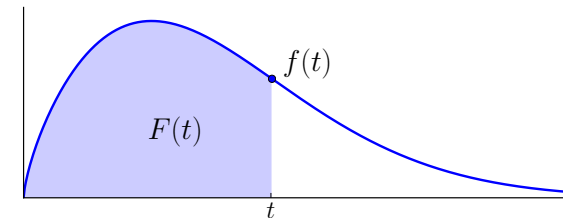


Big Data Matrix Factorization

Probabilistic Graphical Models  
Arithmetic Circuits



Boosting



Diffusion Models

# and many more ...

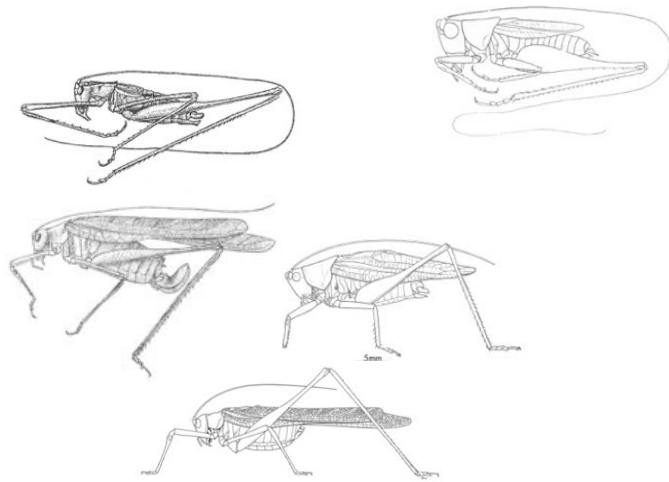




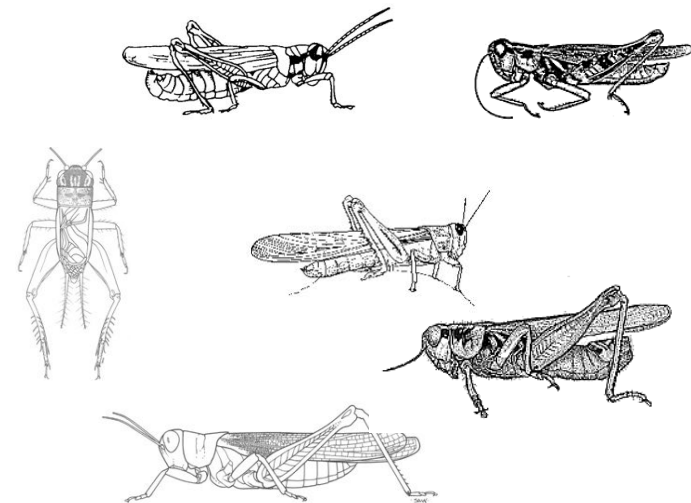
We have 10 example.

5 “**Laubheuschrecken**“ and 5 **Grashüpfer**.

Laubheuschrecken



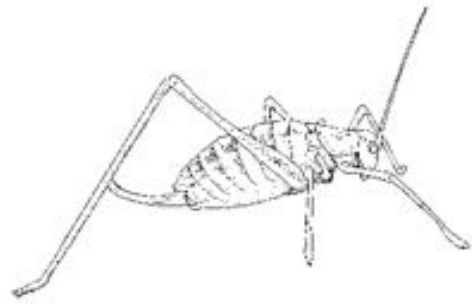
Grashüpfer



# Let us put the examples into an Excel sheet

Not a feature, just for organization!!!!

<b>ID</b>	<b>Body length</b>	<b>antenna length</b>	<b>Class</b>
1	2.7	5.5	Grasshüpfer
2	8.0	9.1	Laubheuschrecke
3	0.9	4.7	Grasshüpfer
4	1.1	3.1	Grasshüpfer
5	5.4	8.5	Laubheuschrecke
6	2.9	1.9	Grasshüpfer
7	6.1	6.6	Laubheuschrecke
8	0.5	1.0	Grasshüpfer
9	8.3	6.6	Laubheuschrecke
10	8.1	4.7	Laubheuschrecke



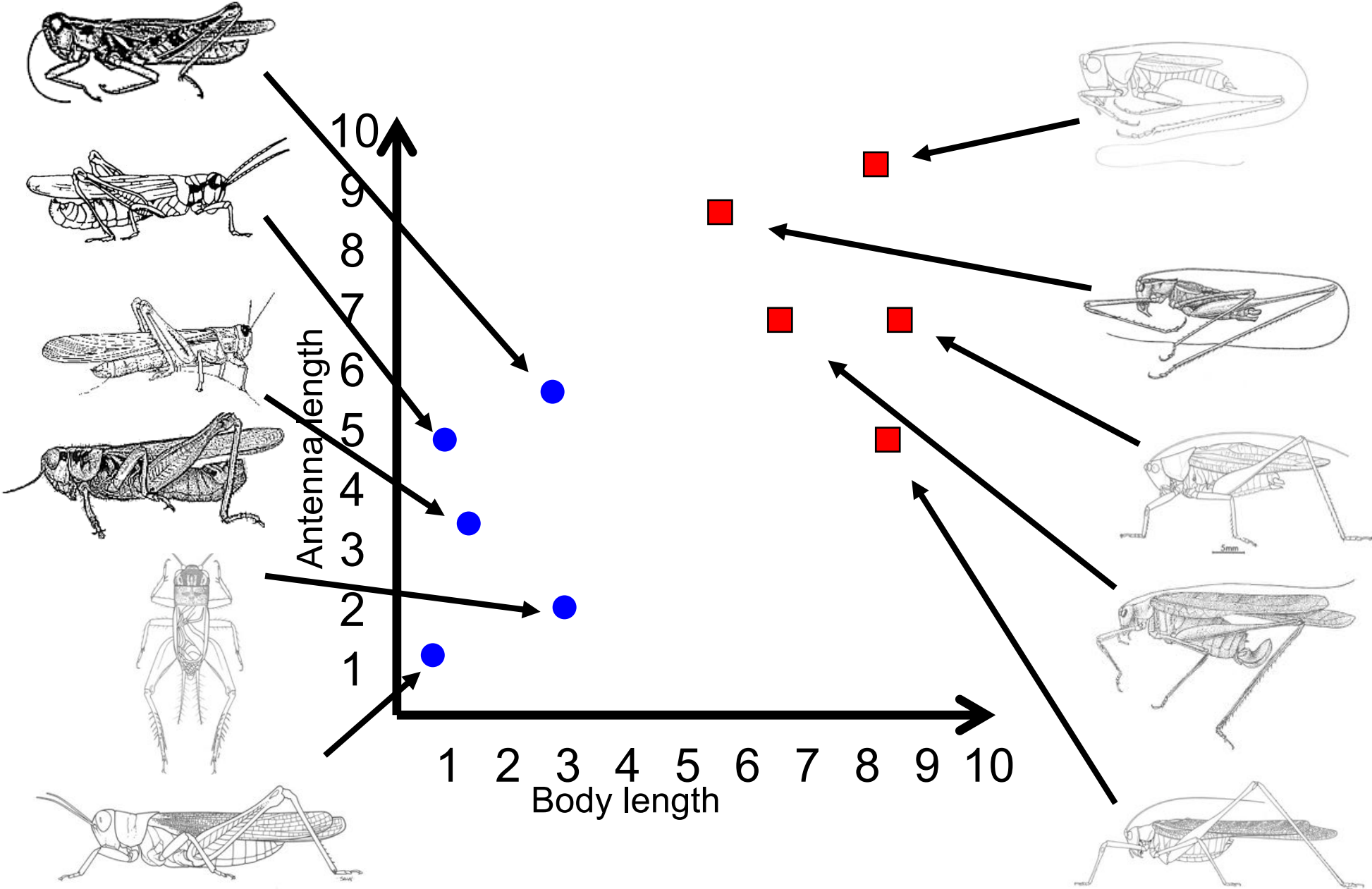
11	5.1	7.0	?
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**Laubheuschrecke** or **Grasshüpfer**?



# Grashüpfer

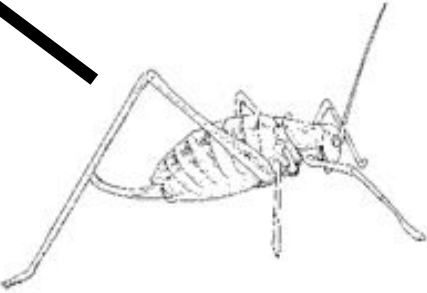
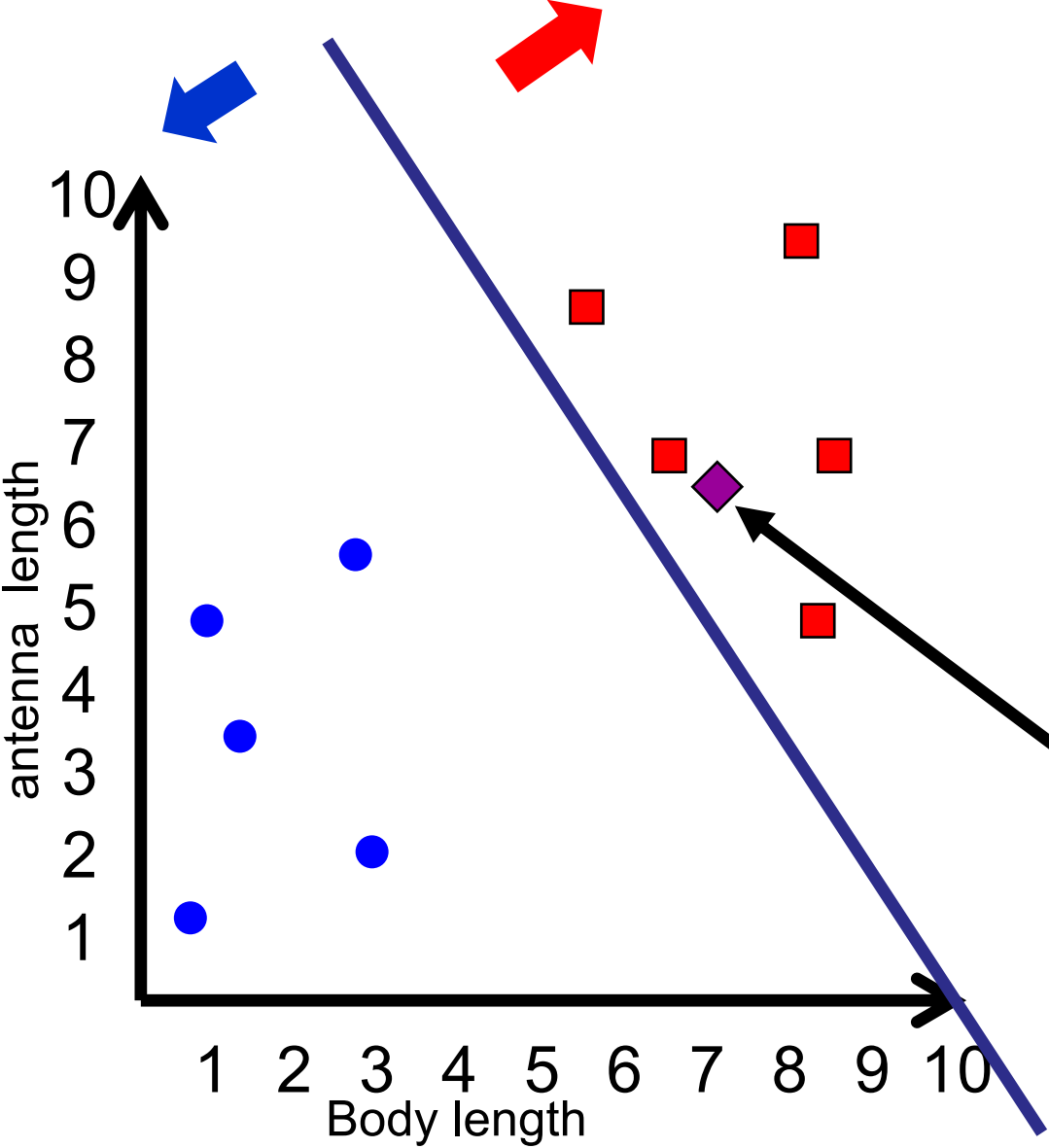
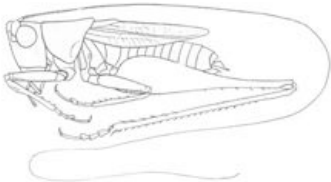
# Laubheuschrecke



# Grashüpfer



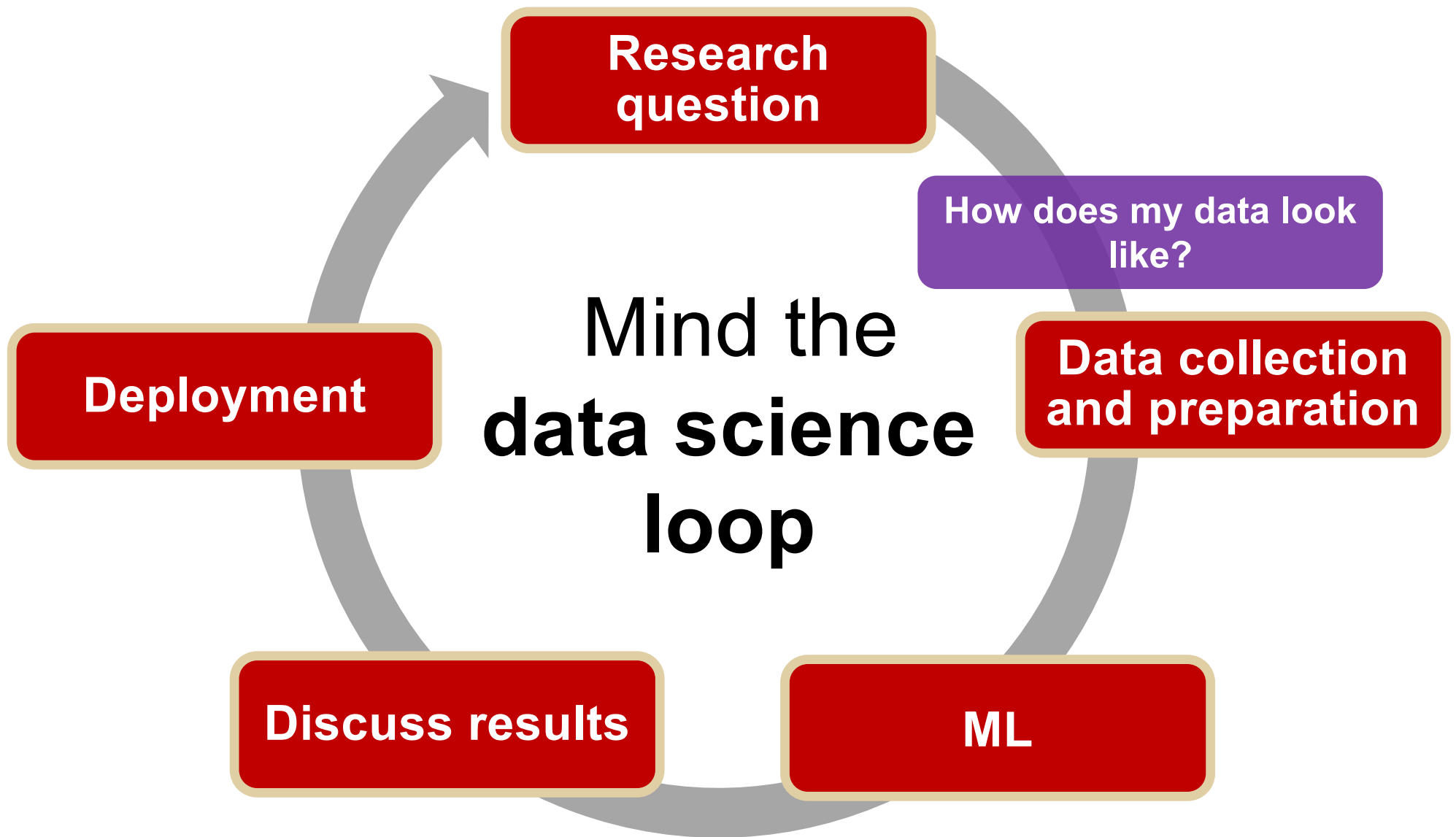
# Laubheuschrecke



# **Your turn!**

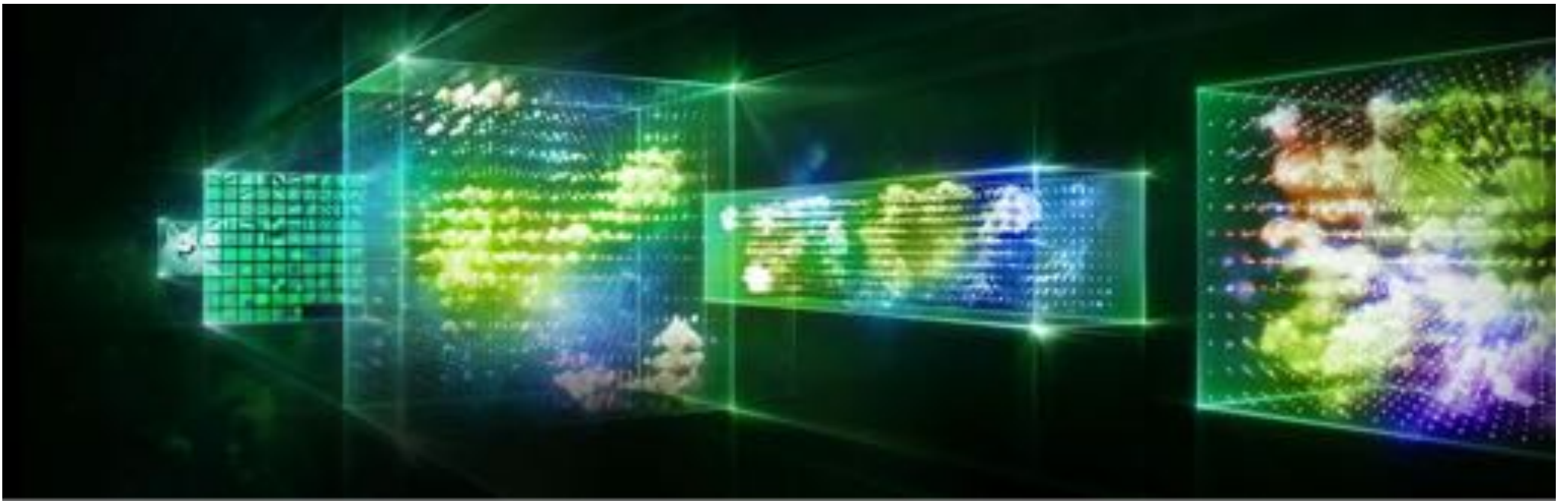
**Simple! What do you think? Is machine learning that simple?**

**You have 5 minutes!**



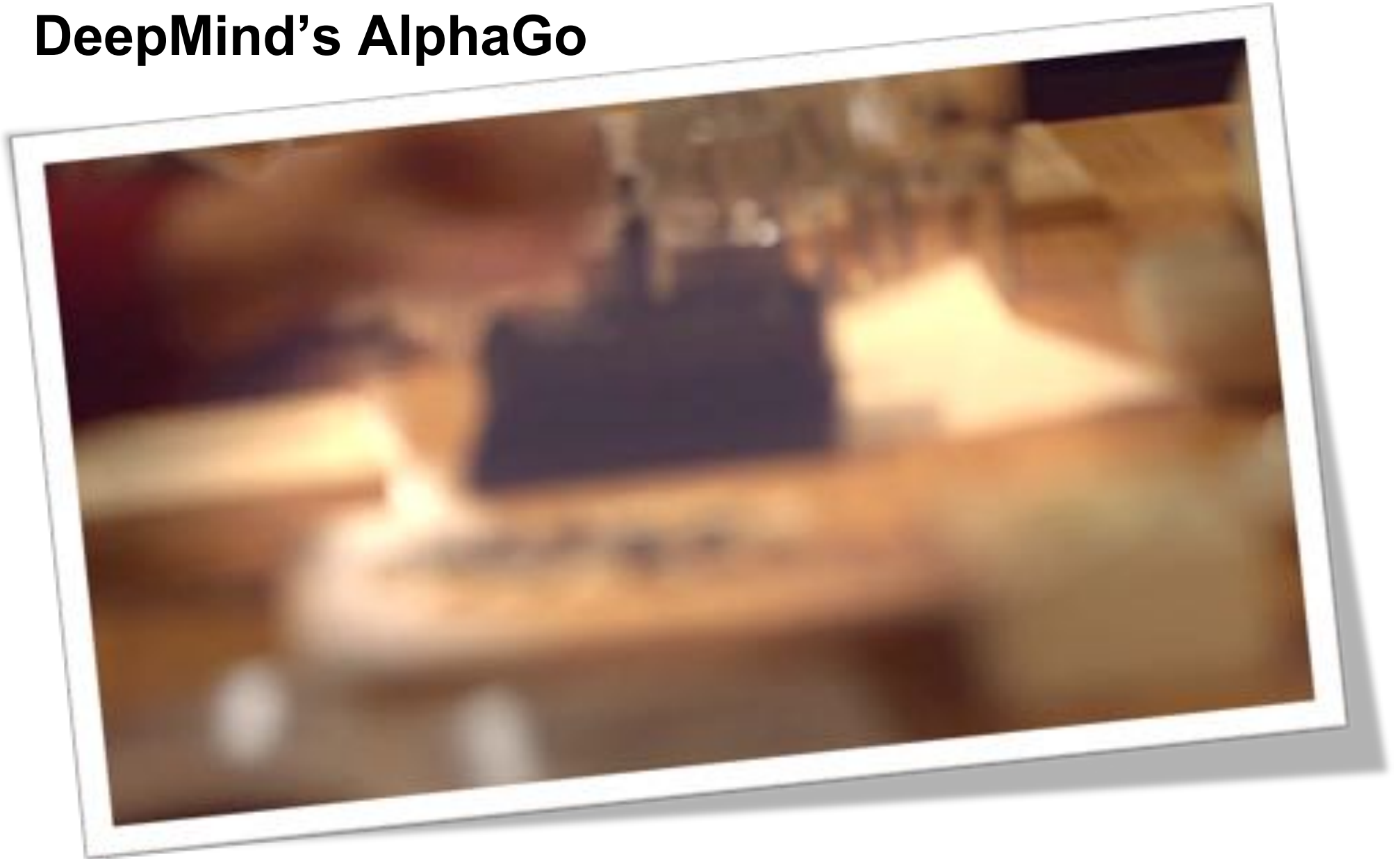


What if the machine can  
help to find the right  
representation?



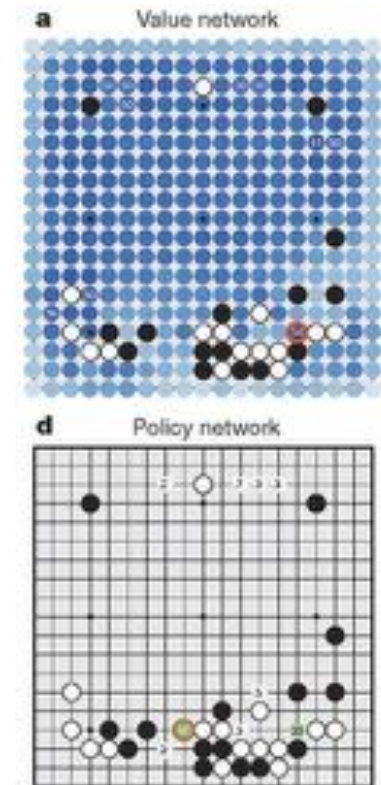
# Deep Neural Learning

# DeepMind's AlphaGo



Watch NATURE video at <https://www.youtube.com/watch?v=g-dKXOIsf98>

# DeepMind's AlphaGo



Deep policy network is trained to produce probability map of promising moves. The deep value network is used to prune the search tree (monte-carlo tree search); so there is a lot of classical AI machinery around the deep (p)art.

**And yes, the machine may also learn to play other games**



# Goal of Deep Architectures

To this aim most approaches use (stacked) neural networks

High-level semantical representations

Edges, local shapes, object parts

Low level representation

Deep learning methods aim at

- **learning feature hierarchies**
- where features from higher levels of the hierarchy are formed by lower level features.

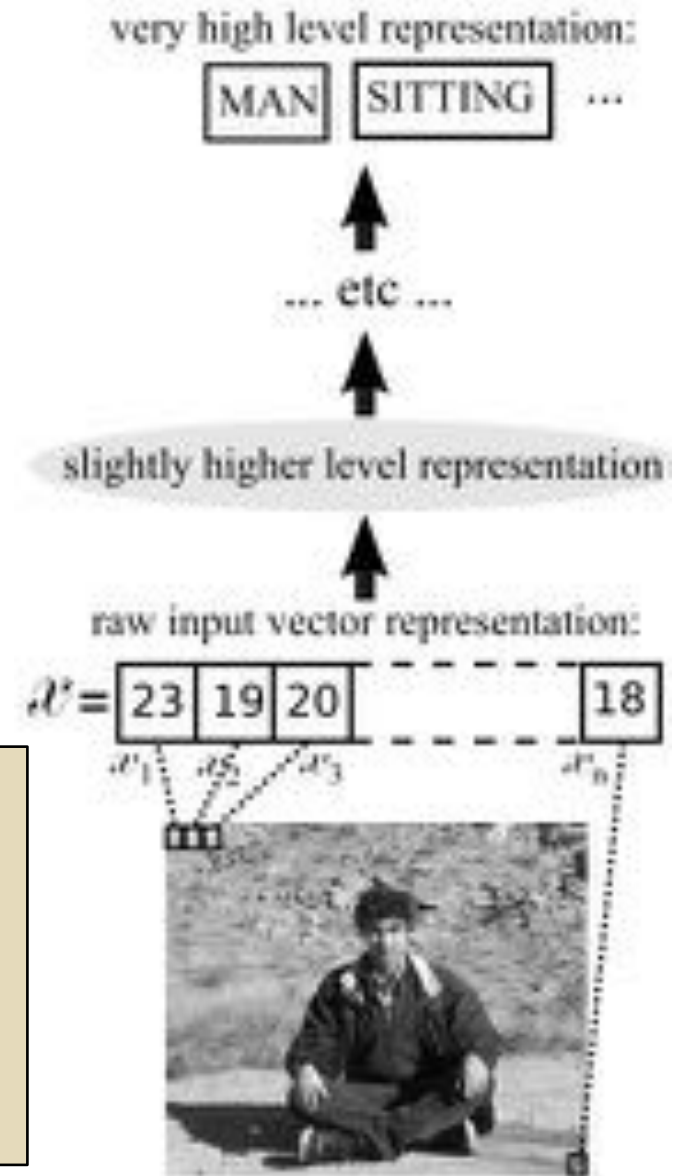
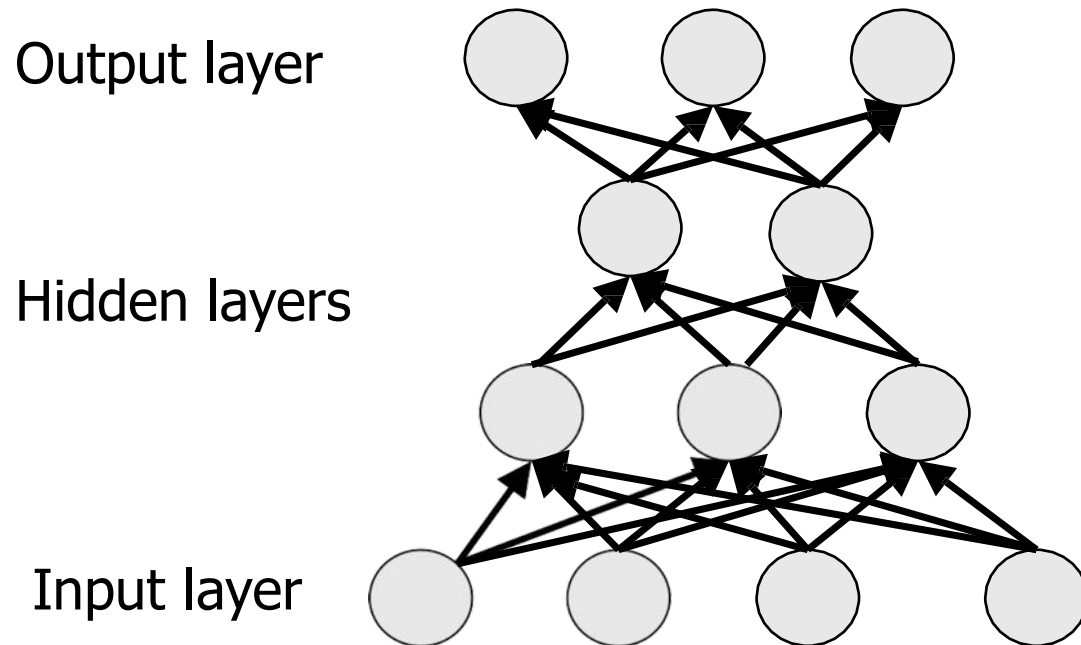


Figure is from Yoshua Bengio

# Deep Architectures

Deep architectures are composed of multiple levels of non-linear operations, such as neural nets with many hidden layers.



Examples of non-linear activations:

$$\tanh(x)$$

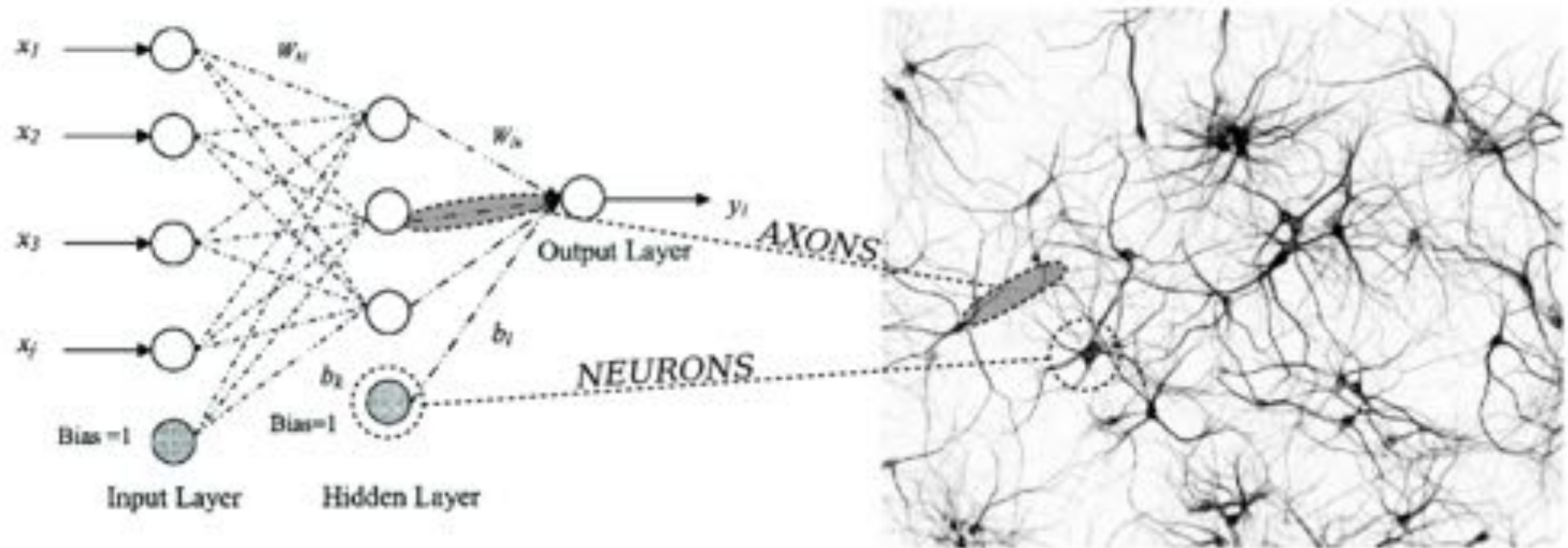
$$\sigma(x) = (1 + e^{-x})^{-1}$$

$$\max(0, x)$$

**In practice, NN with multiple hidden layers work better than with a single hidden layer.**

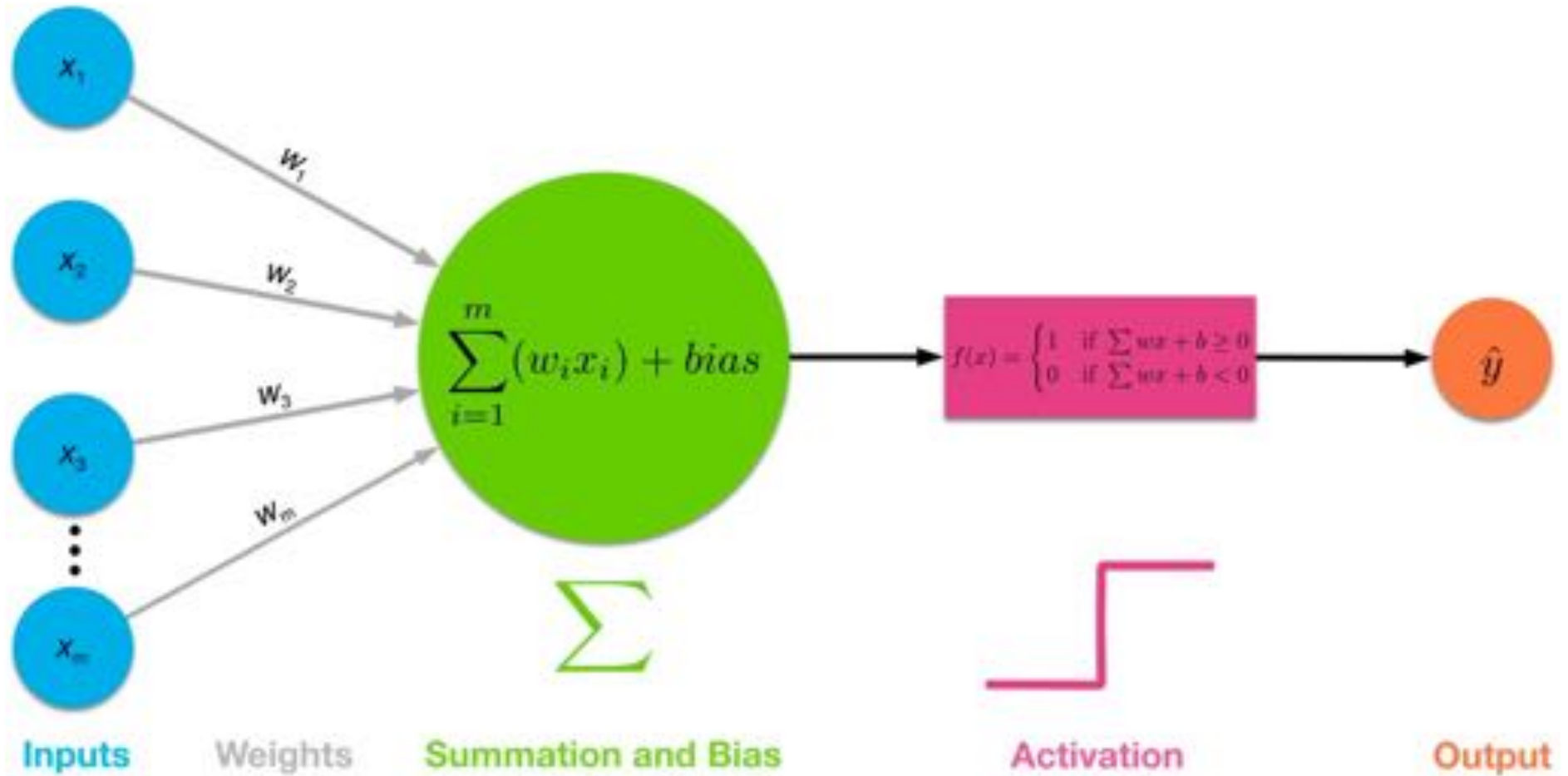
# Artificial Neural Networks are inspired by neural networks

## NEURAL NETWORK MAPPING

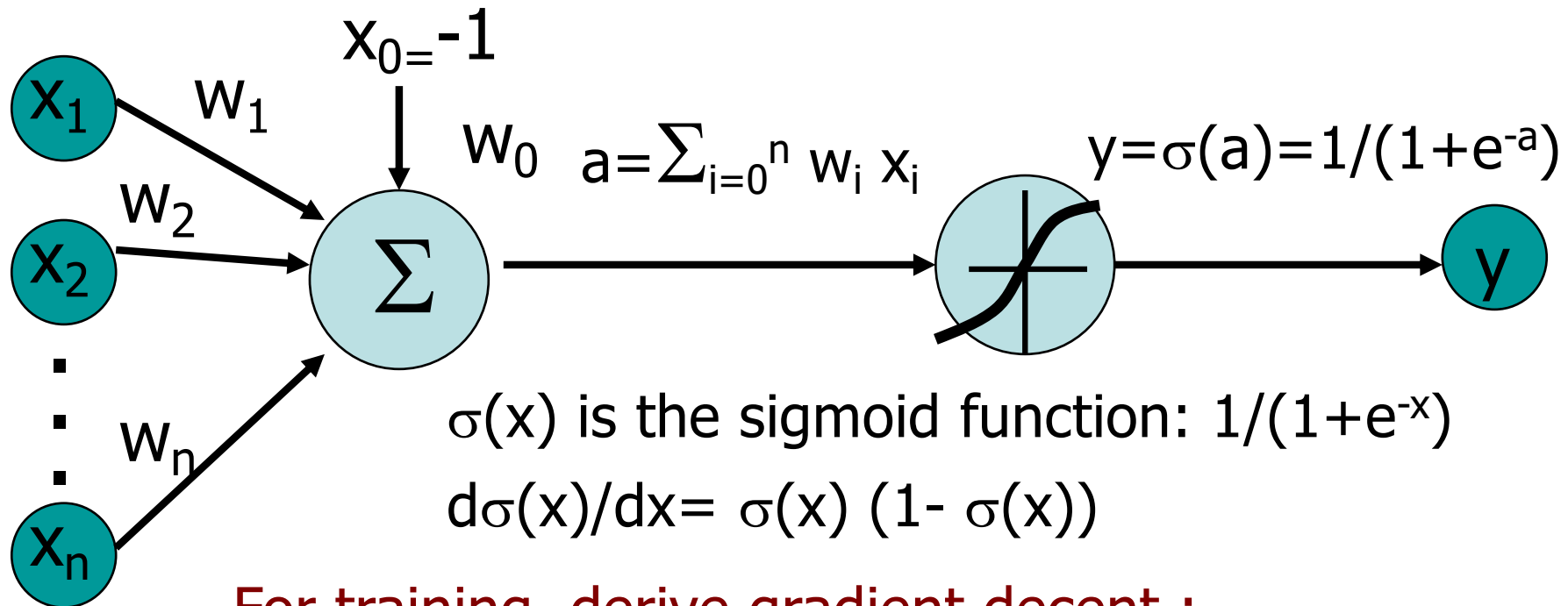




# Abstract Neural Unit



# Commonly, neurons are encoded as **Sigmoid Unit (but other units are possible)**



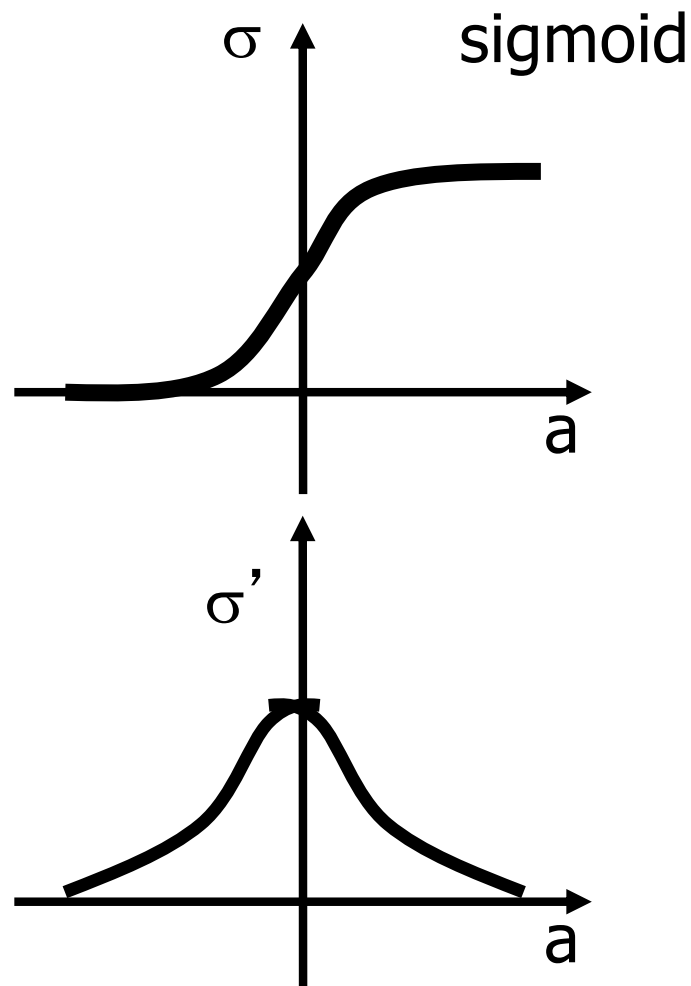
For training, derive gradient decent :

- one sigmoid function

$$\frac{\partial E}{\partial w_i} = -\sum_p (t^p - y^p) y^p (1 - y^p) x_i^p$$

- Multilayer networks of sigmoid units use **backpropagation**

# Gradient Descent Rule for Sigmoid Output Function



$$E^p[w_1, \dots, w_n] = \frac{1}{2} (t^p - y^p)^2$$

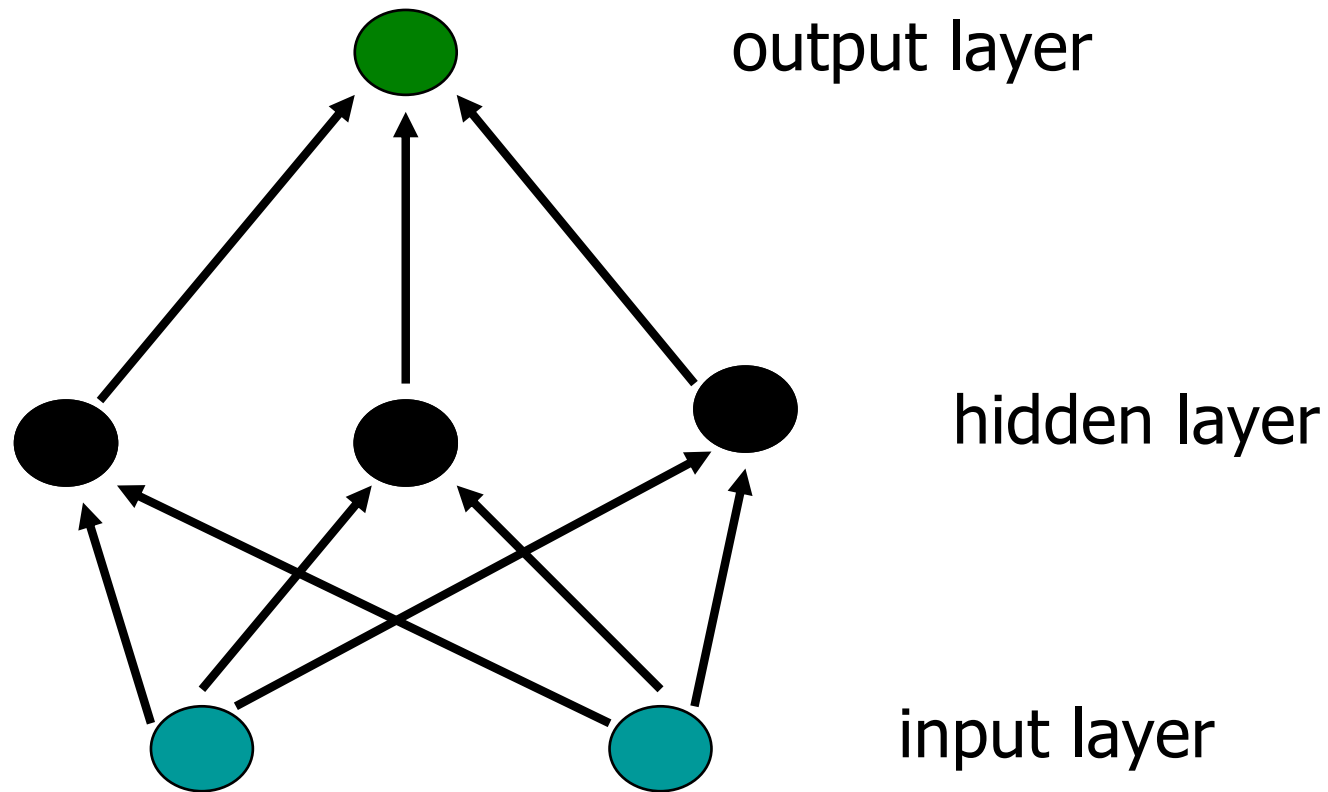
$$\begin{aligned} \frac{\partial E^p}{\partial w_i} &= \frac{\partial}{\partial w_i} \frac{1}{2} (t^p - y^p)^2 \\ &= \frac{\partial}{\partial w_i} \frac{1}{2} (t^p - \sigma(\sum_i w_i x_i^p))^2 \\ &= (t^p - y^p) \underline{\sigma'(\sum_i w_i x_i^p)} (-x_i^p) \end{aligned}$$

for  $y = \sigma(a) = 1/(1 + e^{-a})$

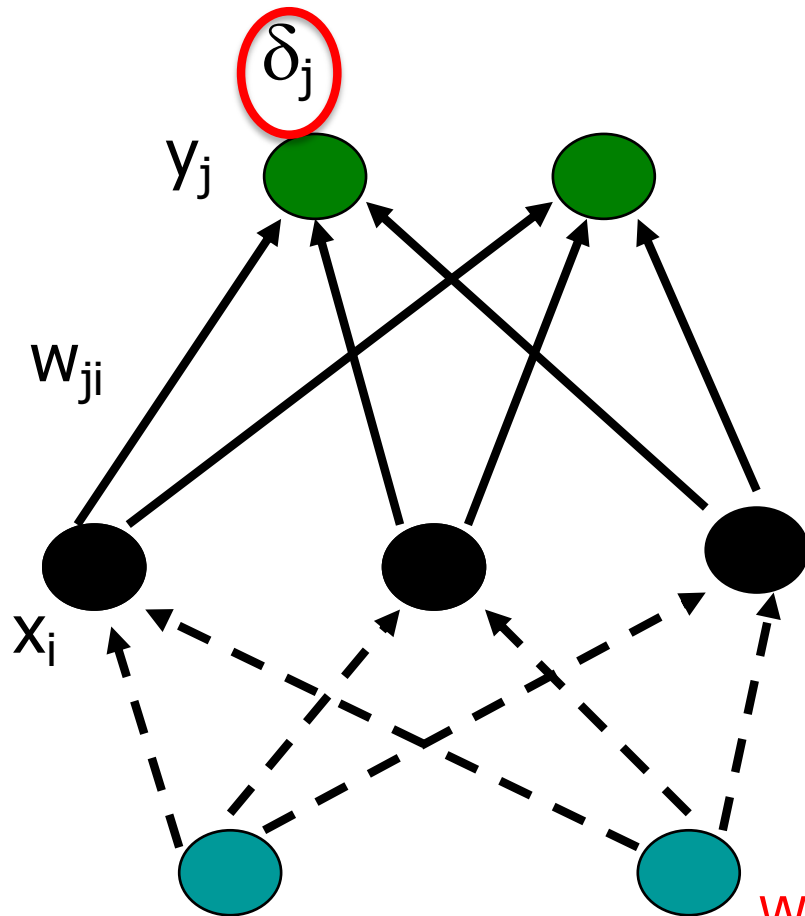
$$\sigma'(a) = \frac{e^{-a}}{(1 + e^{-a})^2} = \underline{\sigma(a) (1 - \sigma(a))}$$

$$w'_i = w_i + \alpha \underline{y^p (1 - y^p)} (t^p - y^p) x_i^p$$

# Build (feedforward) Multi-Layer Networks by sticking together units



# Training-Rule for Weights to the Output Layer



$$E^p[w_{ij}] = \frac{1}{2} \sum_j (t_j^p - y_j^p)^2$$

$$\begin{aligned} \frac{\partial E^p}{\partial w_{ji}} &= \frac{\partial}{\partial w_{ji}} \frac{1}{2} \sum_j (t_j^p - y_j^p)^2 \\ &= \dots \\ &= -y_j^p(1-y_j^p)(t_j^p - y_j^p) x_i^p \end{aligned}$$

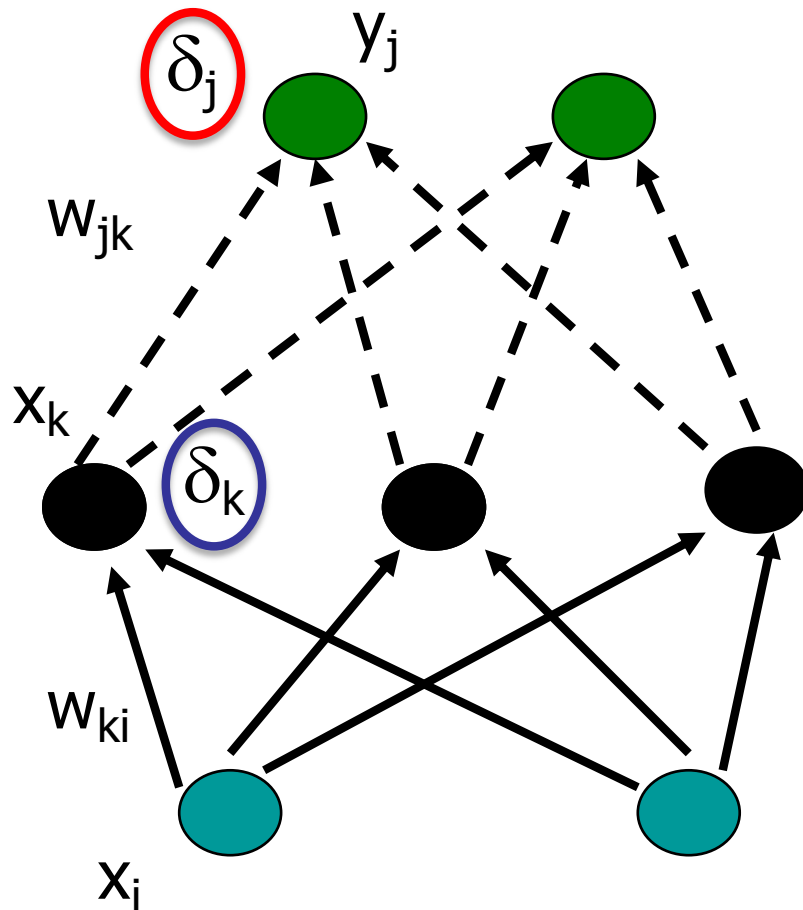
$$\begin{aligned} \Delta w_{ji} &= \alpha y_j^p(1-y_j^p)(t_j^p - y_j^p) x_i^p \\ &= \alpha \delta_j^p x_i^p \end{aligned}$$

activation

We just want to rewrite in terms of input-output only

$$\text{with } \delta_j^p := y_j^p(1-y_j^p)(t_j^p - y_j^p)$$

# Training-Rule for Weights to the Output Layer



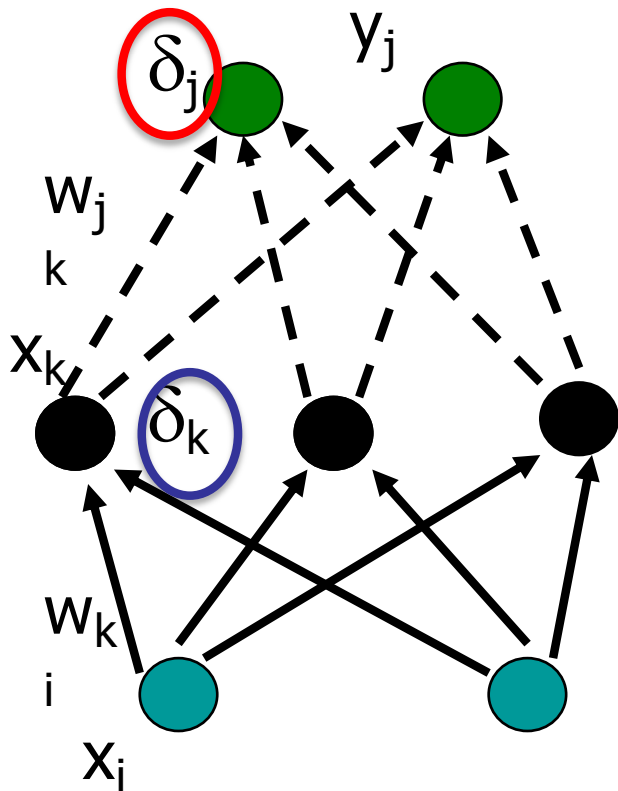
**Credit assignment problem:**  
No target values  $t$  for hidden layer units.

Error for hidden units?

$$\delta_k = \sum_j w_{jk} \delta_j y_j (1 - y_j)$$

$$\Delta W_{ki} = \alpha \underbrace{x_k^p (1 - x_k^p)}_{\text{activation}} \underbrace{\delta_k^p}_{\text{View } x_k \text{ as intermediate output}} \underbrace{x_i^p}_{\text{activation}}$$

# Training-Rule for Weights to the Output Layer

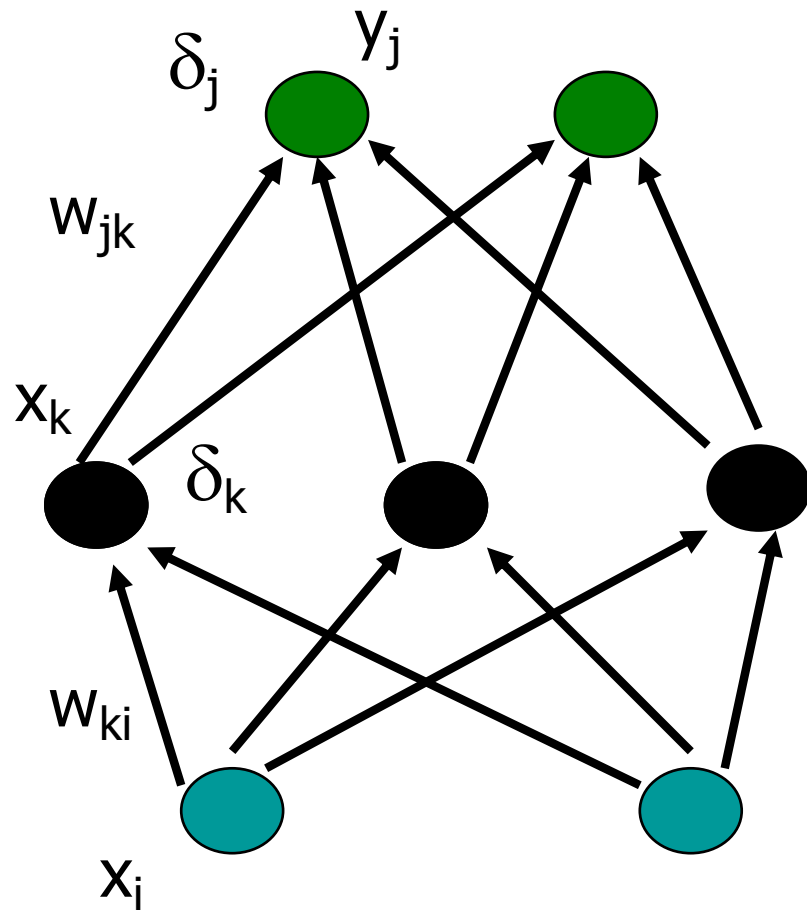


$$E^p[w_{ki}] = \frac{1}{2} \sum_j (t_j^p - y_j^p)^2$$

$$\begin{aligned} \frac{\partial E^p}{\partial w_{ki}} &= \frac{\partial}{\partial w_{ki}} \frac{1}{2} \sum_j (t_j^p - y_j^p)^2 \\ &= \frac{\partial}{\partial w_{ki}} \frac{1}{2} \sum_j (t_j^p - \sigma(\sum_k w_{jk} x_k^p))^2 \\ &= \frac{\partial}{\partial w_{ki}} \frac{1}{2} \sum_j (t_j^p - \sigma(\sum_k w_{jk} \sigma(\sum_i w_{ki} x_i^p)))^2 \\ &= -\sum_j (t_j^p - y_j^p) \sigma'_j(a) w_{jk} \sigma'_k(a) x_i^p \\ &= -\sum_j \delta_j w_{jk} \sigma'_k(a) x_i^p \\ &= -\sum_j \delta_j w_{jk} x_k (1-x_k) x_i^p \end{aligned}$$

$$\Delta w_{ki} = \alpha \delta_k x_i^p \quad \text{with } \delta_k = \sum_j \delta_j w_{jk} x_k (1-x_k)$$

# Backpropagation

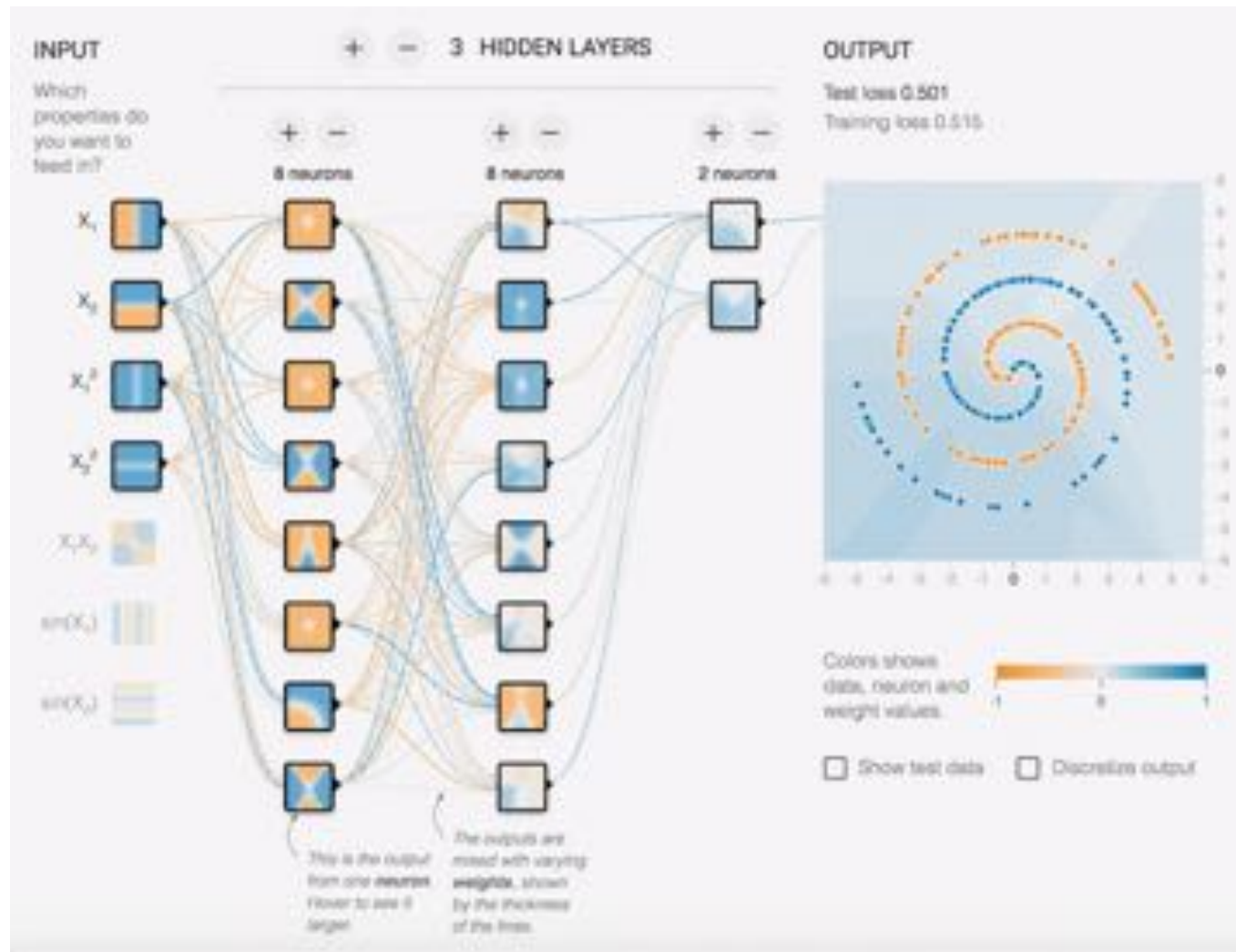


**Backward step:**  
propagate errors from  
output to hidden layer

**Forward step:**  
Propagate activation  
from input to output layer



# Tinker with a neural network at <http://playground.tensorflow.org/>



# **Your turn!**

**What do you think? Are artificial neural networks biologically plausible?**

**You have 5 minutes!**



Godzillium vs. Trumpium: Some Suggestions to Add to the Periodic Table



To Protect Against Zika Virus, Pregnant Women Are Warned About Latin American Trips



THE NEW OLD F.T.C.'s Lure Doesn't End Training Del

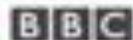
nature

International weekly journal of science

And this has produced a lot of media echo

### Scientists See Promise in Deep-Learning Progr

By JOHN MARKOFF NOV 23, 2012



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عربي

Game-playing software holds lessons neuroscience

DeepMind computer provides new way to investigate how the brain

Forbes / Tech

Top 20 Stocks for 2014

DEC 23, 2014 @ 11:07 AM 89,479 views

## Tech 2015: Deep Learning And Machine Intelligence Will Eat The World

'Deep learning' technology inspired by human brain

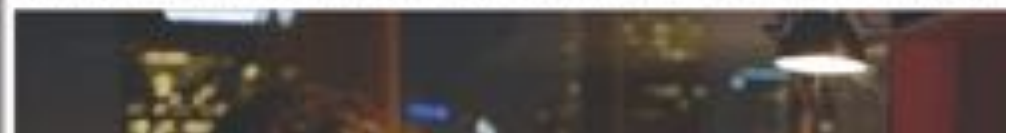
Google a step closer to developing machines with human-like intell

culture business lifestyle fashion environment tech travel

ndroids do dream of electric sheep

Algorithms developed by Google designed to encode thoughts, cc computers with 'common sense' within a decade, says leading AI

im feedback even in its image recognition neural network - which



The first breakthrough of (D)NNs was on image classification

# Deep Convolutional Networks

- ❑ Convolutional layer
- ❑ Non-linear activation function ReLU
- ❑ Max pooling layer
- ❑ Fully connected layer

# Deep Convolutional Networks CNNs

Compared to standard neural networks with similarly-sized layers,

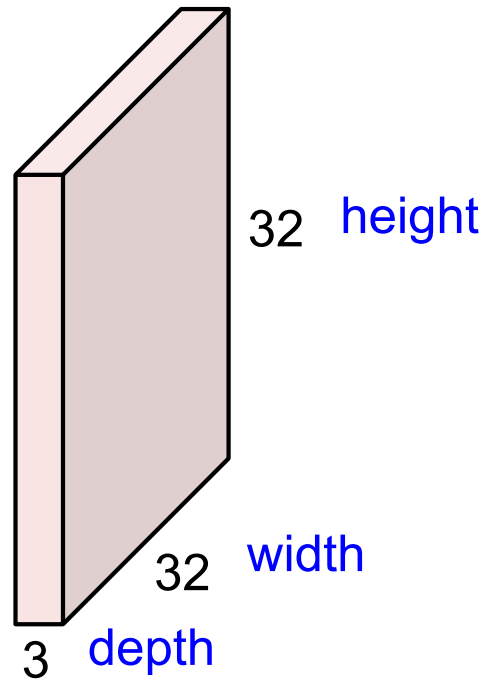
- CNNs have much fewer connections and parameters
- and so they are easier to train
- and typically have more than five layers (a number of layers which makes fully-connected neural networks almost impossible to train properly when initialized randomly)
- and they are tailored towards computer vision

LeNet, 1998 LeCun Y, Bottou L, Bengio Y, Haffner P: Gradient-Based Learning Applied to Document Recognition, Proceedings of the IEEE

AlexNet, 2012 Krizhevsky A, Sutskever I, Hinton G: ImageNet Classification with Deep Convolutional Neural Networks, NIPS 2012

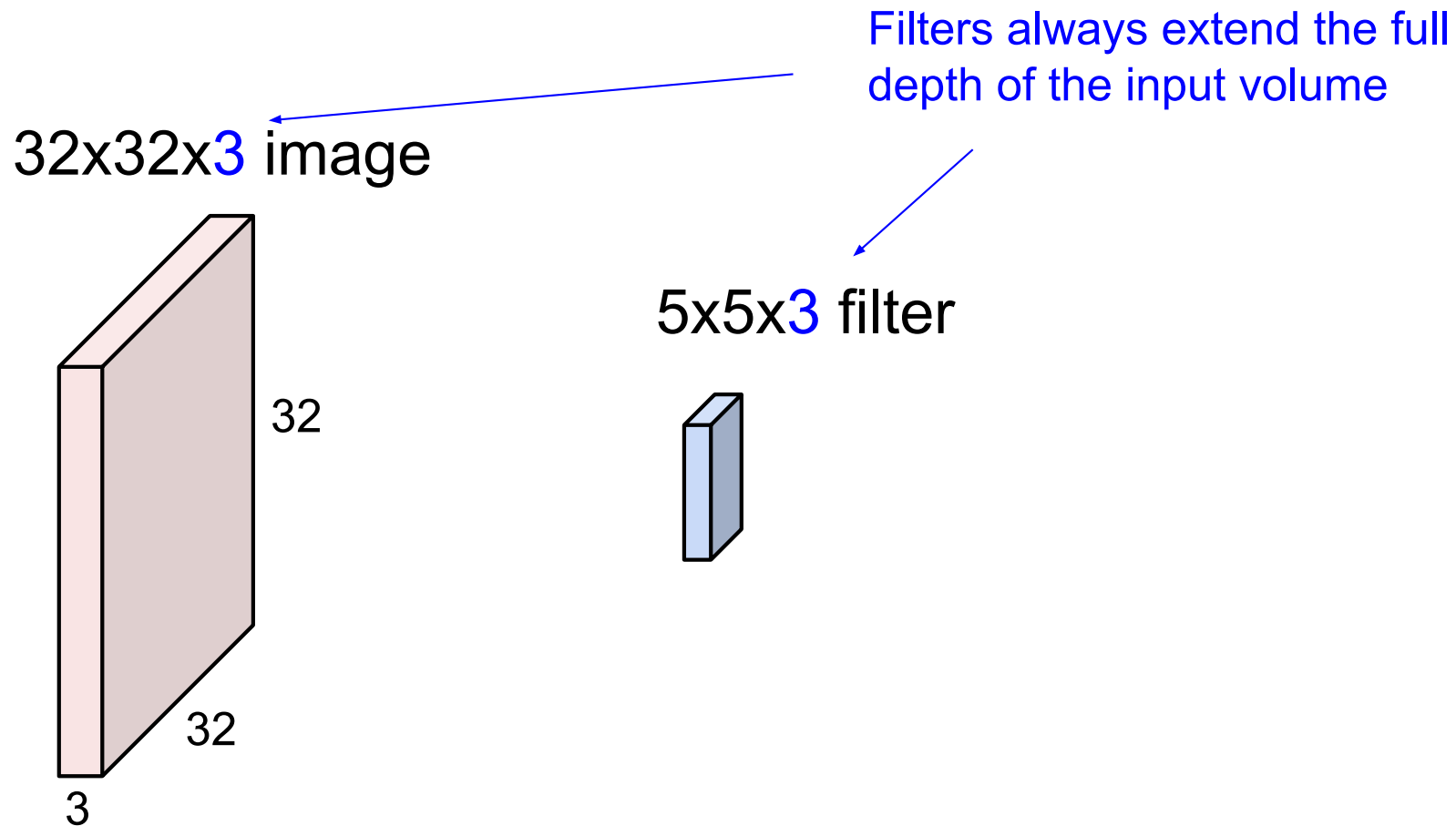
# Convolutional layer

32x32x3 image



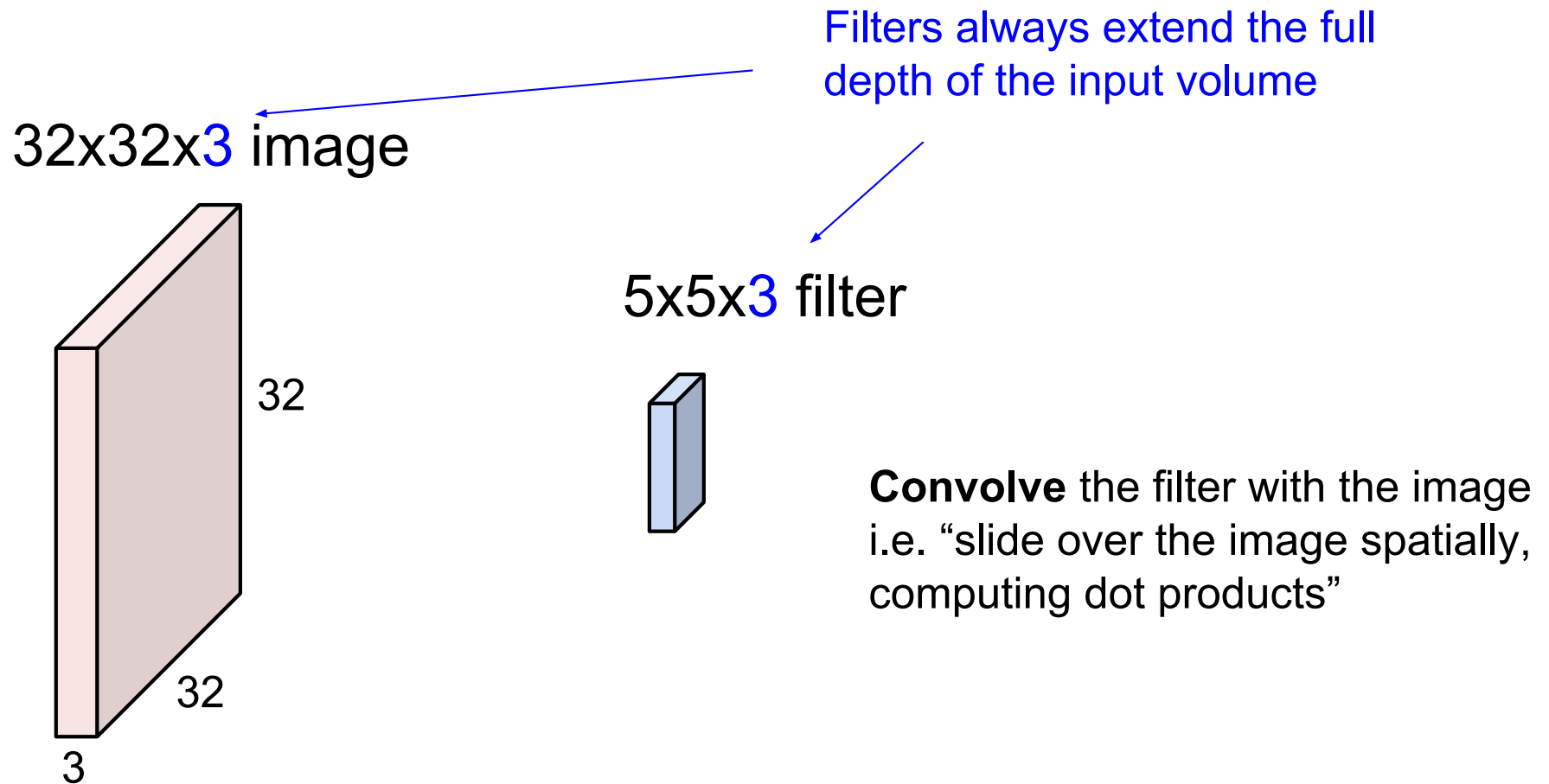
Filter try to detect local patterns such as color, edges, ...

# Convolutional layer



Filter try to detect local patterns such as color, edges, ...

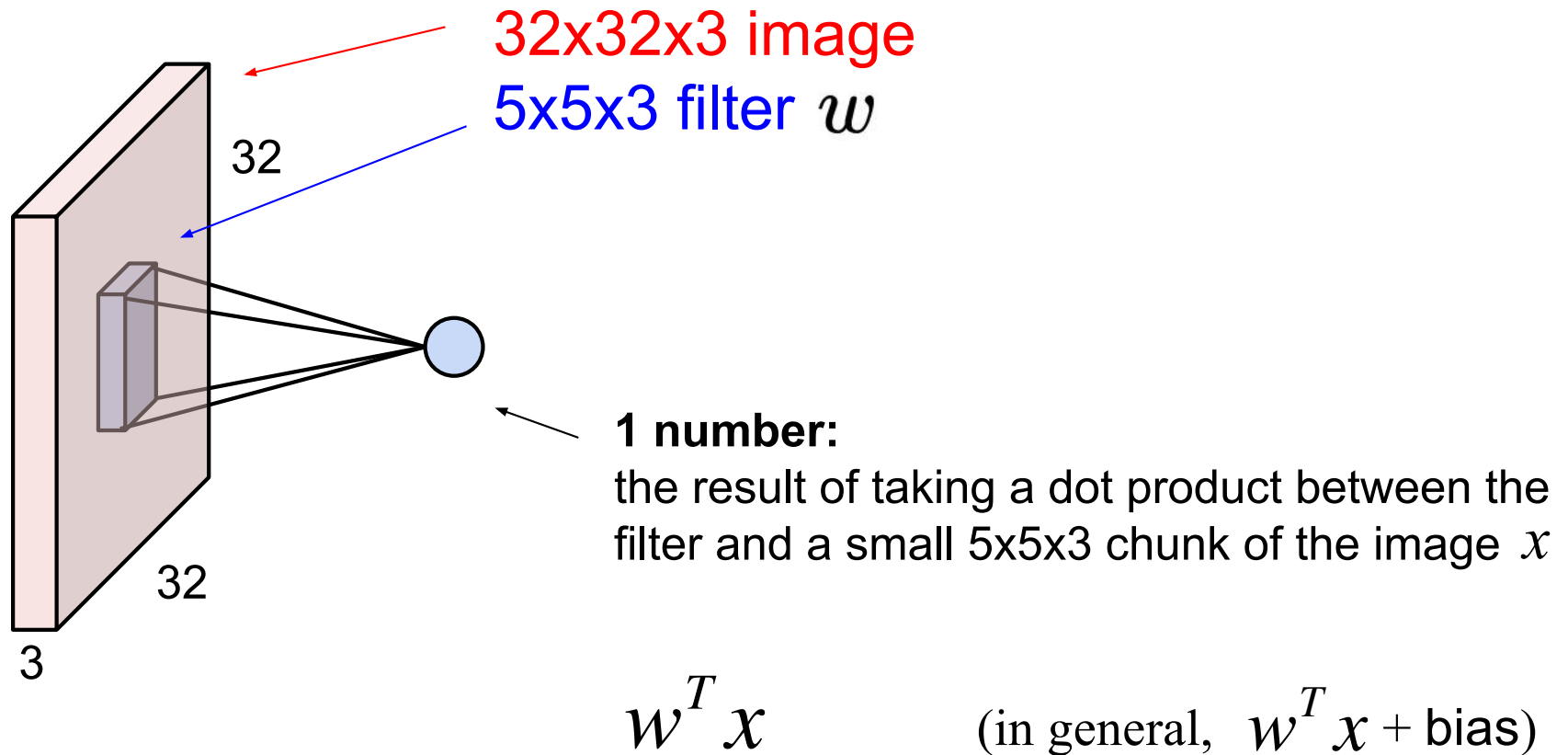
# Convolutional layer



Filter try to detect local patterns such as color, edges, ...

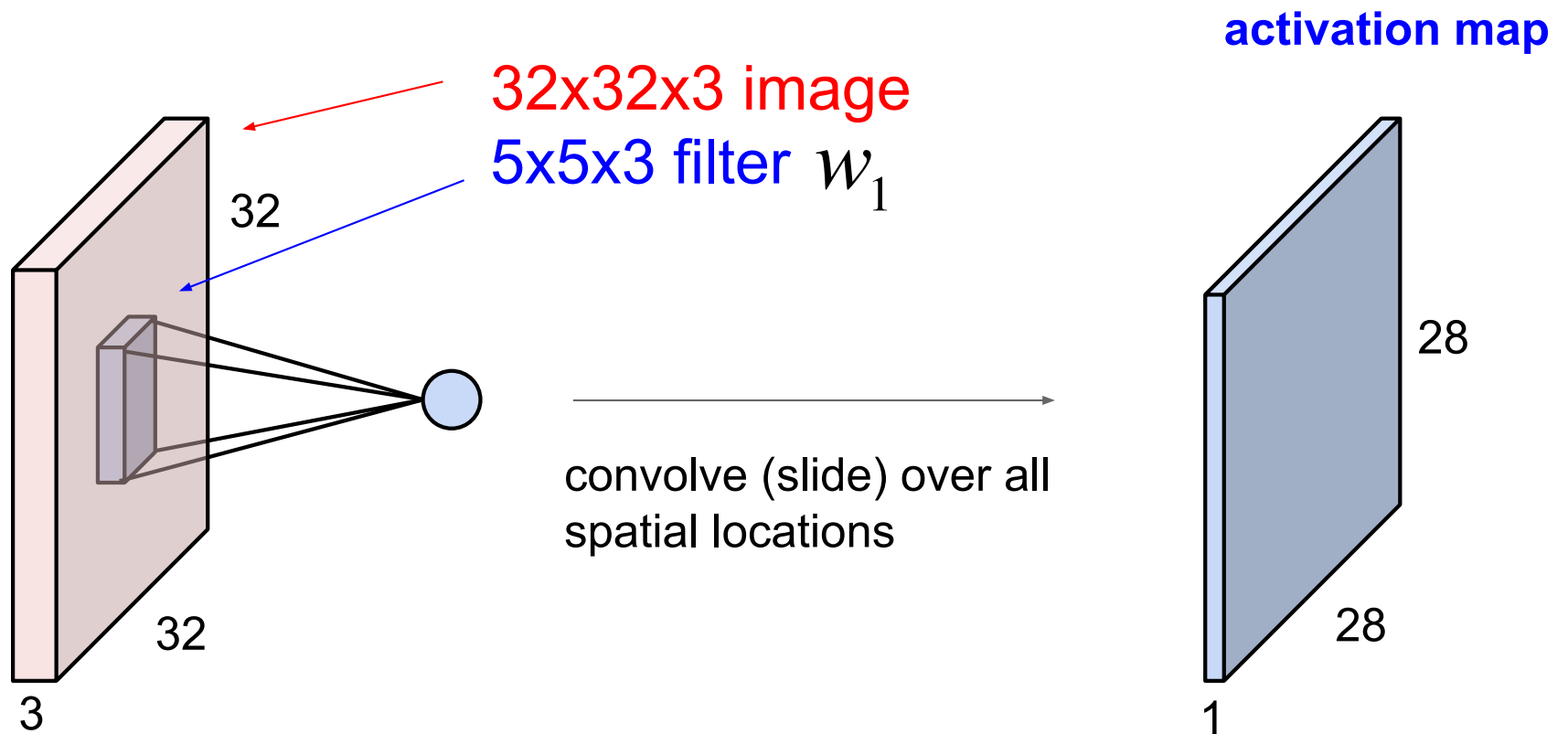


# Convolutional layer



Filter try to detect local patterns such as color, edges, ...

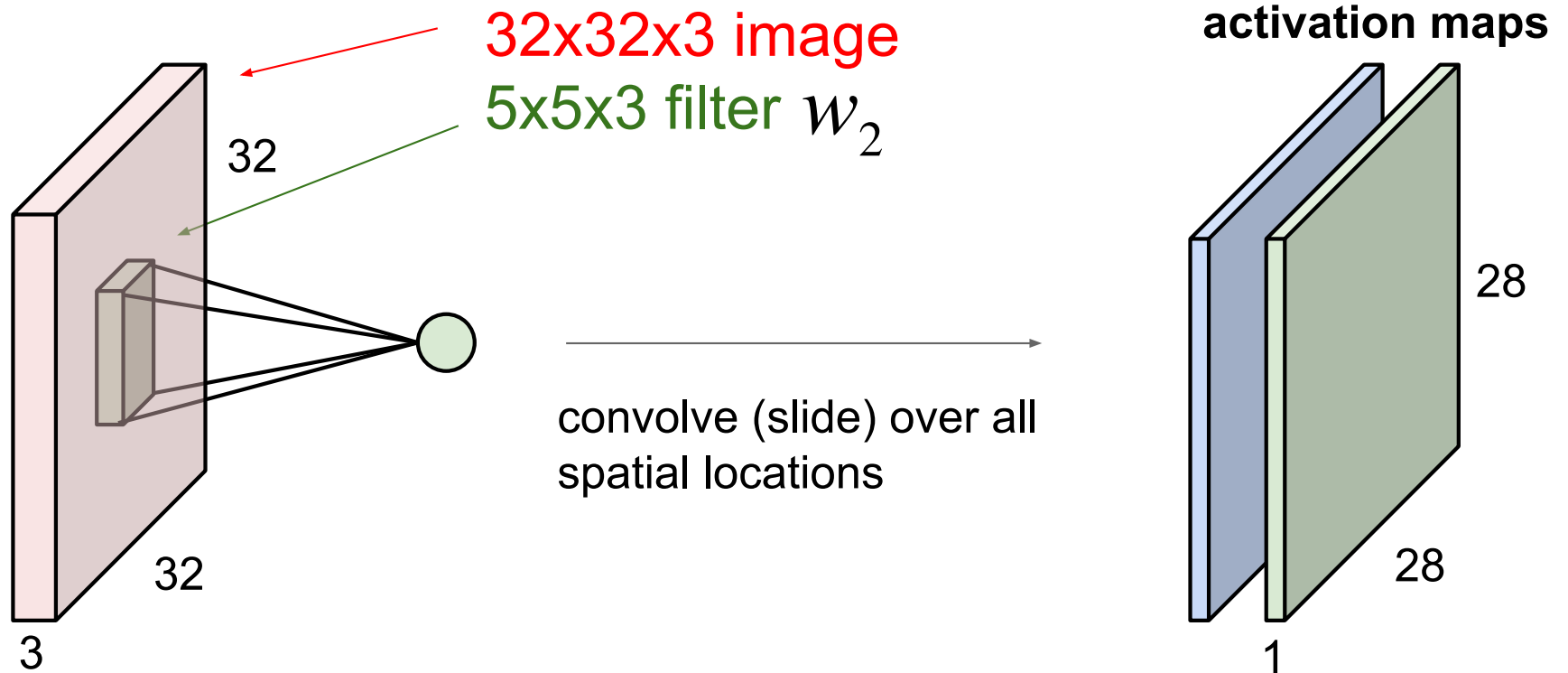
# Convolutional layer



Filter try to detect local patterns such as color, edges, ...

# Convolutional layer

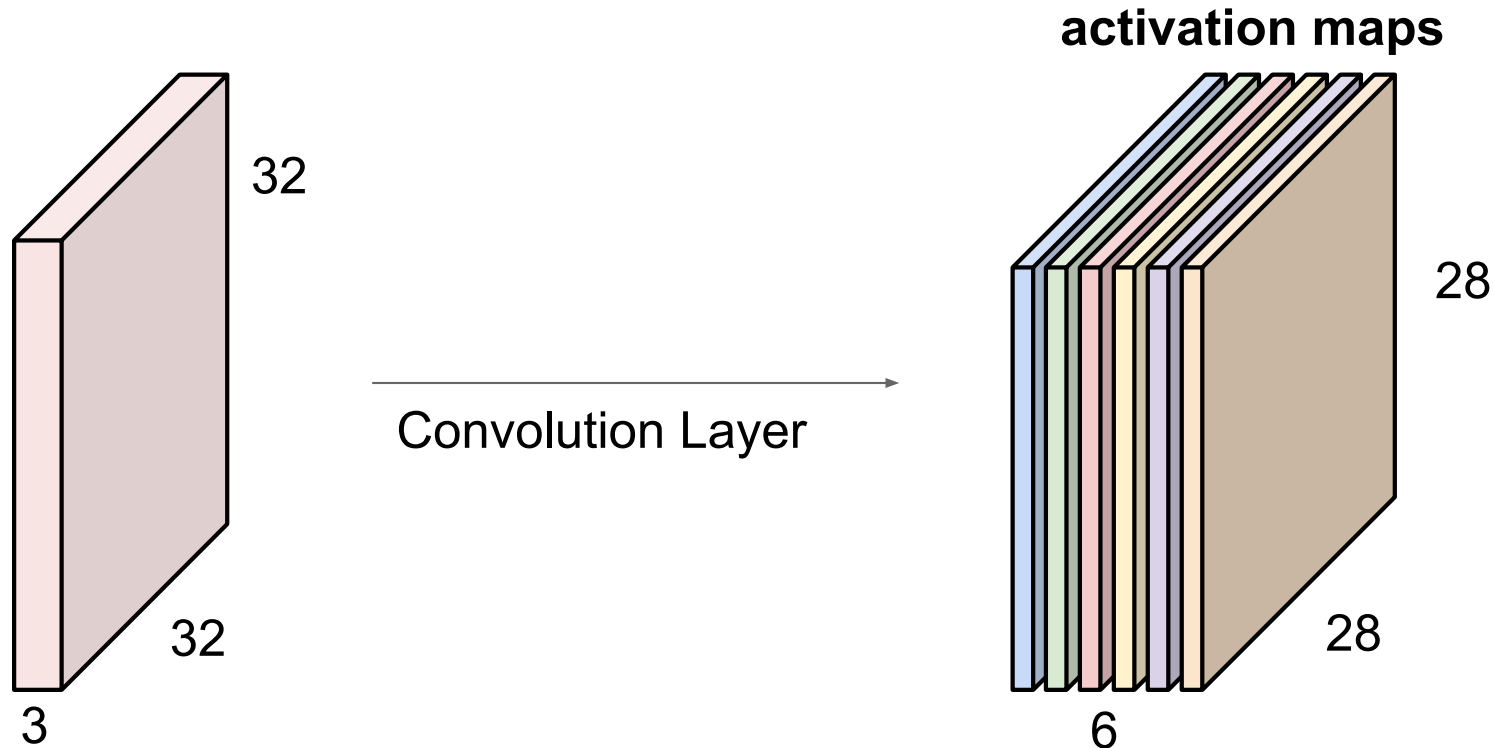
consider a second, green filter



Filter try to detect local patterns such as color, edges, ...

# Convolutional layer

For example, if we had 6  $5 \times 5$  filters, we'll get 6 separate activation maps:  
x3

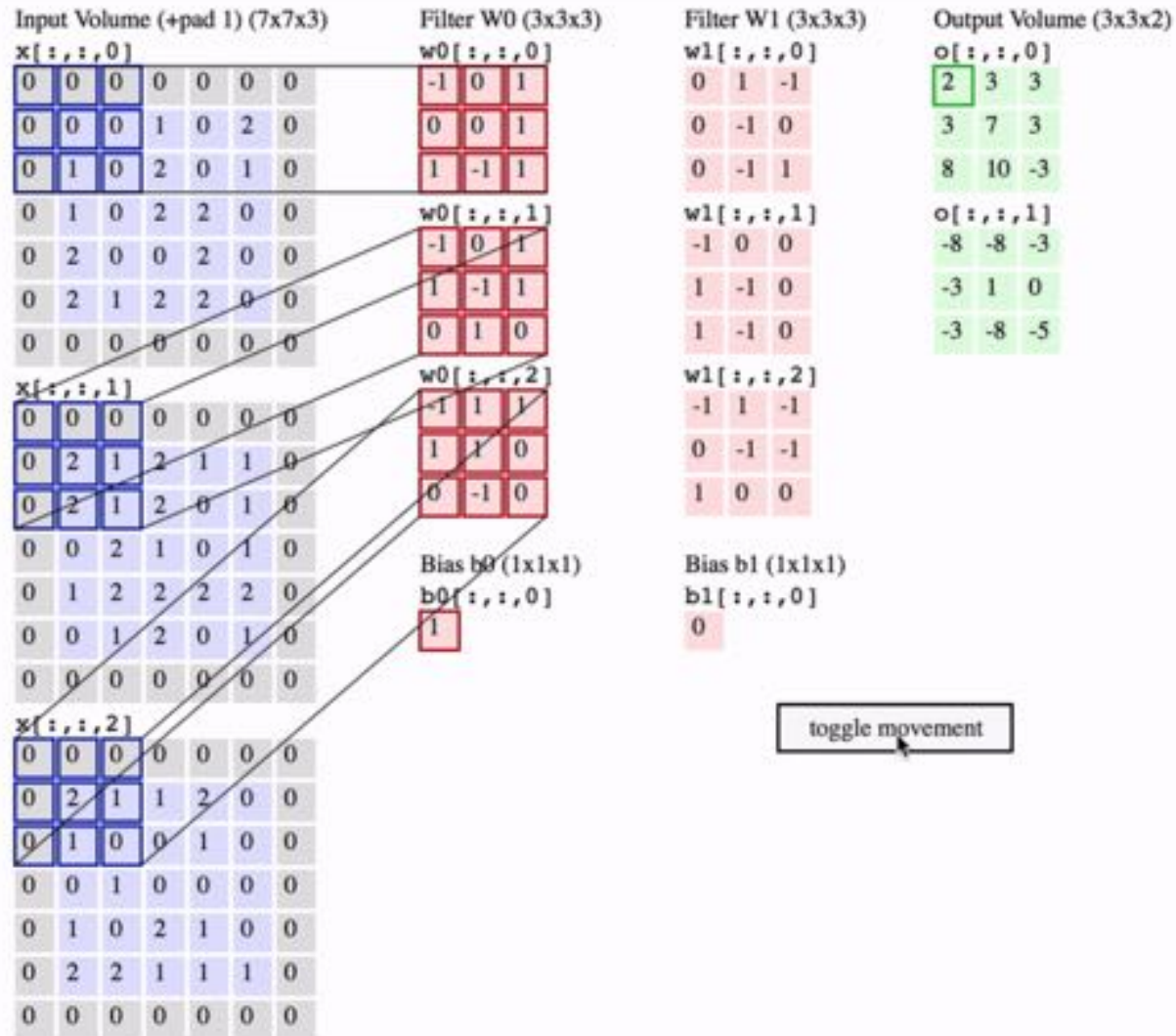


We stack these up to get a “new image” of size  $28 \times 28 \times 6$ !

Filter try to detect local patterns such as color, edges, ...

# Convolutional layer demo

To see this in action: <http://cs231n.github.io/assets/conv-demo/index.html>



# Why is it called convolutional layer?

**Because it is related to convolution of two signals:**

$$f[x, y] * g[x, y] = \sum_{n_1=-\infty}^{\infty} \sum_{n_2=-\infty}^{\infty} f[n_1, n_2] \cdot g[x - n_1, y - n_2]$$

elementwise multiplication and sum of a filter and the signal (image)

E.g. convolution by a bump function is a kind of "blurring", i.e., its effect on images is similar to what a short-sighted person experiences when taking off his or her glasses.



... or edges

Input image



Convolution Kernel

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

Feature map

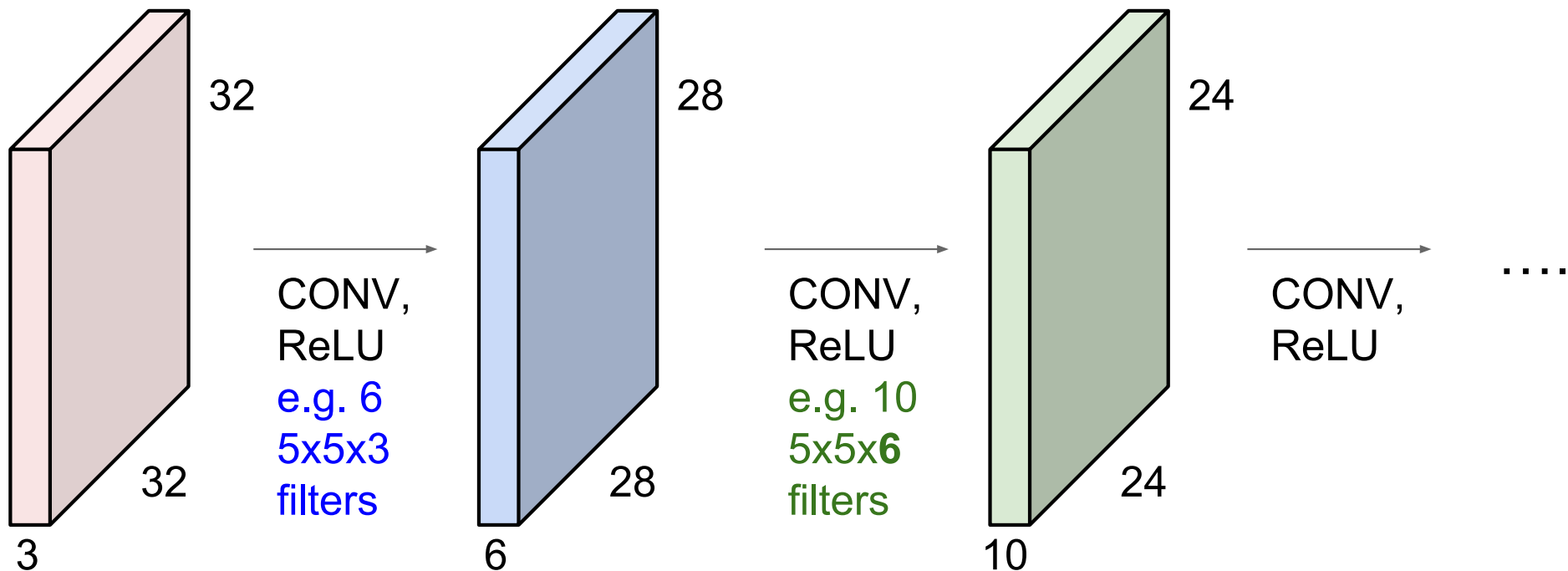


# Deep Convolutional Networks

- Convolutional layer
- Non-linear activation function ReLU
- Max pooling layer
- Fully connected layer

# Where is ReLU?

**Preview:** ConvNet is a sequence of Convolutional Layers, interspersed with activation functions

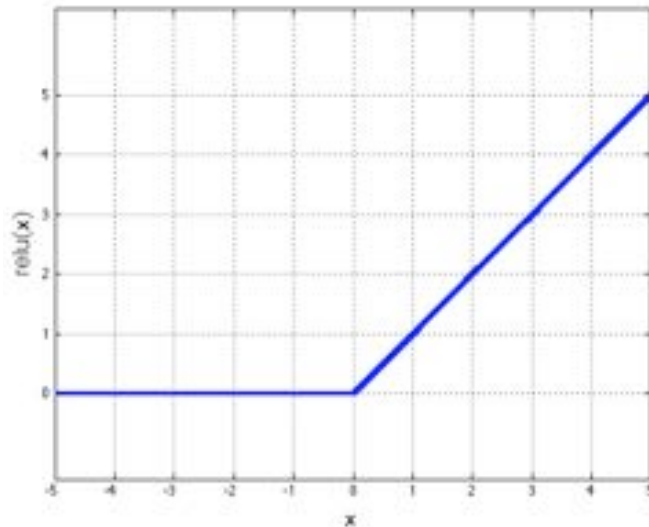




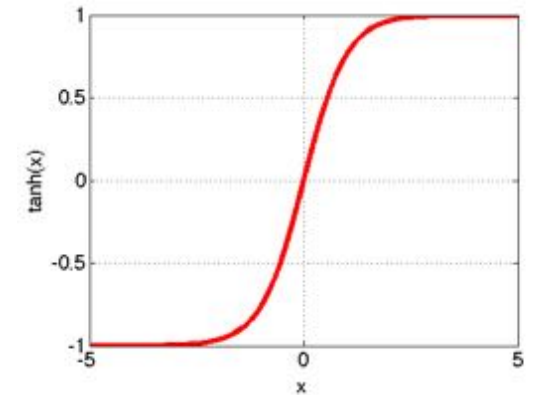
# Rectified Linear Unit, ReLU

- Non-linear activation functions are applied per-element
- Rectified linear unit (ReLU):

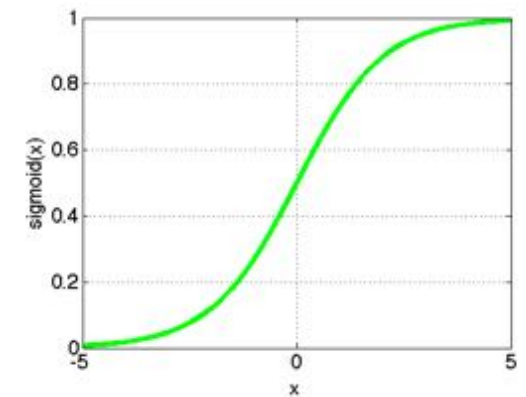
- $\max(0, x)$
- makes learning faster (in practice x6)
- avoids saturation issues (unlike sigmoid, tanh)
- simplifies training with backpropagation
- preferred option (works well)



$\tanh(x)$



$\text{sigmoid}(x) = (1 + e^{-x})^{-1}$



# **Your turn!**

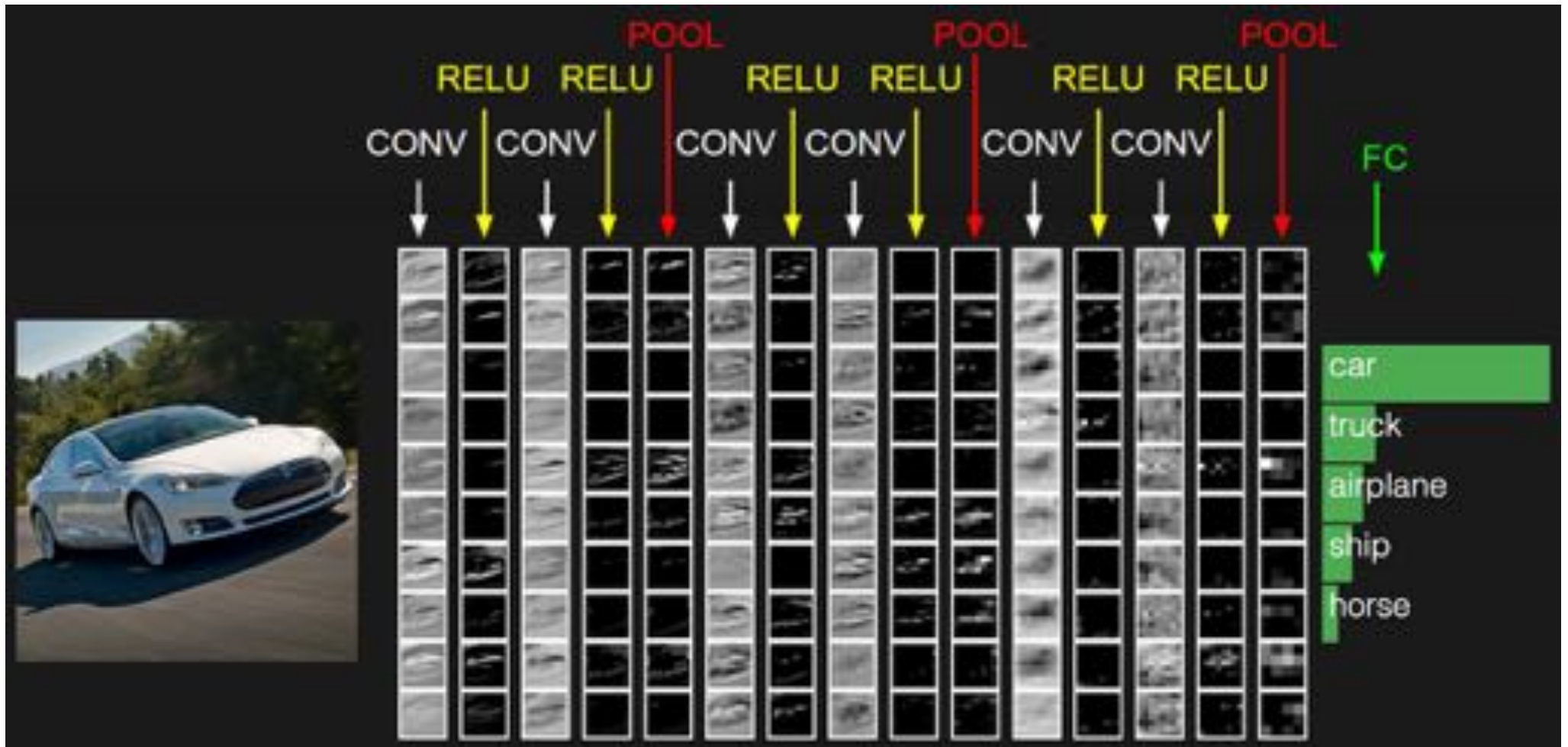
**State the formulas for the sigmoid and ReLU activation functions! Why do you think there are different activation functions? And when to you use which one?**

**You have 5 minutes!**

# Deep Convolutional Networks

- Convolutional layer
- Non-linear activation function ReLU
- Max pooling layer
- Fully connected layer

# Where is pooling?

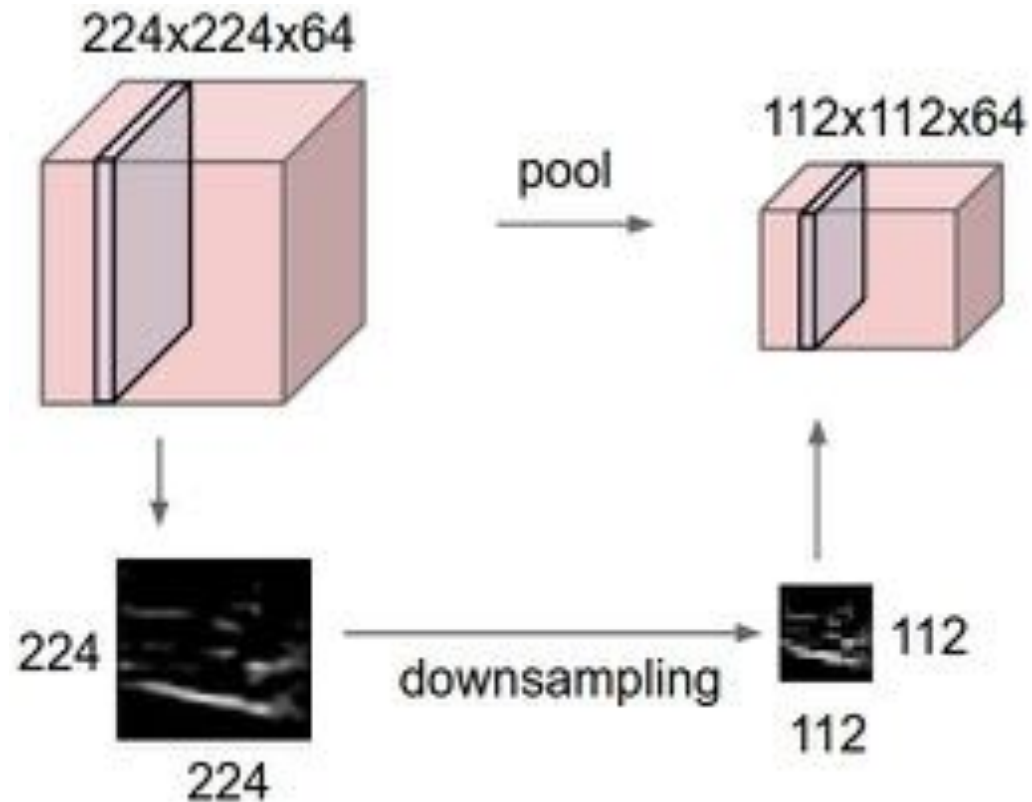


Two more layers to go: pooling and fully connected layers 😊

# Spatial pooling

## Pooling layer

- **Makes the representations smaller (downsampling)**
- Operates over each activation map independently
- Role: invariance to small transformation



# Max pooling

Single activation map

1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

max pool with 2x2 filters  
and stride 2



6	8
3	4

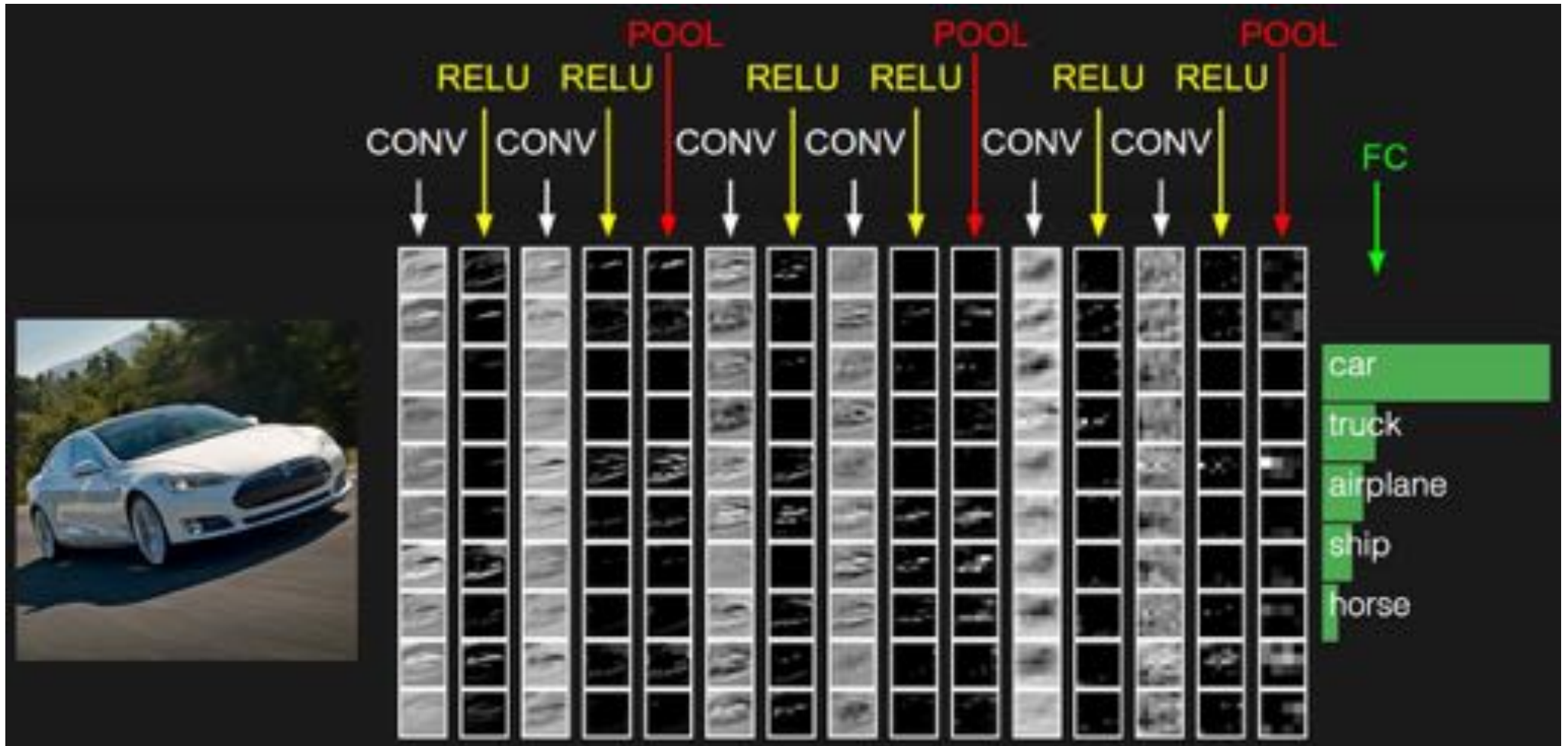
Alternatives:

- sum pooling
- overlapping pooling

# Deep Convolutional Networks

- Convolutional layer
- Non-linear activation function ReLU
- Max pooling layer
- Fully connected layer

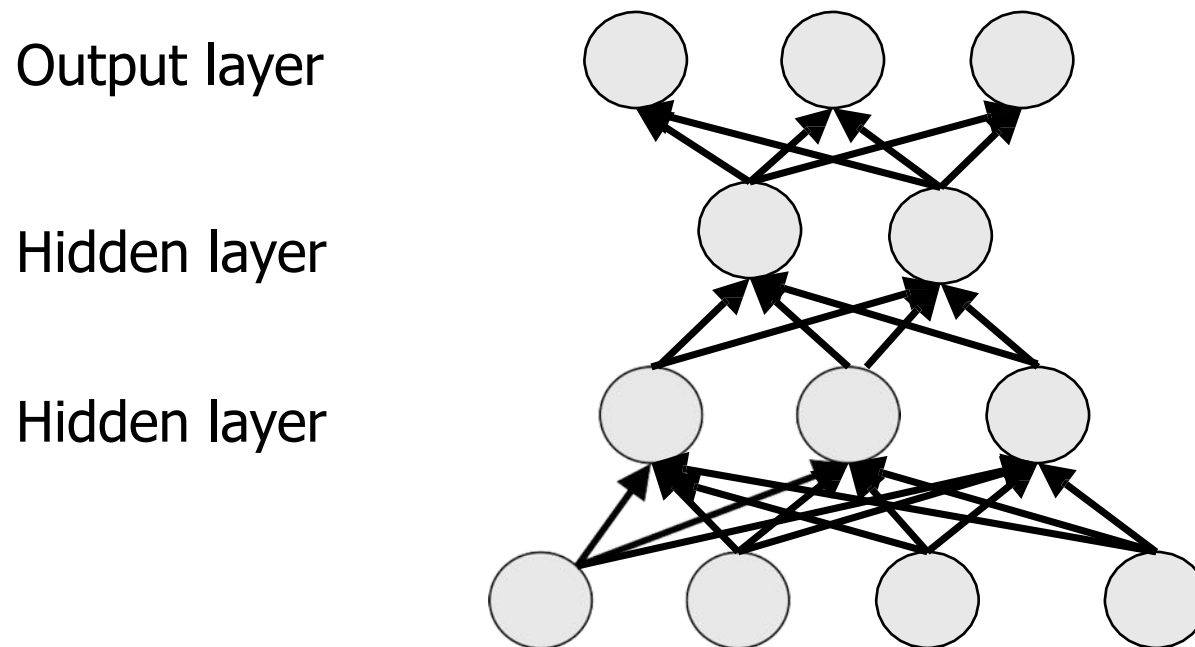
# Where is a fully connected layer (FC)?





# Fully connected (last) layer

Contains neurons that connect to the entire input volume, as in ordinary Neural Networks:

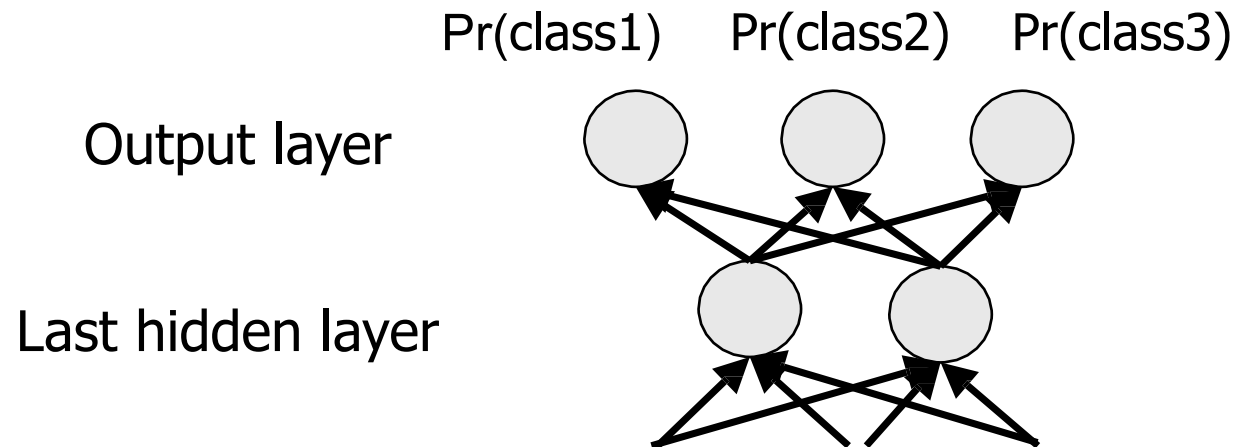


neurons between two adjacent layers are fully pairwise connected, but neurons within a single layer share no connections

# Output layer

## In classification:

- the output layer is fully connected with **number of neurons equal to number of classes**
- followed by softmax non-linear activation



# Running CNNs demo

To see this in action, check

<http://cs.stanford.edu/people/karpathy/convnetjs/demo/cifar10.html>

[https://www.tensorflow.org/tutorials/deep\\_cnn](https://www.tensorflow.org/tutorials/deep_cnn)

[http://scienceai.github.io/neocortex/cifar10\\_cnn/](http://scienceai.github.io/neocortex/cifar10_cnn/)

- Deep Networks are composed of multiple levels of non-linear operations, such as neural nets with many hidden layers
- We went through the architecture of a standard deep network and have seen all major ingredients.

## Deep Convolutional Networks

- ✓ Convolutional layer
- ✓ Non-linear activation function ReLU
- ✓ Max pooling layer
- ✓ Fully connected layer

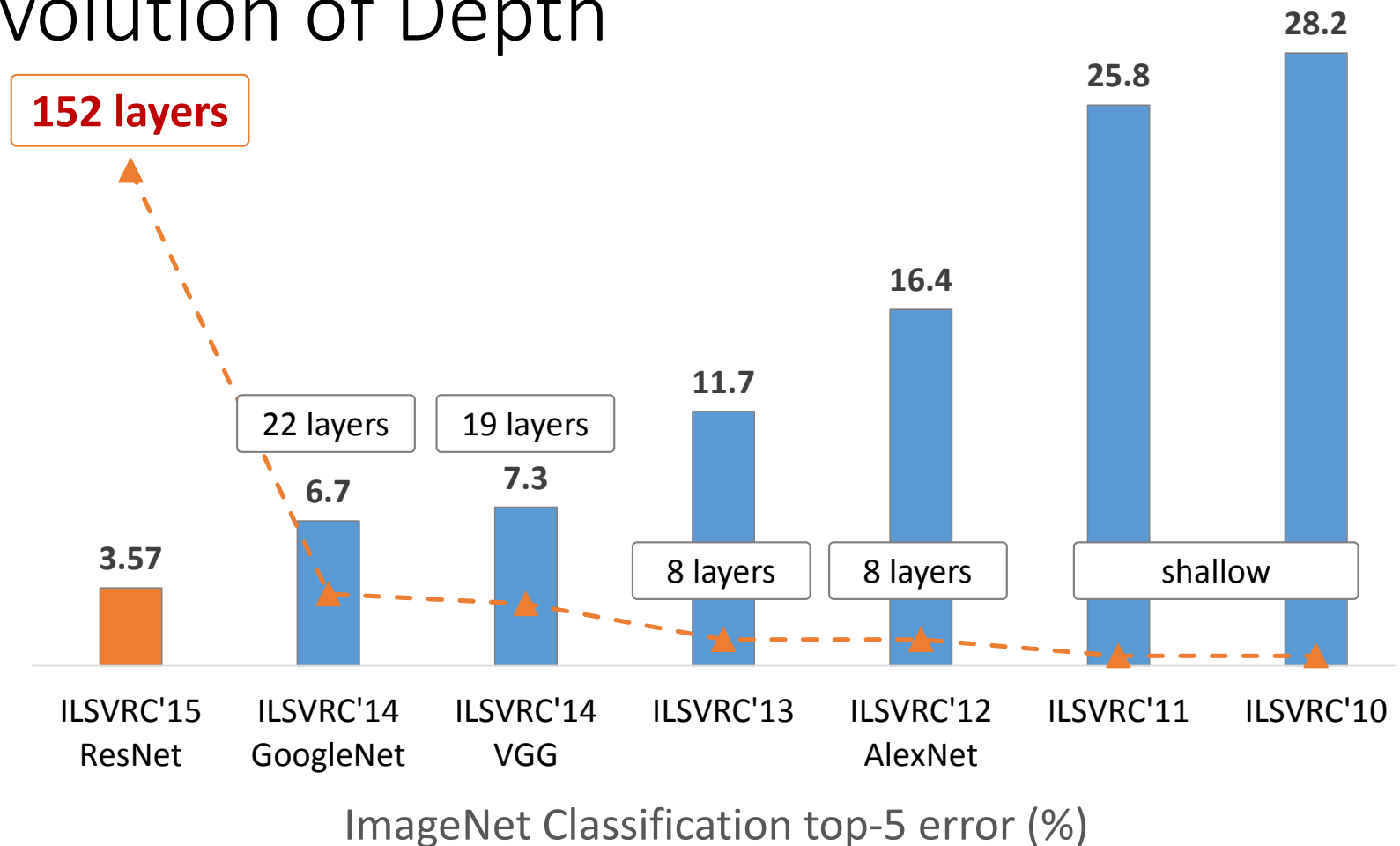
**Your turn!**

**What do you think? Are deep  
networks superhuman?**

**You have 5 minutes!**

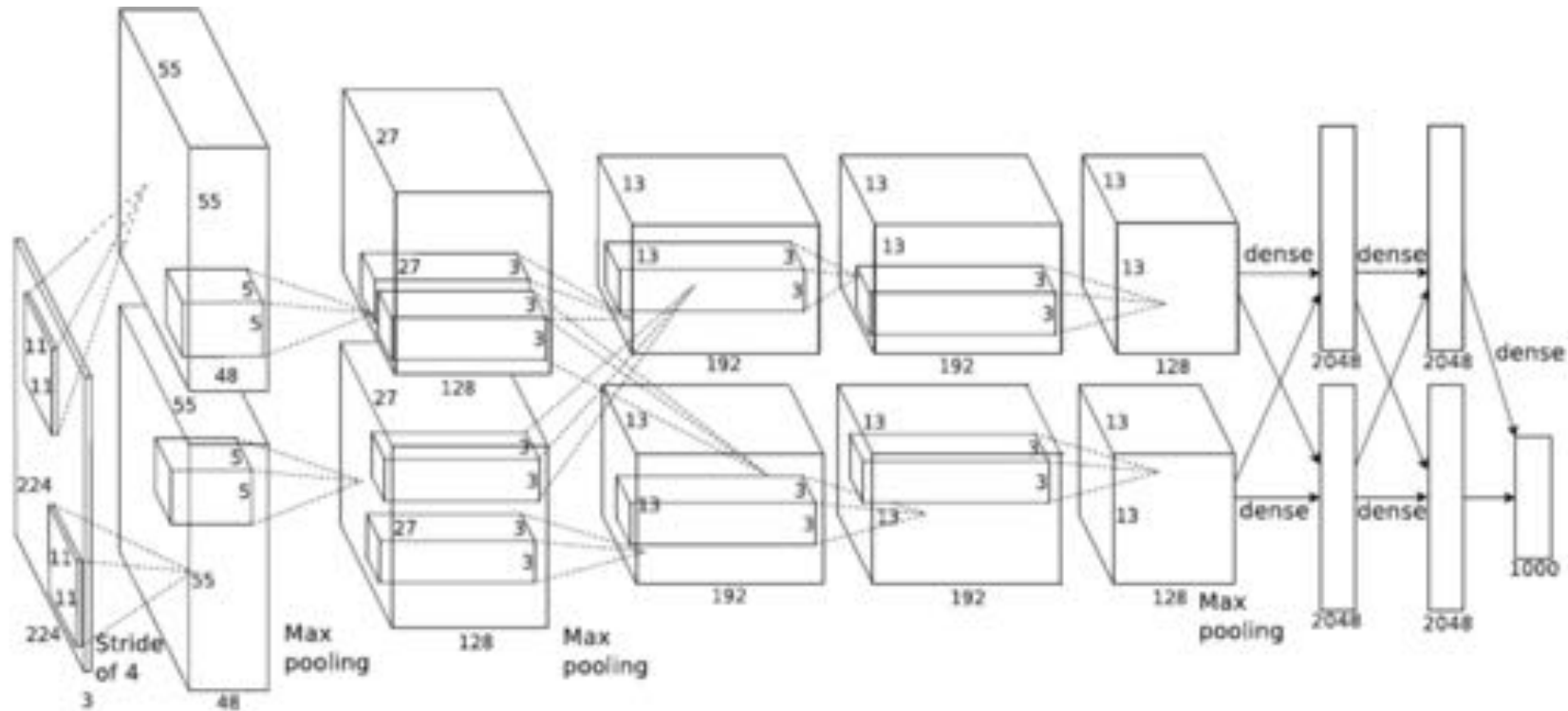
# Fast-forward to today

## Revolution of Depth



Kaiming He, et al. Deep residual learning for Image Recognition, 2015

# A “deeper” example: AlexNet



- Input: RGB image
- Output: class label (out of 1000 classes)
- 5 convolutional layers + 3 fully connected layers (with ReLU, max pooling)
- trained using 2 streams (2 GPU). In this lecture, we will present the architecture as 1 stream for simplicity and clarity.

# AlexNet was trained on ImageNet

- ❑ 15M images
- ❑ 22K categories
- ❑ Images collected from Web
- ❑ Human labelers (Amazon's Mechanical Turk crowd-sourcing)
- ❑ ImageNet Large Scale Visual Recognition Challenge (ILSVRC-2010)
  - 1K categories
  - 1.2M training images (~1000 per category)
  - 50,000 validation images
  - 150,000 testing images
- ❑ RGB images; mean normalization
- ❑ Variable-resolution, but this architecture scales them to 256x256 size



# ImageNet Tasks

## Classification goals:

- ❑ Make 1 guess about the label (Top-1 error)
- ❑ make 5 guesses about the label (Top-5 error)



# Results of AlexNet on ImageNet



# What have we learnt so far?

- Deep Neural Networks aim at learning feature hierarchies
- We have understood the structure of convolutional neural networks, one of the central DNN architectures
  - Convolutional layer, ReLU, Max pooling layer, fully connected layer
- DNNs are rather large but result in state-of-the-art performance on many tasks

# Let's now consider training in more details

- Training Deep Convolutional Neural Networks
  - Stochastic gradient descent
  - Backpropagation
  - Initialization
- Preventing overfitting
  - Dropout regularization
  - Data augmentation
- Fine-tuning

# Stochastic gradient descent (SGD)

## (Mini-batch) SGD

Initialize the parameters randomly but smart

Loop over the whole training data (multiple times):

❑ **Sample** a datapoint (a batch of data)

❑ **Forward** propagate the data through the network, compute the classification loss.

$$E = \frac{1}{2} (y_{\text{predicted}} - y_{\text{true}})^2$$

❑ **Backpropagate** the gradient of the loss w.r.t. parameters through the network

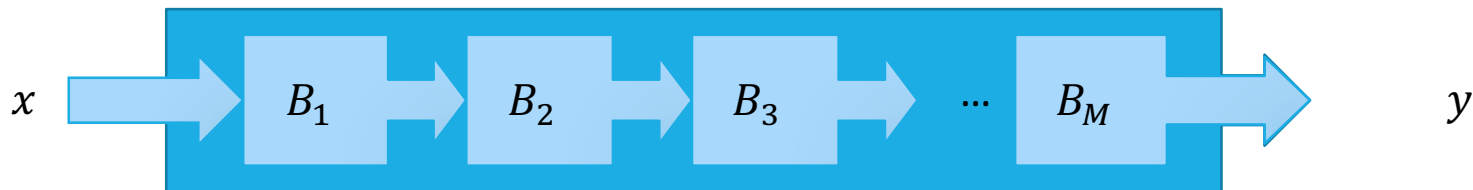
❑ **Update** the parameters using the gradient  $w^{t+1} = w^t - \alpha \cdot \frac{dE}{dw}(w^t)$

# Recall Backpropagation

Implementations typically maintain a modular structure, where the nodes/bricks implement the forward and backward procedures

## Sequential brick

---



### Propagation

- Apply propagation rule to  $B_1, B_2, B_3, \dots, B_M$ .

### Back-propagation

- Apply back-propagation rule to  $B_M, \dots, B_3, B_2, B_1$ .

# Recall Backpropagation

Last layer used for classification

## Square loss brick

---



Propagation

$$E = y = \frac{1}{2}(x - d)^2$$

Back-propagation

$$\frac{\partial E}{\partial x} = (x - d)^T \frac{\partial E}{\partial y} = (x - d)^T$$

# Recall Backpropagation

Typical choices

## Loss bricks

---

		Propagation	Back-propagation
Square		$y = \frac{1}{2}(x - d)^2$	$\frac{\partial E}{\partial x} = (x - d)^T \frac{\partial E}{\partial y}$
Log	$c = \pm 1$	$y = \log(1 + e^{-cx})$	$\frac{\partial E}{\partial x} = \frac{-c}{1 + e^{cx}} \frac{\partial E}{\partial y}$
Hinge	$c = \pm 1$	$y = \max(0, m - cx)$	$\frac{\partial E}{\partial x} = -c \mathbb{I}\{cx < m\} \frac{\partial E}{\partial y}$
LogSoftMax	$c = 1 \dots k$	$y = \log(\sum_k e^{x_k}) - x_c$	$\left[\frac{\partial E}{\partial x}\right]_s = (e^{x_s} / \sum_k e^{x_k} - \delta_{sc}) \frac{\partial E}{\partial y}$
MaxMargin	$c = 1 \dots k$	$y = \left[ \max_{k \neq c} \{x_k + m\} - x_c \right]_+$	$\left[\frac{\partial E}{\partial x}\right]_s = (\delta_{sk^*} - \delta_{sc}) \mathbb{I}\{E > 0\} \frac{\partial E}{\partial y}$

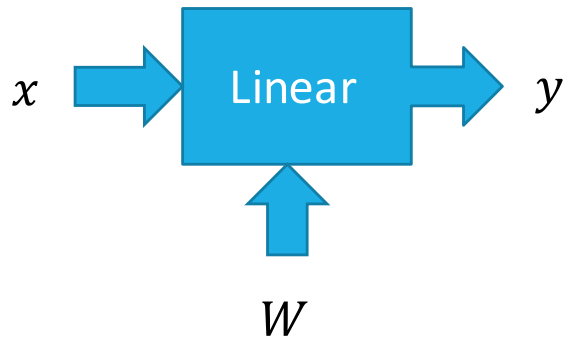


# Recall Backpropagation

Fully connected layers, convolutional layers (dot product)

## Linear brick

---



Propagation

$$y = Wx$$

Back-propagation

$$\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} W$$

$$\frac{\partial E}{\partial W} = x \frac{\partial E}{\partial v}$$

# Recall Backpropagation

Non-linear activations

## Activation function brick

---



Propagation

$$y_s = f(x_s)$$

Back-propagation

$$\left[ \frac{\partial E}{\partial x} \right]_s = \left[ \frac{\partial E}{\partial y} \right]_s f'(x_s)$$

# Recall Backpropagation

Typical non-linear activations

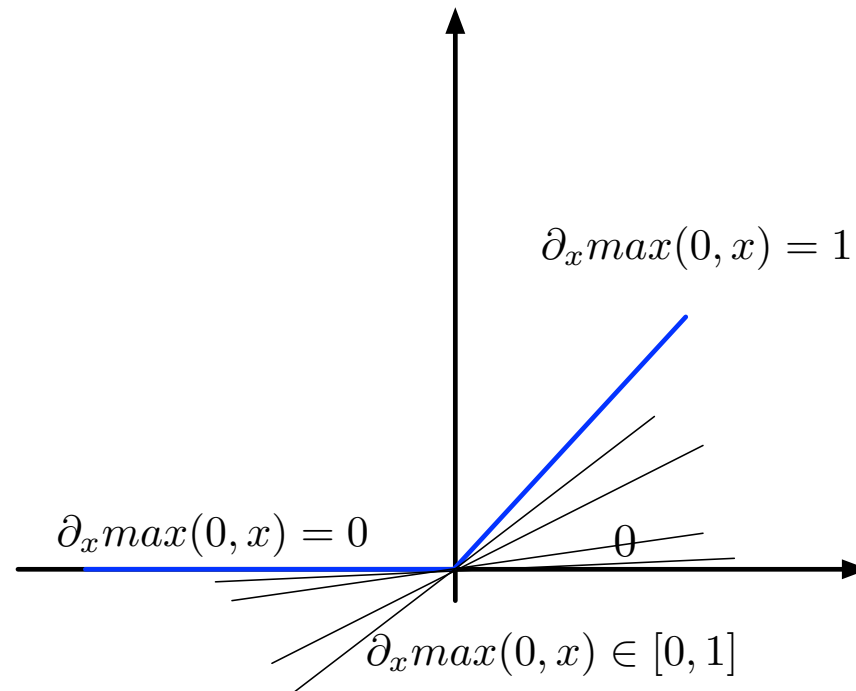
## Activation functions

---

	Propagation	Back-propagation
Sigmoid	$y_s = \frac{1}{1+e^{-x_s}}$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \frac{1}{(1+e^{x_s})(1+e^{-x_s})}$
Tanh	$y_s = \tanh(x_s)$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \frac{1}{\cosh^2 x_s}$
ReLU	$y_s = \max(0, x_s)$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \mathbb{I}\{x_s > 0\}$
Ramp	$y_s = \min(-1, \max(1, x_s))$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \mathbb{I}\{-1 < x_s < 1\}$

# Subgradients

ReLU gradient is not defined at  $x=0$ , use a **subgradient** instead




Practice note: during training, when a 'kink' point was crossed, the numerical gradient will not be exact.

# Some SGD guidelines

## Initialization of the (filter) weights

- don't initialize with zero
- don't initialize with the same value
- sample from uniform distribution  $U[-b,b]$  around zero or from Normal distribution

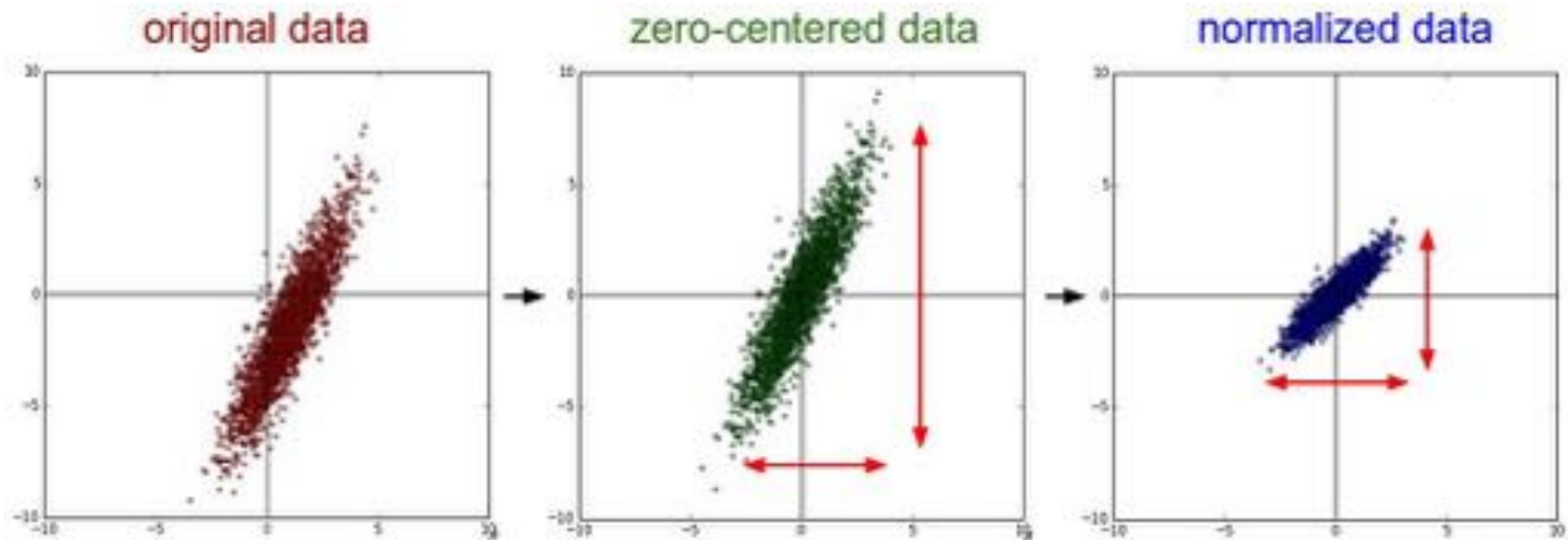
Decay of the learning rate  $\alpha$    $w^{t+1} = w^t - \alpha \cdot \frac{dE}{dw}(w^t)$

as we get closer to the optimum, take smaller update steps

- start with large learning rate (e.g. 0.1)
- maintain until validation error stops improving
- divide learning rate by 2 and go back to previous step

# Normalization is important

Data preprocessing: normalization (recall e.g. clustering)

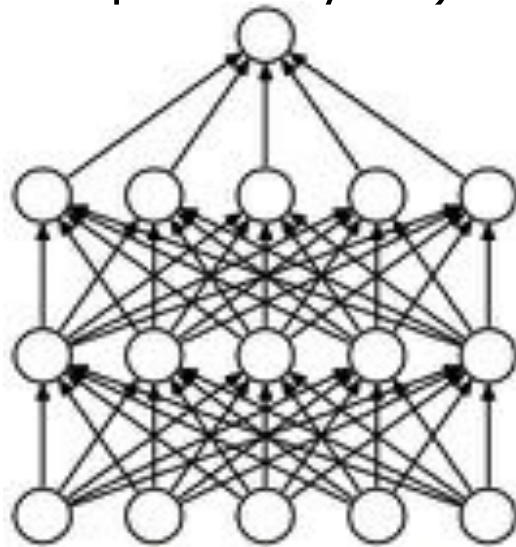


In images: subtract the mean of RGB intensities of the whole dataset from each pixel

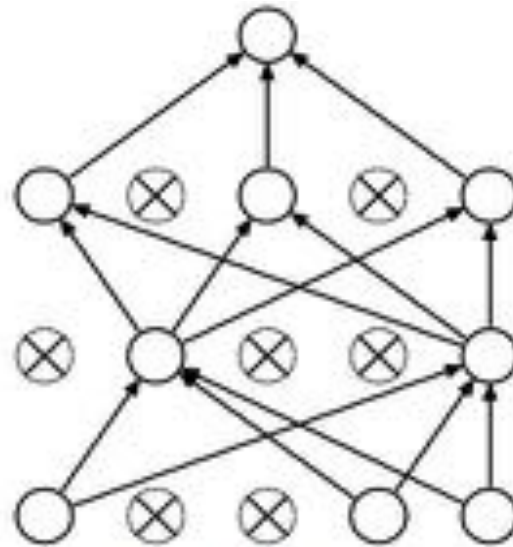
# Also regularization

## Regularization: **Dropout**

“randomly set some neurons to zero in the forward pass”  
(with probability 0.5)



(a) Standard Neural Net



(b) After applying dropout.

*[Srivastava et al., 2014]*

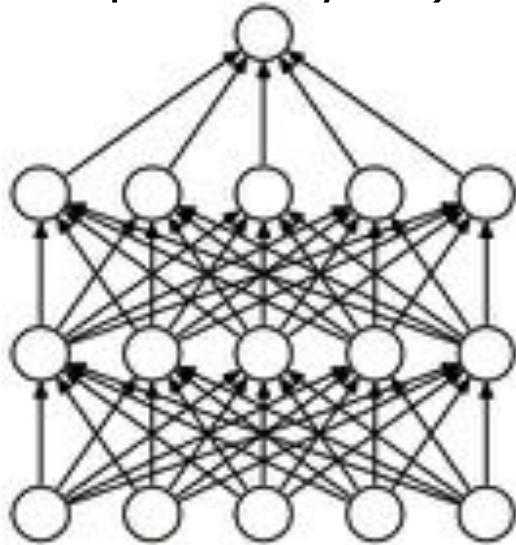
The neurons which are “dropped out” do not contribute to the forward pass and do not participate in backpropagation.

So every time an input is presented, the neural network samples different architecture, but all these architectures share weights.

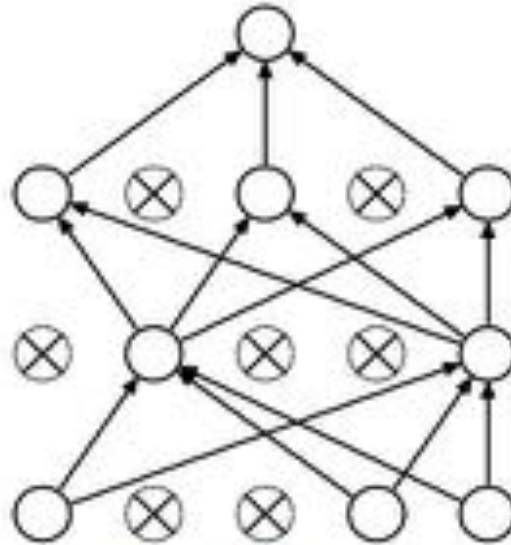
# Also regularization

## Regularization: **Dropout**

“randomly set some neurons to zero in the forward pass”  
(with probability 0.5)



(a) Standard Neural Net



(b) After applying dropout.

*[Srivastava et al., 2014]*

At test time, use average predictions over all the ensemble of models  
(weighted with 0.5)

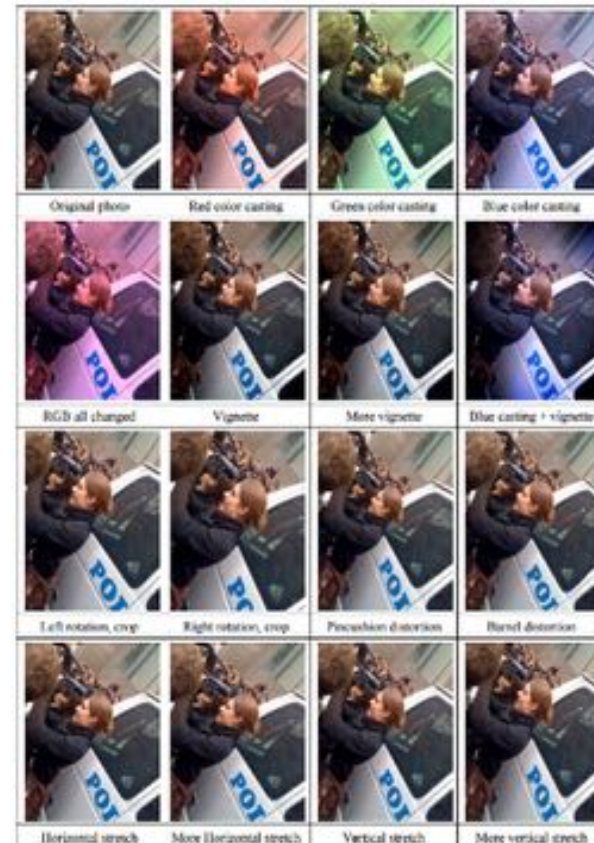


# And data augmentation

The easiest and most common method **to reduce overfitting** on image data is to artificially **enlarge the dataset** using label-preserving transformations.

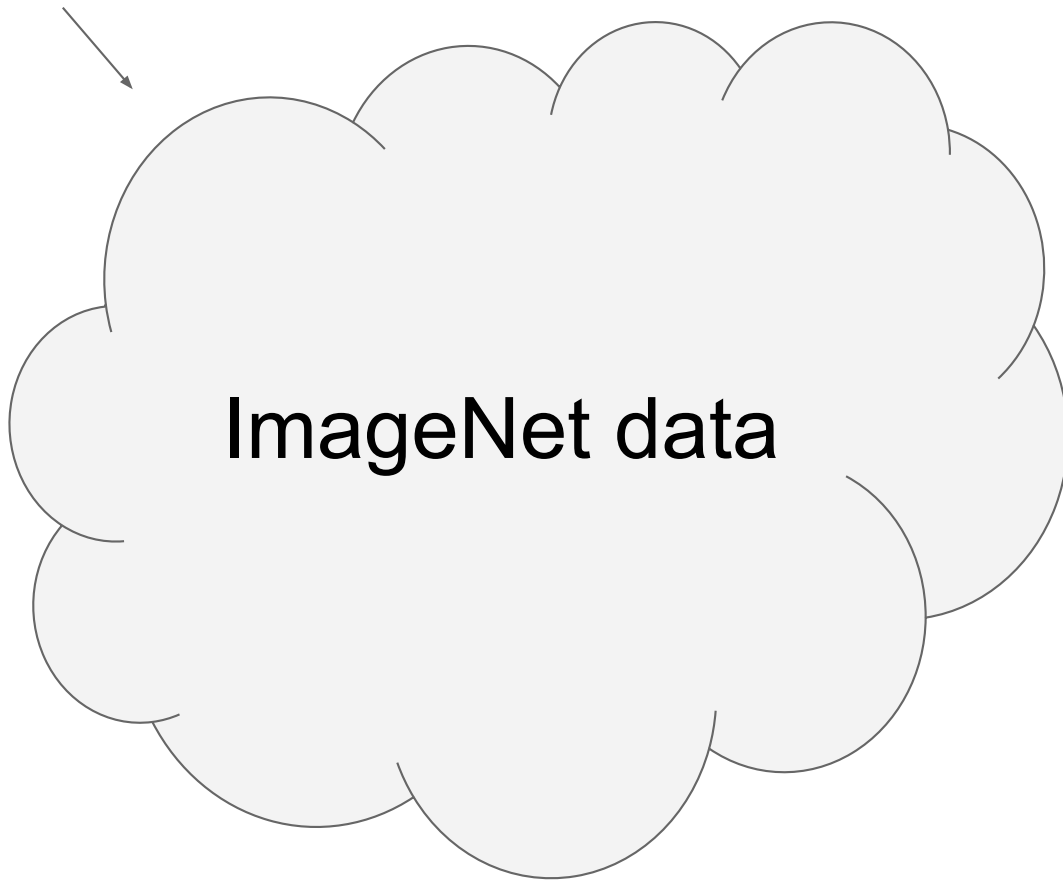
Forms of data augmentation (for images):

- horizontal reflections
- random crop
- changing RGB intensities
- image translation

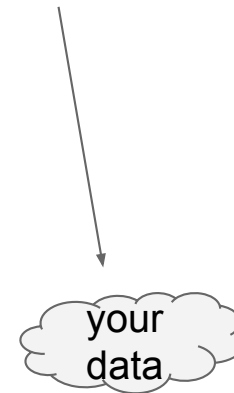


# As well as fine-tuning

1. Train on ImageNet



2. Finetune network on your own data

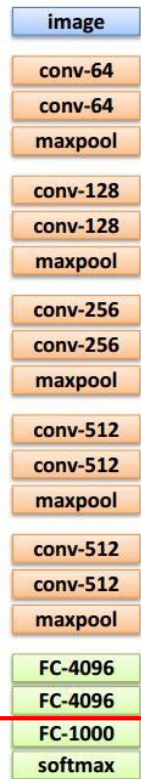


# Fine-tuning

## Transfer Learning with CNNs



1. Train on ImageNet



2. If small dataset: fix all weights (treat CNN as fixed feature extractor), retrain only the classifier

i.e. swap the Softmax layer at the end

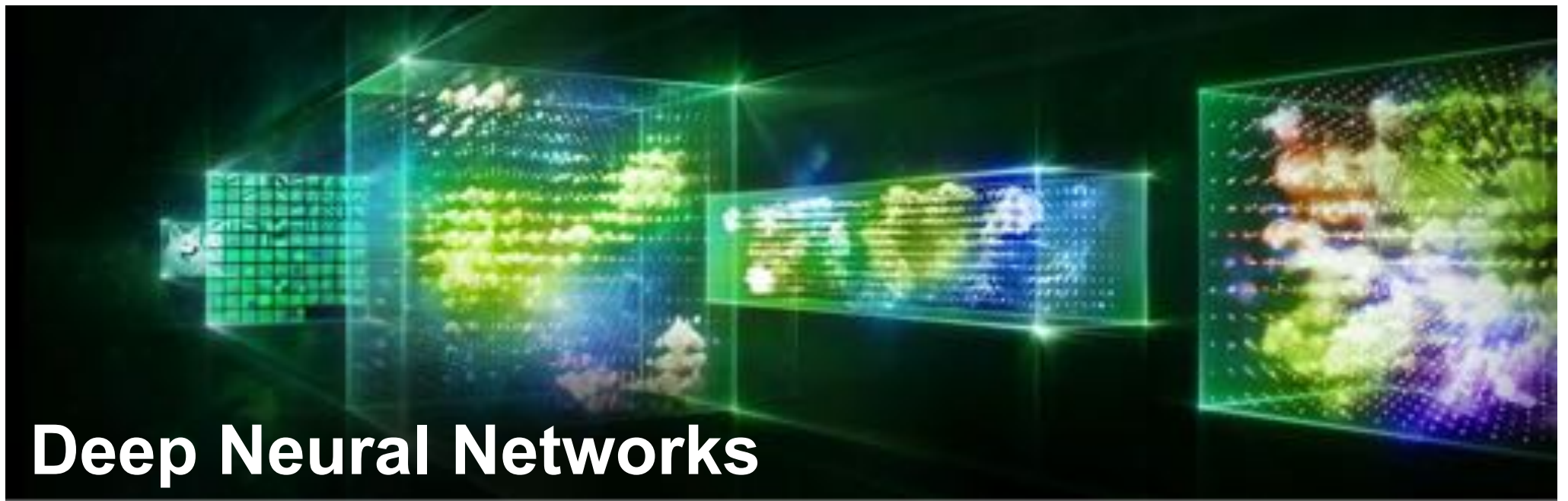


3. If you have medium sized dataset, “**finetune**” instead: use the old weights as initialization, train the full network or only some of the higher layers

retrain bigger portion of the network, or even all of it.

A lot of pre-trained models in Caffe Model Zoo

<https://github.com/BVLC/caffe/wiki/Model-Zoo>



# Deep Neural Networks

- Aim at learning feature hierarchies
- Typical architectures: Convolutional layer, ReLU, Max pooling layer, fully connected layer
- Rather large networks but SOTA performance on many tasks
- Training done via SGD together with normalization, regularization, and data augmentation
- Large networks often used in a pre-trained fashion

And this is the  
major idea of  
deep learning!



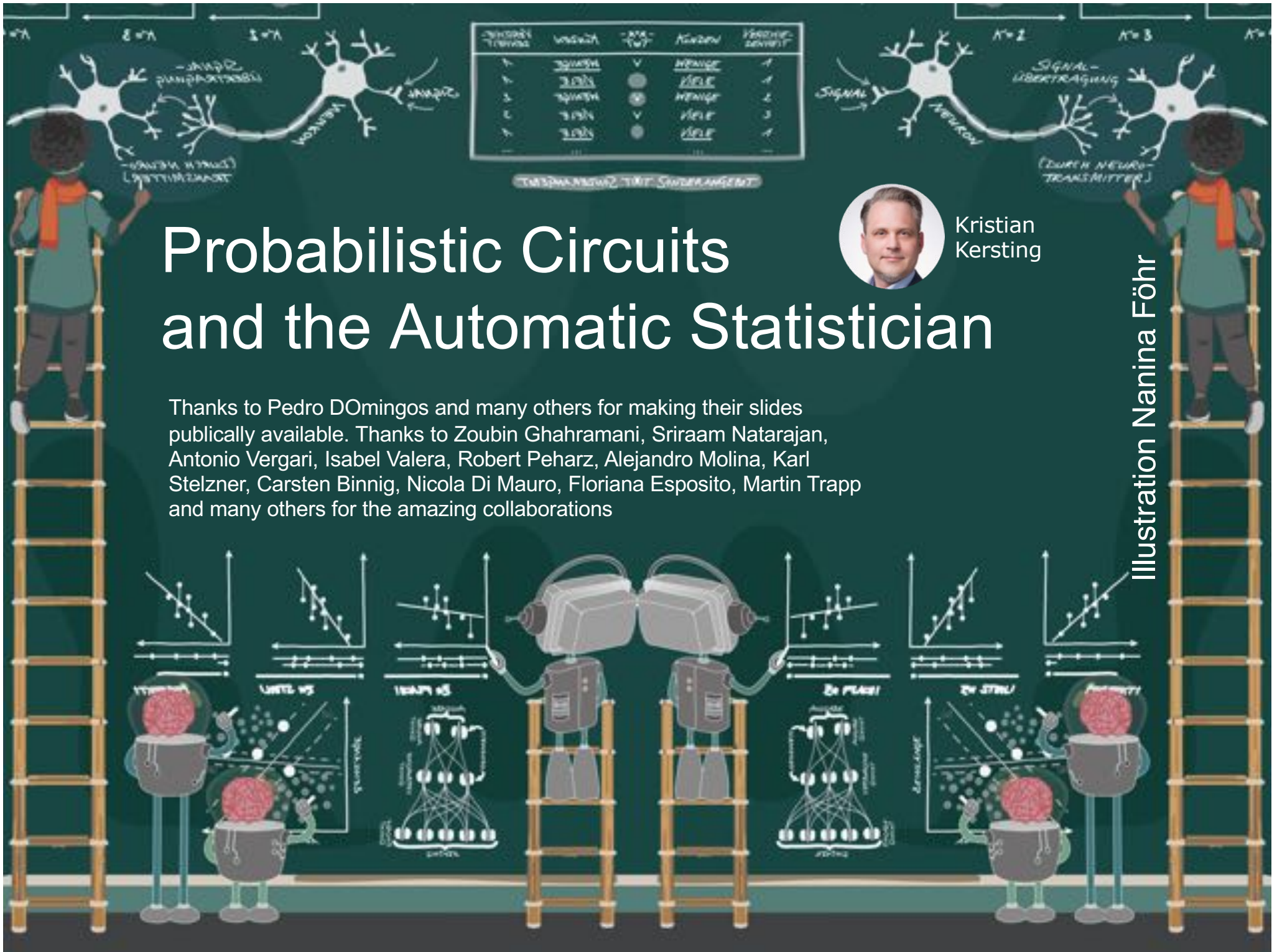
# Probabilistic Circuits and the Automatic Statistician



Kristian Kersting

Thanks to Pedro Domingos and many others for making their slides publically available. Thanks to Zoubin Ghahramani, Sriraam Natarajan, Antonio Vergari, Isabel Valera, Robert Peharz, Alejandro Molina, Karl Stelzner, Carsten Binnig, Nicola Di Mauro, Floriana Esposito, Martin Trapp and many others for the amazing collaborations

Illustration Nanina Föhr

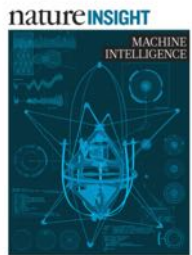


# Deep learning makes the difference



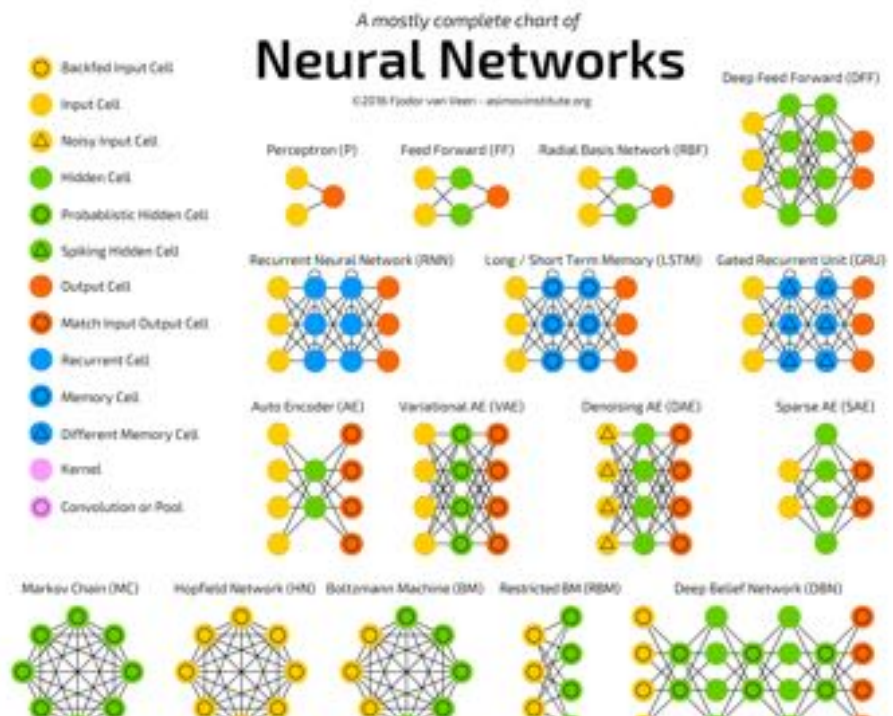
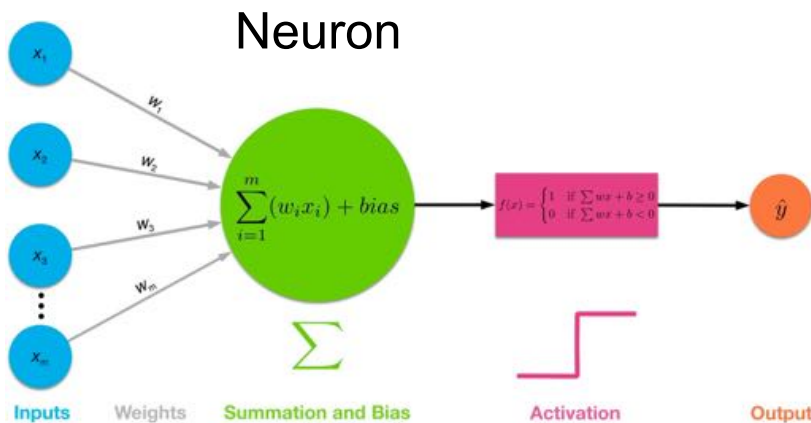
Data are now ubiquitous. There is great value from understanding this data, building models and making predictions

# Deep Neural Networks



Potentially much more powerful than shallow architectures, represent computations

[LeCun, Bengio, Hinton Nature 521, 436–444, 2015]



**Differentiable Programming**

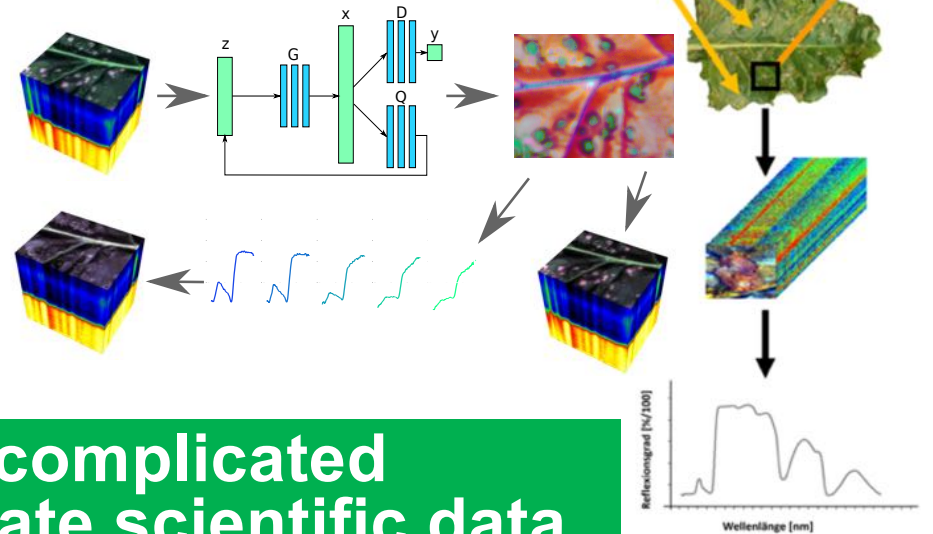
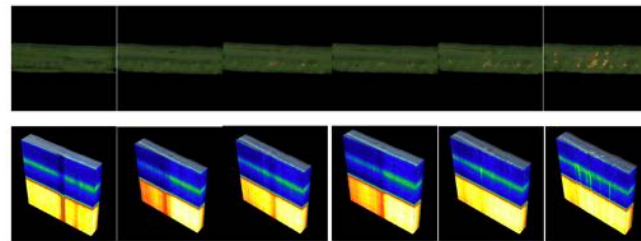
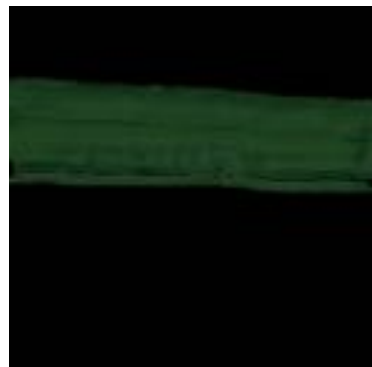


# Deep Neural Networks



Potentially much more powerful than shallow architectures, represent computations

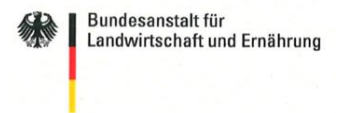
[LeCun, Bengio, Hinton Nature 521, 436–444, 2015]



They “develop intuition” about complicated biological processes and generate scientific data

[Schramowski, Brugger, Mahlein, Kersting 2019]

DePhenSe

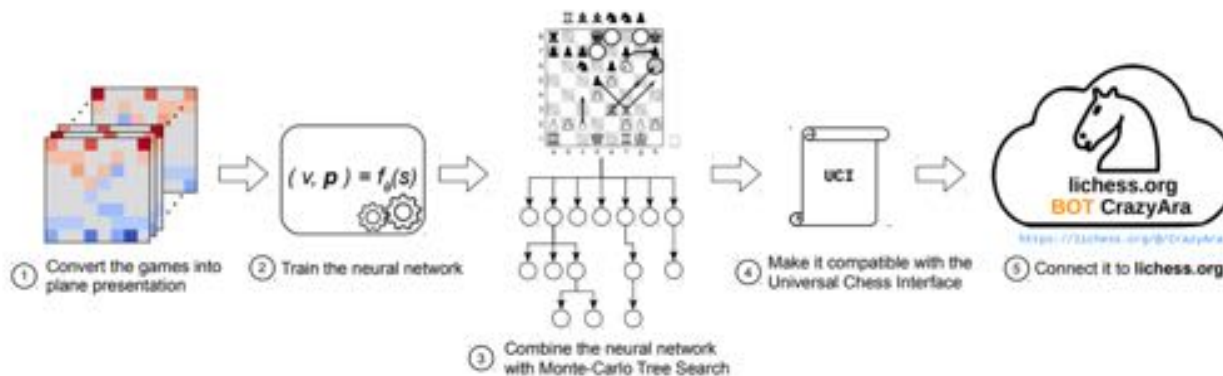


# Deep Neural Networks



Potentially much more powerful than shallow architectures, represent computations

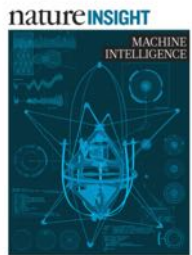
[LeCun, Bengio, Hinton Nature 521, 436–444, 2015]



**They can beat the world champion in CrazyHouse**

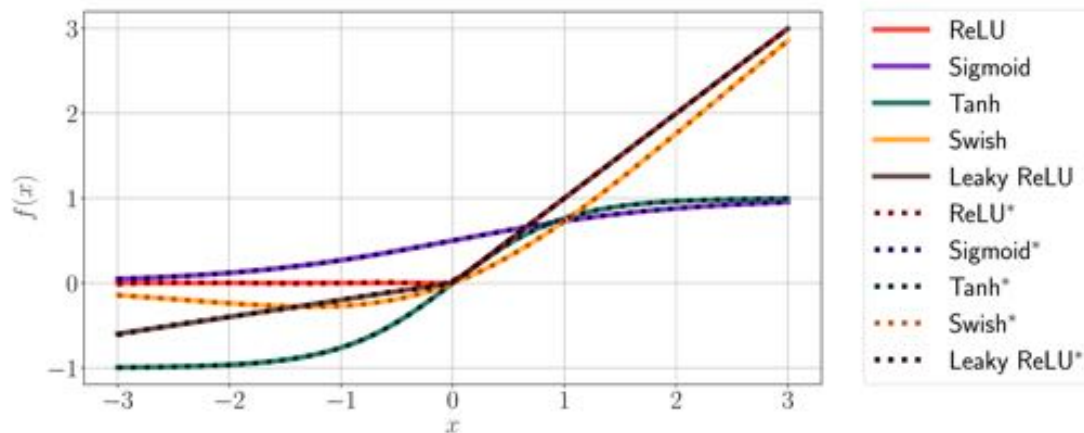
[Czech, Willig, Beyer, Kersting, Fürnkranz arXiv:1908.06660 2019.]

# Deep Neural Networks



Potentially much more powerful than shallow architectures, represent computations

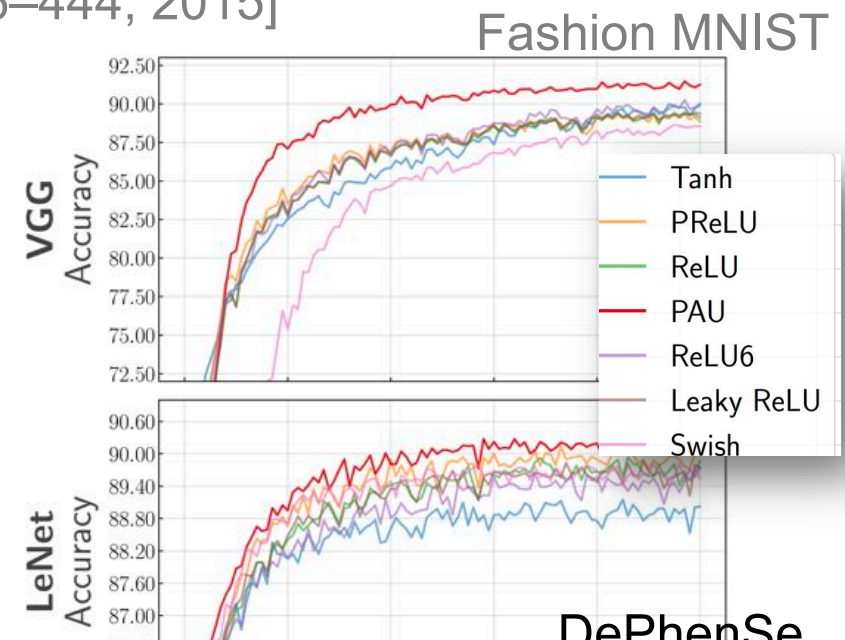
[LeCun, Bengio, Hinton Nature 521, 436–444, 2015]



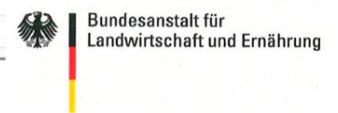
<https://github.com/ml-research/pau>

## Bias in activations! E2E-Learning Activations

[Molina, Schramowski, Kersting arxiv:1901.03704 2019]



DePhenSe

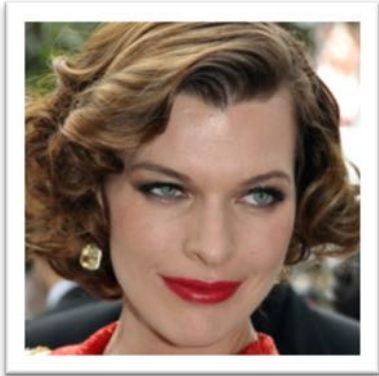


# **Your turn!**

**Deep neural learning = AI? Is it solving everything? Are there pitfalls? Can we trust deep neural networks?**

**You have 5 minutes!**

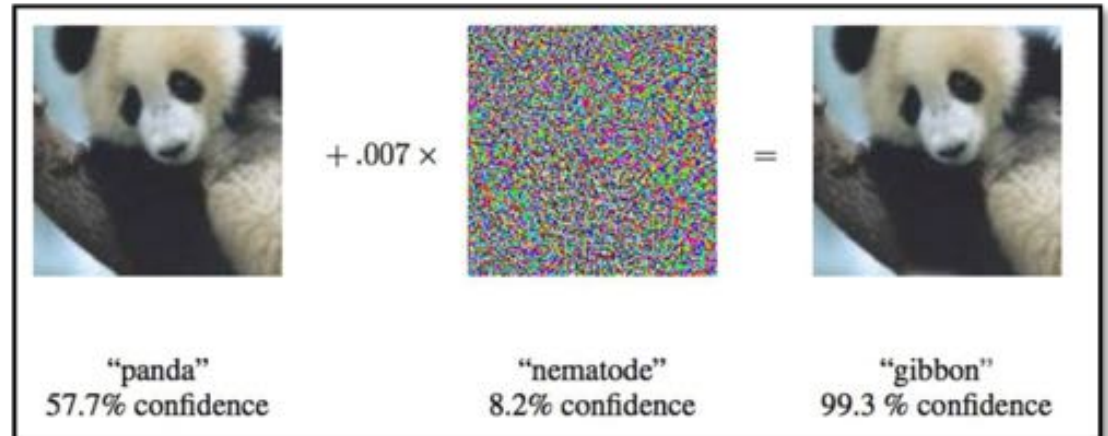
# They “capture” stereotypes and can be rather brittle



Sharif et al., 2015



Brown et al. (2017)



Google, 2015

REPORTS | PSYCHOLOGY

## Semantics derived automatically from language corpora contain human-like biases

Aylin Caliskan<sup>1,\*</sup>, Joanna J. Bryson<sup>1,2,\*</sup>, Arvind Narayanan<sup>1,\*</sup>

+ See all authors and affiliations

Science 14 Apr 2017;  
Vol. 356, Issue 6334, pp. 183-186  
DOI: 10.1126/science.aal4230



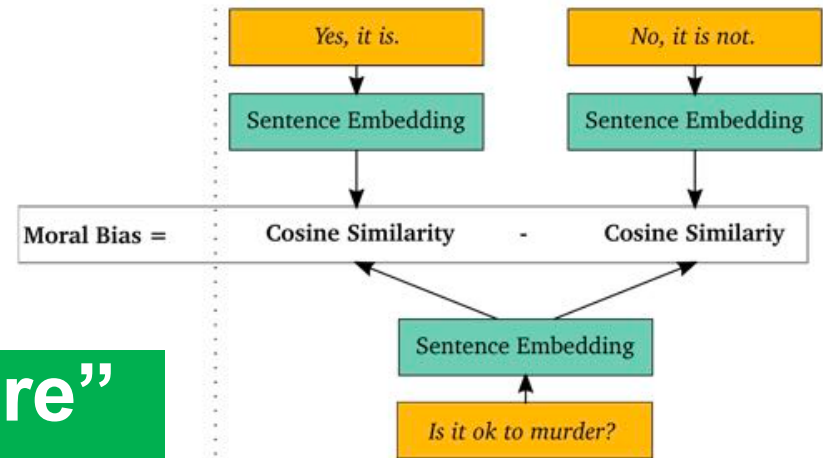


Video 05:10 Min.  
 Der Hamster gehört nicht in den Toaster – Wie Forscher von der TU Darmstadt versuchen, Maschinen ... [Videoseite]  
 hauptsache kultur | 14.03.19, 22:45 Uhr

# The Moral Choice Machine

Dos	WEAT	Bias	Don'ts	WEAT	Bias
smile	0.116	0.348	rot	-0.099	-1.118
sightsee	0.090	0.281	negative	-0.101	-0.763
cheer	0.094	0.277	harm	-0.110	-0.730
celebrate	0.114	0.264	damage	-0.105	-0.664
picnic	0.093	0.260	slander	-0.108	-0.600
snuggle	0.108	0.238	slur	-0.109	-0.569

**But lucky they also “capture” our moral choices**

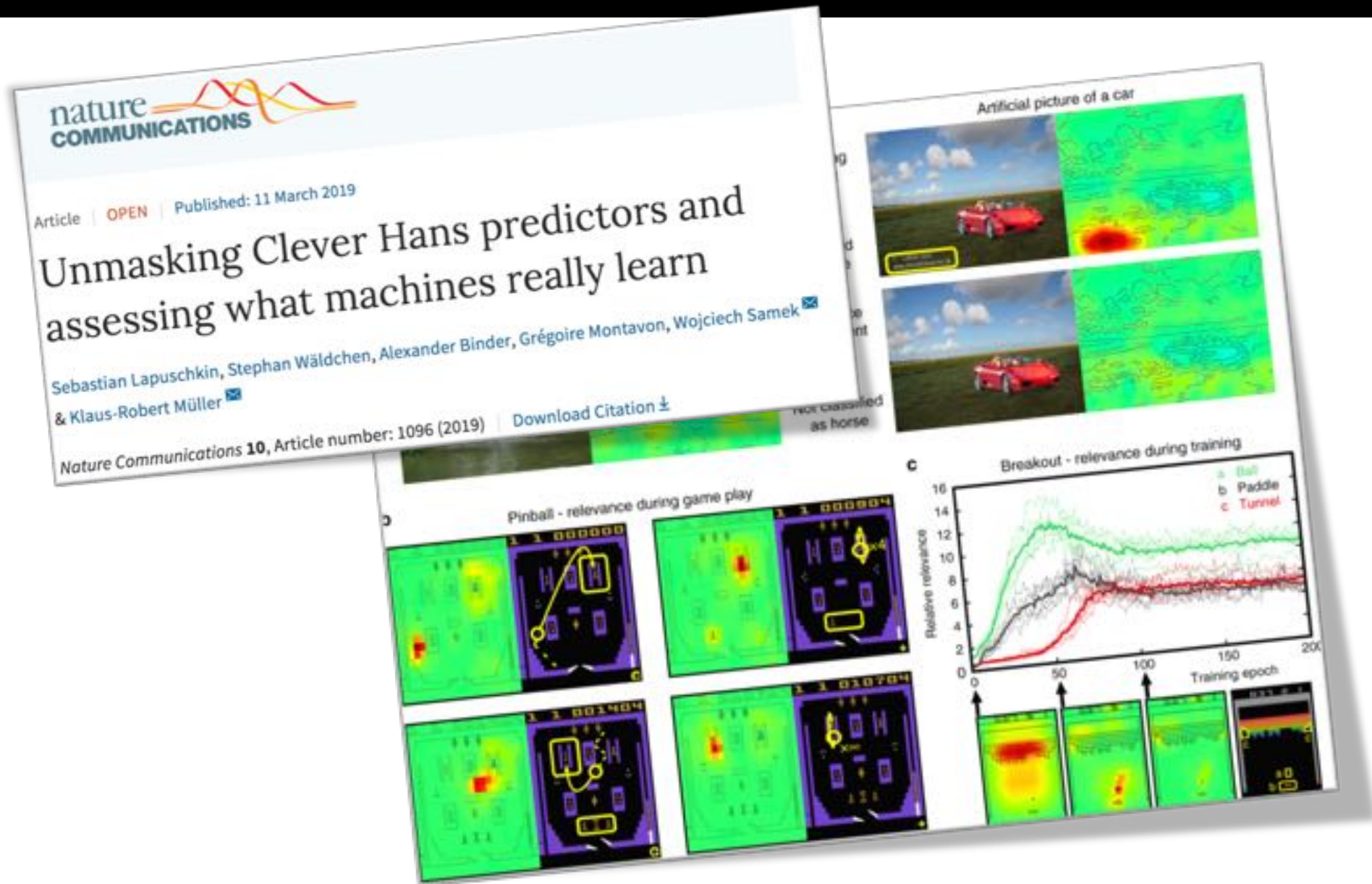


[Jentzsch, Schramowski, Rothkopf, Kersting AIES 2019]



AAAI / ACM conference on  
**ARTIFICIAL INTELLIGENCE,  
 ETHICS, AND SOCIETY**

# Can we trust deep neural networks?



**DNNs often have no probabilistic semantics. They are not calibrated joint distributions.**

$$P(Y|X) \neq P(Y,X)$$

**MNIST**



**Train & Evaluate**

**SVHN**

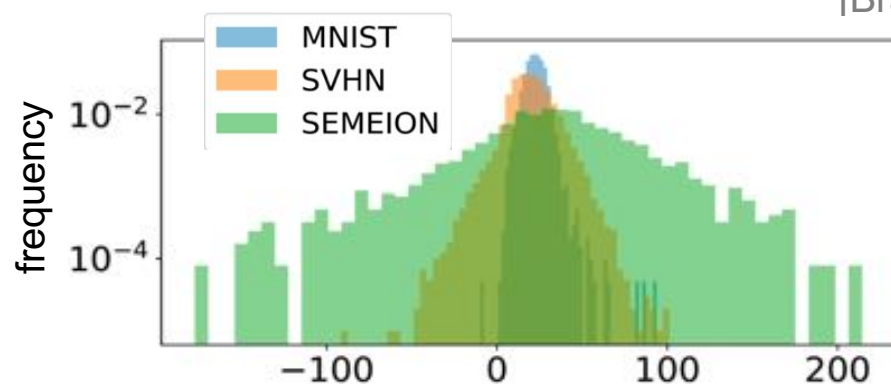


**Transfer Testing**

**SEMEION**



[Bradshaw et al. arXiv:1707.02476 2017]



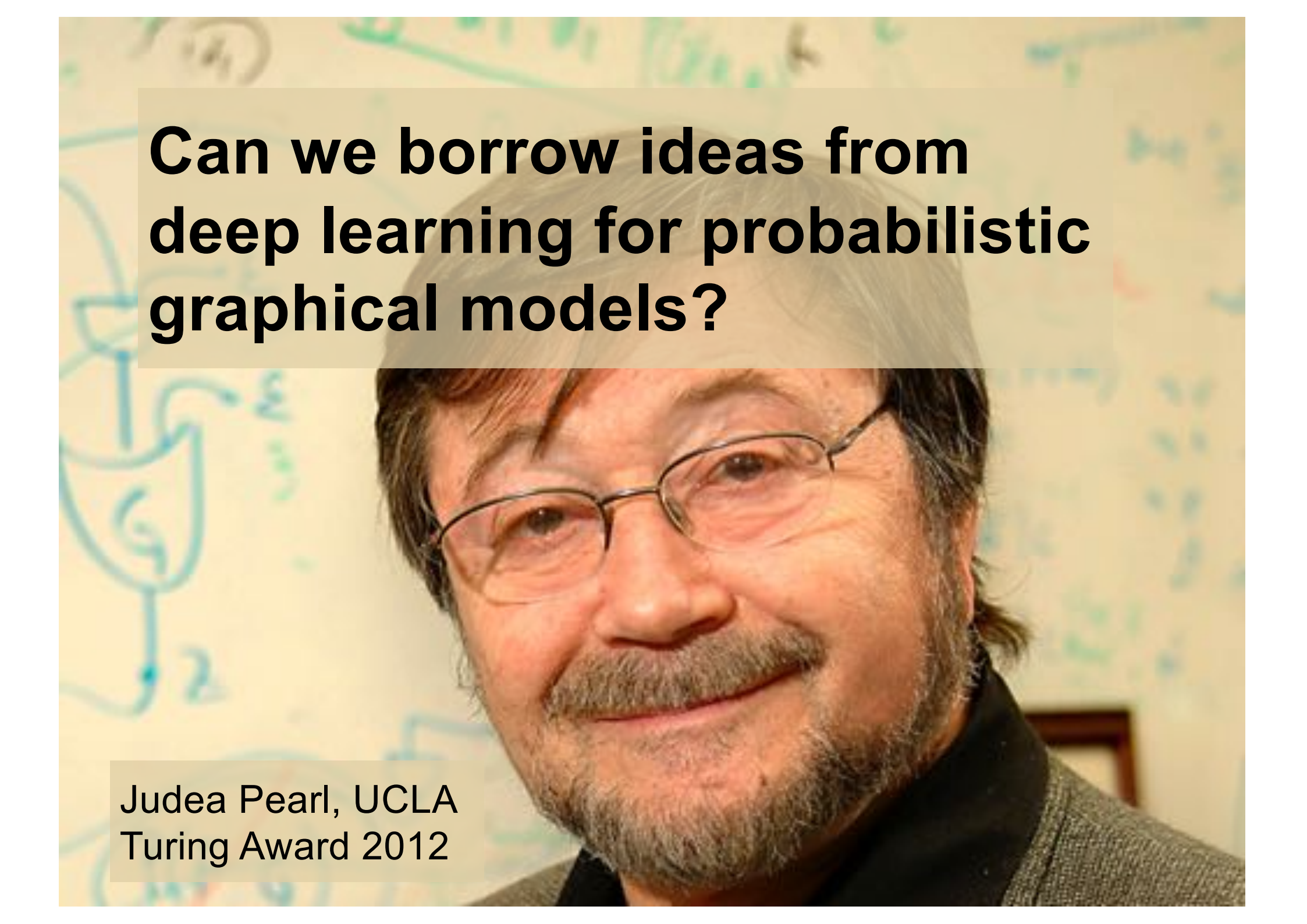
MLP

**Many DNNs cannot distinguish the datasets**

Input log „likelihood“ (sum over outputs)

[Peharz, Vergari, Molina, Stelzner, Trapp, Kersting, Ghahramani UAI 2019]



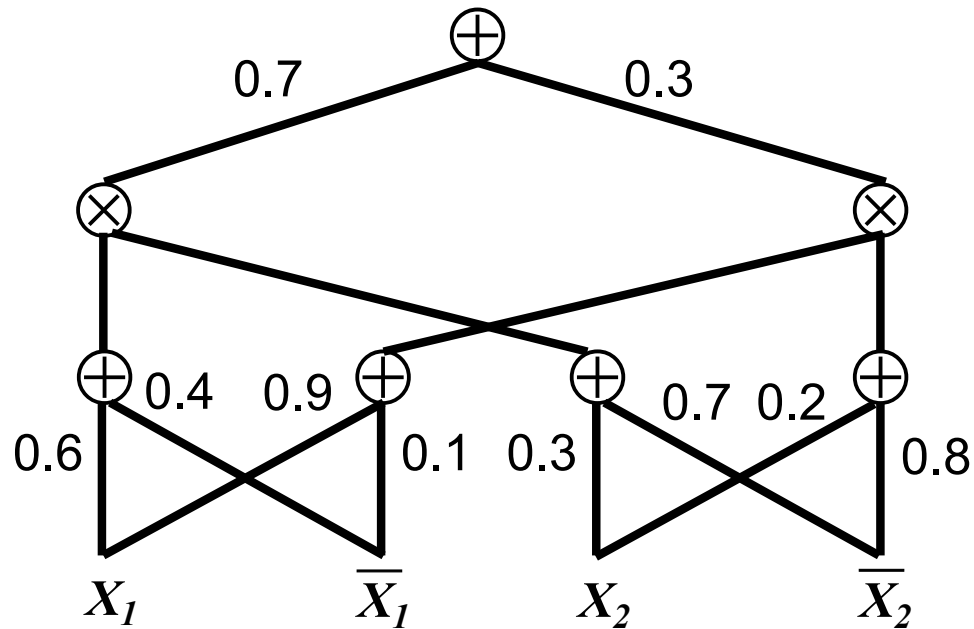
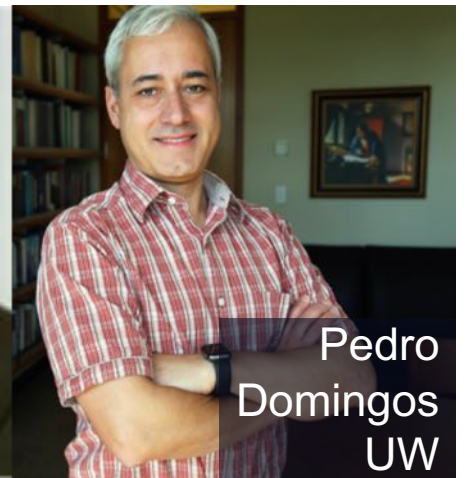


# Can we borrow ideas from deep learning for probabilistic graphical models?

Judea Pearl, UCLA  
Turing Award 2012

# Sum-Product Networks

a deep probabilistic learning framework



Computational graph  
(kind of TensorFlow  
graphs) that encodes  
how to compute  
probabilities

**Inference is linear in size of network**

# Alternative Representation: Graphical Models as (Deep) Networks

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

$$\begin{aligned} P(X) = & 0.4 \cdot I[X_1=1] \cdot I[X_2=1] \\ & + 0.2 \cdot I[X_1=1] \cdot I[X_2=0] \\ & + 0.1 \cdot I[X_1=0] \cdot I[X_2=1] \\ & + 0.3 \cdot I[X_1=0] \cdot I[X_2=0] \end{aligned}$$

# Alternative Representation: Graphical Models as (Deep) Networks

$X_1$	$X_2$	$P(X)$
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# Shorthand using Indicators

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

$$\begin{aligned} P(X) = & 0.4 \cdot X_1 \cdot X_2 \\ & + 0.2 \cdot X_1 \cdot \bar{X}_2 \\ & + 0.1 \cdot \bar{X}_1 \cdot X_2 \\ & + 0.3 \cdot \bar{X}_1 \cdot \bar{X}_2 \end{aligned}$$

# Summing Out Variables

Let us say, we want to compute  $P(X_1 = 1)$

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

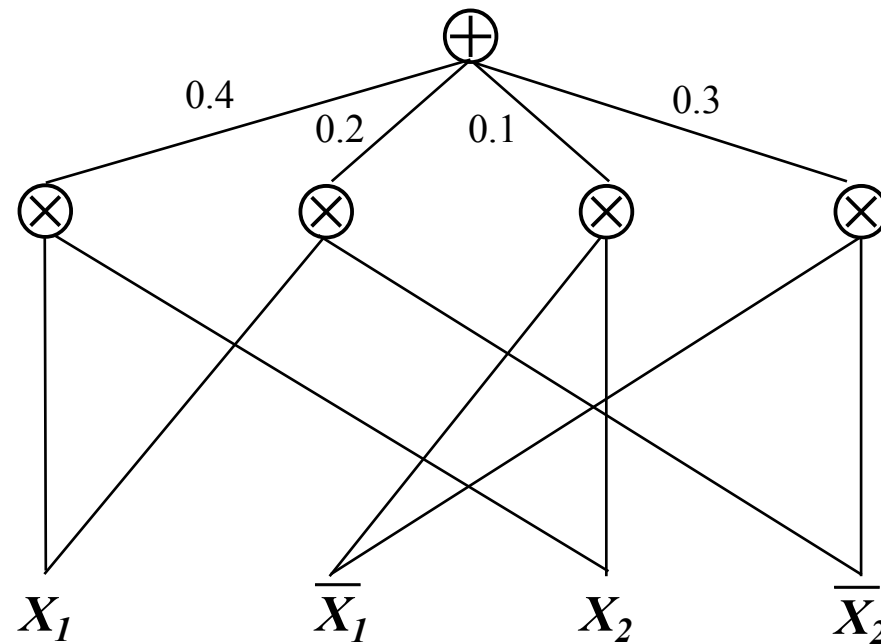
$$\begin{aligned}P(e) = & \mathbf{0.4} \cdot X_1 \cdot X_2 \\ & + \mathbf{0.2} \cdot X_1 \cdot \bar{X}_2 \\ & + 0.1 \cdot \bar{X}_1 \cdot X_2 \\ & + 0.3 \cdot \bar{X}_1 \cdot \bar{X}_2\end{aligned}$$

Set  $X_1 = 1, \bar{X}_1 = 0, X_2 = 1, \bar{X}_2 = 1$

Easy: Set both indicators of  $X_2$  to 1

**This can be represented as a computational graph**

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

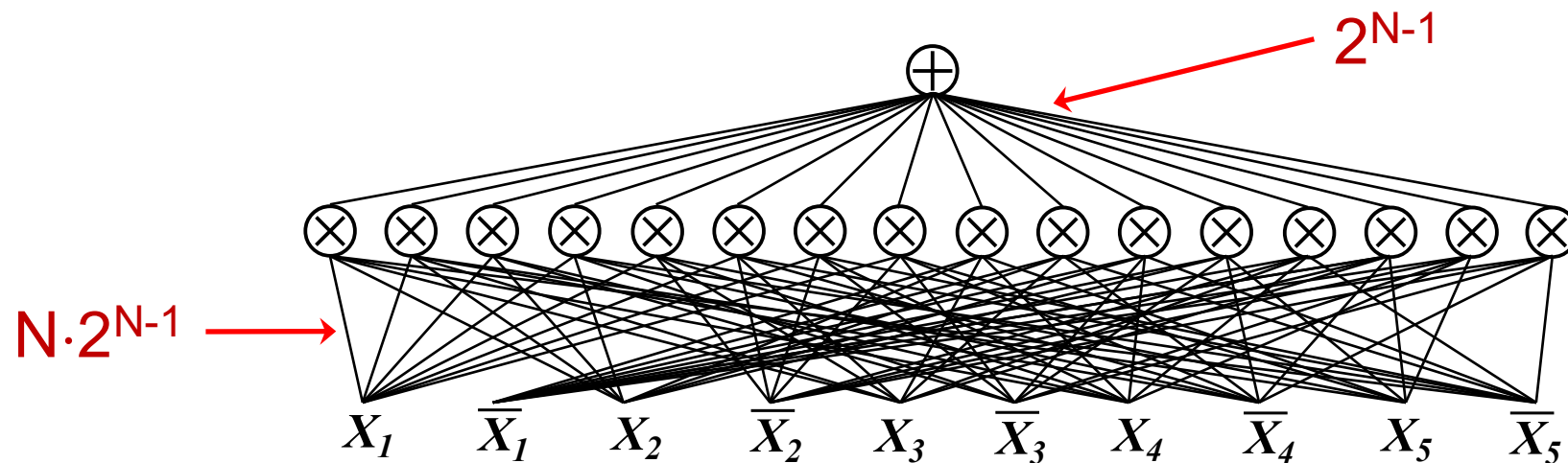


network polynomial

However, the network polynomial of a distribution might be exponentially large

### Example: Parity

Uniform distribution over states with even number of 1's

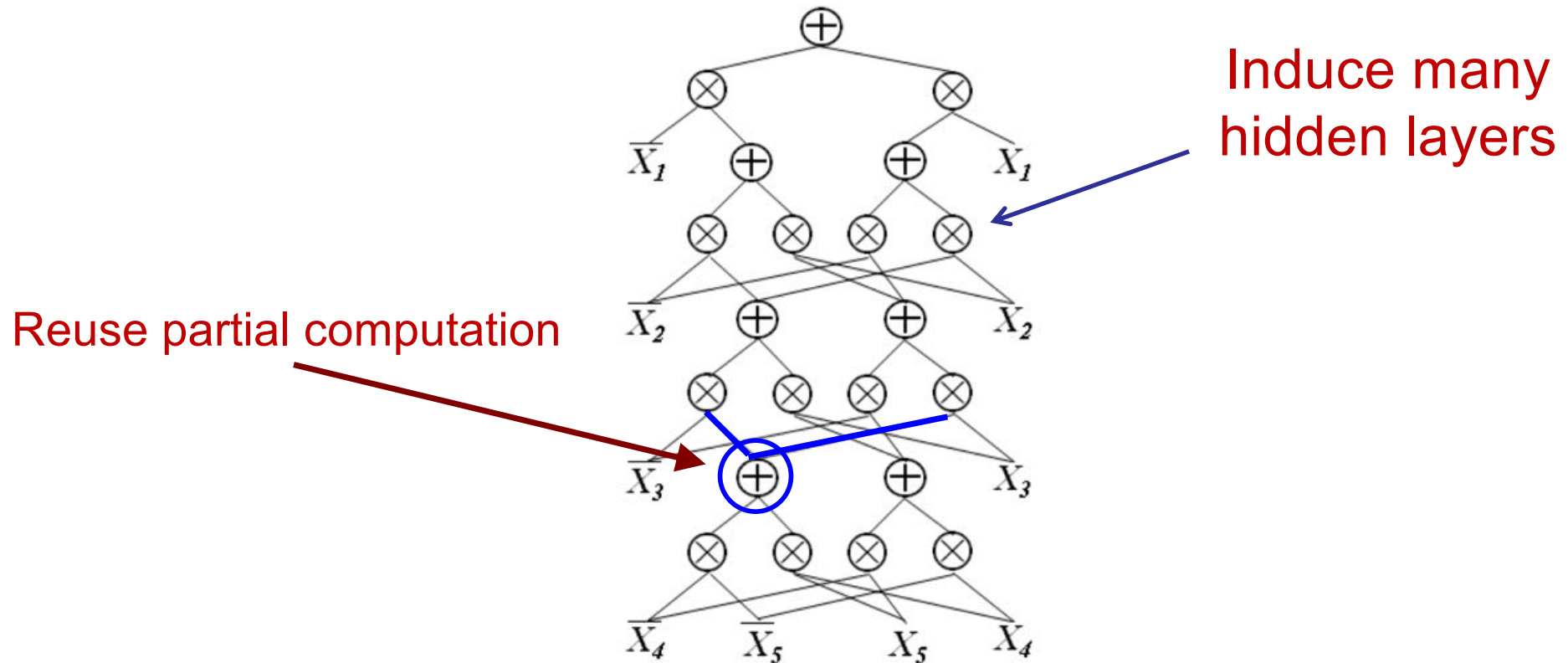




# Make the computational graphs deep

## Example: Parity

Uniform distribution over states with even number of 1's



# Alternative Representation: Graphical Models as Deep Networks

$X_1$	$X_2$	$P(X)$
1	1	0.4
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# Alternative Representation: Graphical Models as Deep Networks

$X_1$	$X_2$	$P(X)$
<b>1</b>	<b>1</b>	<b>0.4</b>
1	0	0.2
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# Shorthand for Indicators

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

$$\begin{aligned} P(X) = & 0.4 \cdot X_1 \cdot X_2 \\ & + 0.2 \cdot X_1 \cdot \bar{X}_2 \\ & + 0.1 \cdot \bar{X}_1 \cdot X_2 \\ & + 0.3 \cdot \bar{X}_1 \cdot \bar{X}_2 \end{aligned}$$

# Sum Out Variables

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3

$$e: X_1 = 1$$

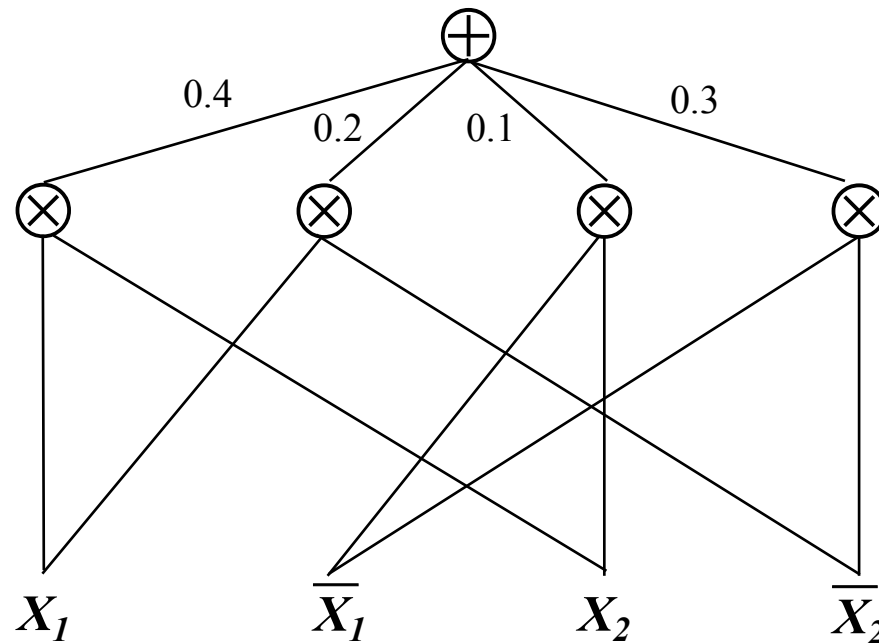
$$\begin{aligned} P(e) = & \mathbf{0.4} \cdot X_1 \cdot X_2 \\ & + \mathbf{0.2} \cdot X_1 \cdot \bar{X}_2 \\ & + 0.1 \cdot \bar{X}_1 \cdot X_2 \\ & + 0.3 \cdot \bar{X}_1 \cdot \bar{X}_2 \end{aligned}$$

$$\text{Set } X_1 = 1, \bar{X}_1 = 0, \mathbf{X_2 = 1, \bar{X}_2 = 1}$$

Easy: Set both indicators of  $X_2$  to 1

# Idea: Deeper Network Representation of a Graphical Model that encodes how to compute probabilities

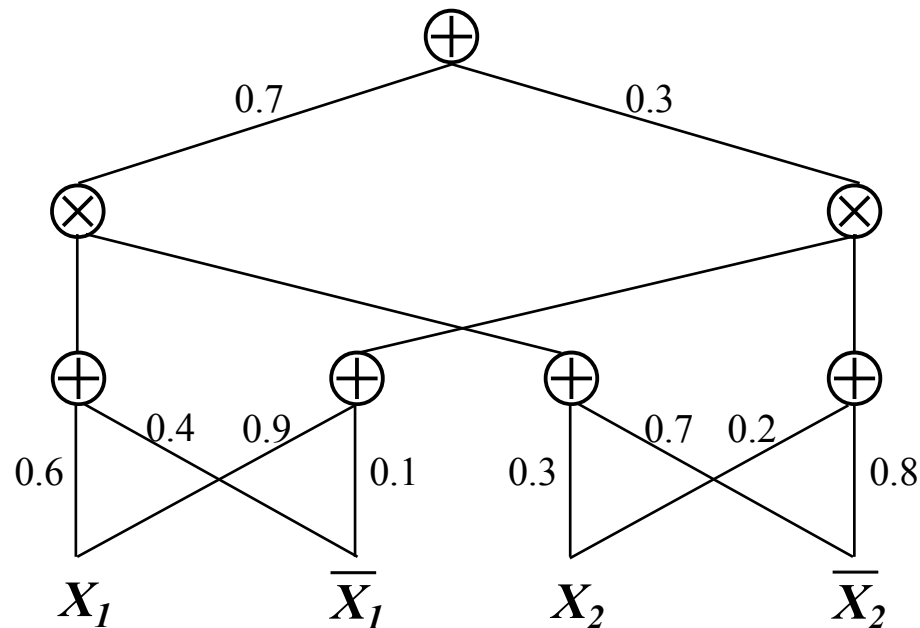
$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3



# Sum-Product Networks\* (SPNs)

[Poon, Domingos UAI 2011]

A SPN  $S$  is a rooted DAG where:  
Nodes: Sum, product, input indicator  
Weights on edges from sum to children



\*SPNs are an instance of Arithmetic Circuits (ACs). ACs have been introduced into the AI literature more than 15 years ago as a tractable representation of probability distributions

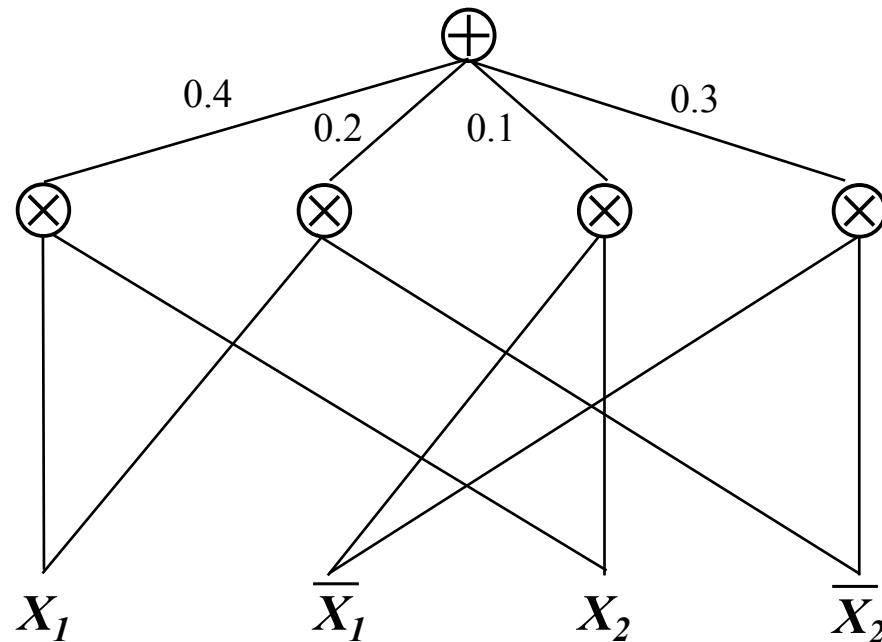
[Darwiche CACM 48(4):608-647 2001]

# Your turn!

$$P(x|y) = \frac{P(x,y)}{P(y)}$$

## What is $P(X_2)$ ? What is $P(X_1|X_2=1)$ ?

$X_1$	$X_2$	$P(X)$
1	1	0.4
1	0	0.2
0	1	0.1
0	0	0.3



# You have 10 minutes!



[Poon, Domingos UAI'11; Molina, Natarajan, Kersting AAAI'17; Vergari, Peharz, Di Mauro, Molina, Kersting, Esposito AAAI '18; Molina, Vergari, Di Mauro, Esposito, Natarajan, Kersting AAAI '18]

# FL ⊕ W for SPFlow: An Easy and Extensible Library for Sum-Product Networks

[Molina, Vergari, Stelzner, Peharz, Subramani, Poupart, Di Mauro, Kersting 2019]



<https://github.com/SPFlow/SPFlow>

```
from spn.structure.leaves.parametric.Parametric import Categorical
from spn.structure.Base import Sum, Product
from spn.structure.base import assign_ids, rebuild_scopes_bottom_up

p0 = Product(children=[Categorical(p=[0.3, 0.7], scope=1), Categorical(p=[0.4, 0.6], scope=2)])
p1 = Product(children=[Categorical(p=[0.5, 0.5], scope=1), Categorical(p=[0.6, 0.4], scope=2)])
s1 = Sum(weights=[0.3, 0.7], children=[p0, p1])
p2 = Product(children=[Categorical(p=[0.2, 0.8], scope=0), s1])
p3 = Product(children=[Categorical(p=[0.2, 0.8], scope=0), Categorical(p=[0.3, 0.7], scope=1)])
p4 = Product(children=[p3, Categorical(p=[0.4, 0.6], scope=2)])
spn = Sum(weights=[0.4, 0.6], children=[p2, p4])

assign_ids(spn)
rebuild_scopes_bottom_up(spn)




return spn
```

**Domain Specific Language,  
Inference, EM, and Model  
Selection as well as  
Compilation of SPNs into TF  
and PyTorch and also into flat,  
library-free code even suitable  
for running on devices:  
C/C++, GPU, FPGA**

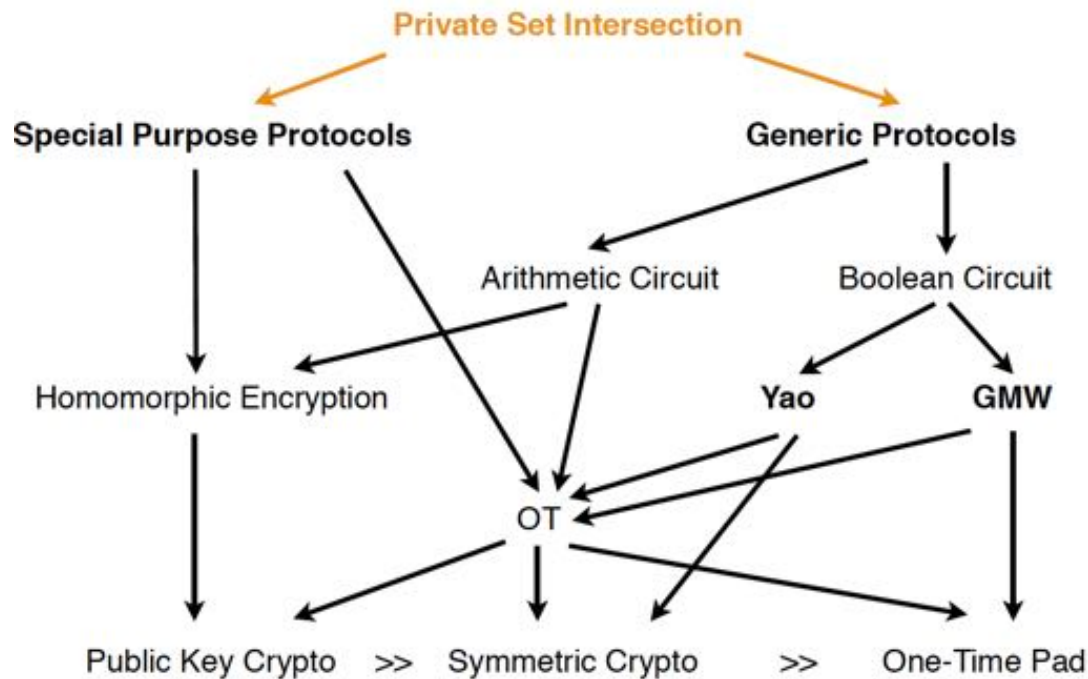
SPFlow, an open-source Python library providing a simple interface to inference, learning and manipulation routines for deep and tractable probabilistic models called Sum-Product Networks (SPNs). The library allows one to quickly create SPNs both from data and through a domain specific language (DSL). It efficiently implements several probabilistic inference routines like computing marginals, conditionals and (approximate) most probable explanations (MPEs) along with compilation

TABLE II

PERFORMANCE COMPARISON. BEST END-TO-END THROUGHPUTS (T), EXCLUDING THE CYCLE COUNTER MEASUREMENTS, ARE DENOTED BOLD.

Dataset	Rows	CPU ( $\mu$ s)	T-CPU (rows/ $\mu$ s)	CPUF ( $\mu$ s)	T-CPUF (rows/ $\mu$ s)	GPU ( $\mu$ s)	T-GPU (rows/ $\mu$ s)	FPGA Cycle Counter	FPGAC ( $\mu$ s)	T-FPGAC (rows/ $\mu$ s)	FPGA ( $\mu$ s)	T-FPGA (rows/ $\mu$ s)
Accidents	17009	2798.27			7.87	63090.94	0.27	17249			696.00	<b>24.44</b>
Audio	20000	4271.78			5.4			20317			761.00	<b>26.28</b>
Netflix	20000	4892.22			4.8			20322			654.00	<b>30.58</b>
MSNBC200	388434	15476.05			30.5			388900	19		008.00	<b>77.56</b>
MSNBC300	388434	10060.78			41.2			388810	19		933.00	<b>78.74</b>
NLCS	21574	791.80			31.3			21904	1		566.00	<b>38.12</b>
Plants	23215	3621.71	6.41	3521.04	6.59	67004.41	0.35	23592	117.96	196.80	778.00	<b>29.84</b>
NIPS5	10000	25.11	<b>398.31</b>	26.37	379.23	8210.32	1.22	10236	51.18	195.39	337.30	29.65
NIPS10	10000	83.60	<b>119.61</b>	84.39	118.49	11550.82	0.87	10279	51.40	194.57	464.30	21.54
NIPS20	10000	191.30	52.27	182.73	<b>54.72</b>	18689.04	0.54	10285	51.43	194.46	543.60	18.40
NIPS30	10000	387.61	25.80	349.84	<b>28.58</b>	25355.93	0.39	10308	51.80	193.06	592.30	16.88
NIPS40	10000	551.64	18.13	471.26	<b>21.22</b>	30820.49	0.32	10306	51.53	194.06	632.20	15.82
NIPS50	10000	812.44	12.31	792.13	12.62	36355.60	0.28	10559	52.80	189.41	720.60	<b>13.88</b>
NIPS60	10000	1046.38	9.56	662.53	<b>15.09</b>	40778.36	0.25	12271	61.36	162.99	799.20	12.51
NIPS70	10000	1148.17	8.71	1134.80	8.81	46759.26	0.21	14022	70.11	142.63	858.60	<b>11.65</b>
NIPS80	10000	1556.99	6.42	1277.81	7.83	63217.99	0.16	14275	78.51	127.37	961.80	<b>10.40</b>

# How do we do deep learning offshore?



There are generic protocols to validate computations on authenticated data without knowledge of the secret key

#### DNA MSPN ####

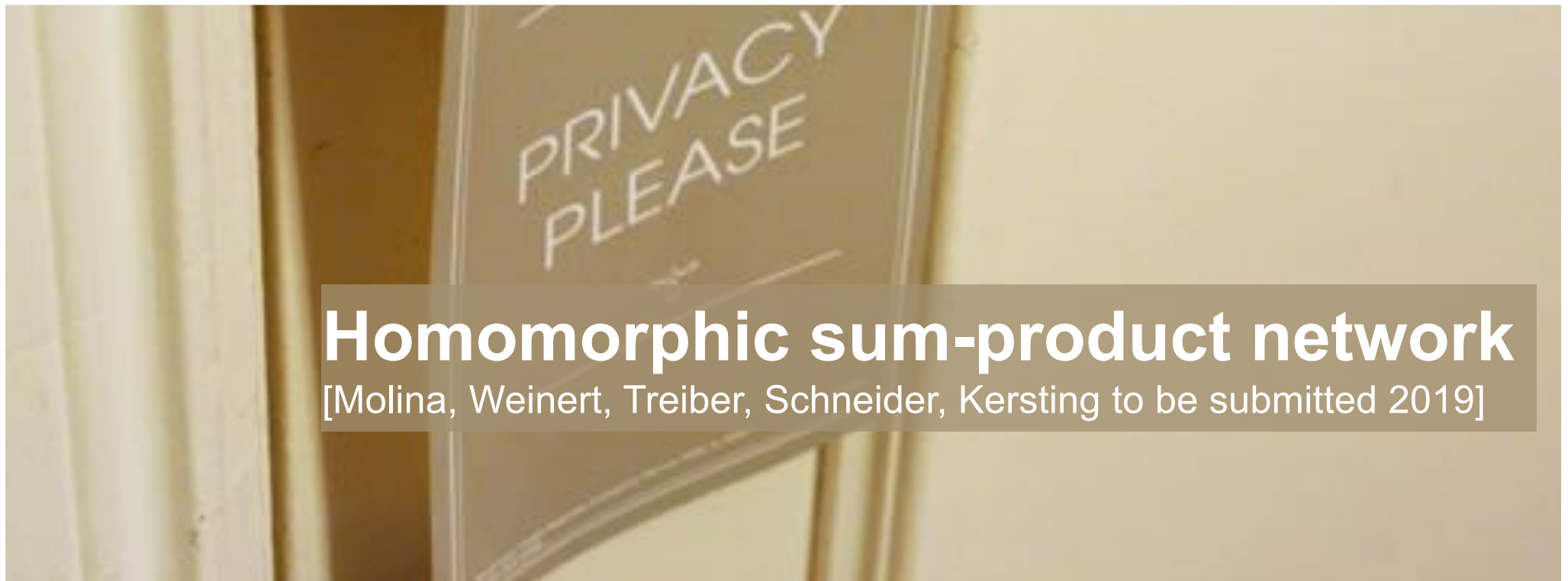
Gates: 298208 Yao Bytes: 9542656 Depth: 615

#### DNA PSPN ####

Gates: 228272 Yao Bytes: 7304704 Depth: 589

#### NIPS MSPN ####

Gates: 1001477 Yao Bytes: 32047264 Depth: 970



# Homomorphic sum-product network

[Molina, Weinert, Treiber, Schneider, Kersting to be submitted 2019]

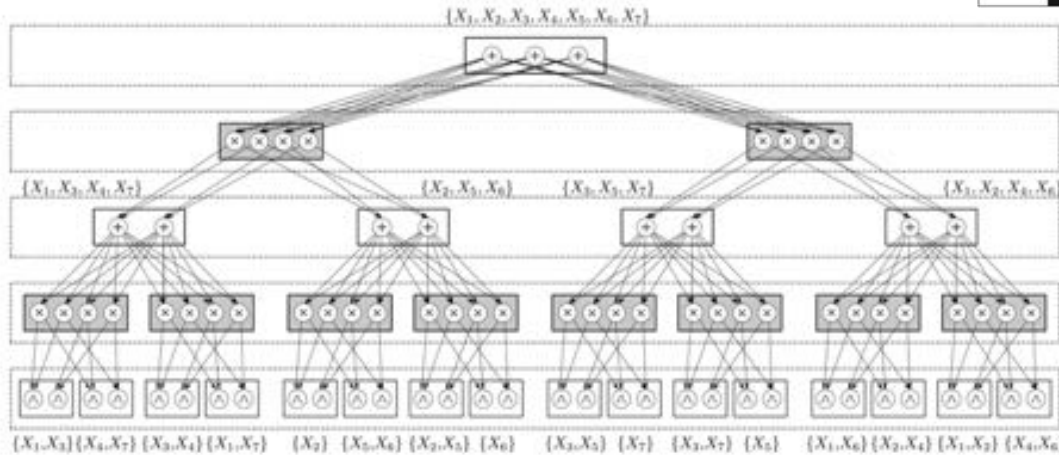
# Random sum-product networks

[Peharz, Vergari, Molina, Stelzner, Trapp, Kersting, Ghahramani UAI 2019]



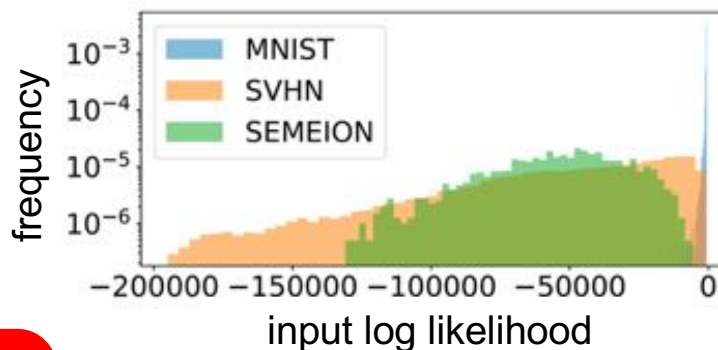
Conference on Uncertainty in Artificial Intelligence  
Tel Aviv, Israel  
July 22 - 25, 2019

uai2019



Build a random SPN structure. This can be done in an informed way or completely at random

	RAT-SPN	MLP	vMLP	
Accuracy	MNIST	98.19 (8.5M)	98.32 (2.64M)	98.09 (5.28M)
	F-MNIST	89.52 (0.65M)	90.81 (9.28M)	89.81 (1.07M)
	20-NG	47.8 (0.37M)	49.05 (0.31M)	48.81 (0.16M)
Cross-Entropy	MNIST	0.0852 (17M)	0.0874 (0.82M)	0.0974 (0.22M)
	F-MNIST	0.3525 (0.65M)	0.2965 (0.82M)	0.325 (0.29M)
	20-NG	1.6954 (1.63M)	1.6180 (0.22M)	1.6263 (0.22M)



SPNs can have similar predictive performances as (simple) DNNs

SPNs can distinguish the datasets

SPNs know when they do not know by design

# **Your turn!**

**Mission completed? Just give me  
data and everything is done by  
ML/AI?**

**You have 5 minutes!**

# Reproducibility Crisis in Science (2016)



M. Baker: „1,500 scientists lift the lid on reproducibility“. Nature, 2016 May 26;533(7604):452-4. doi: 10.1038/533452  
<https://www.nature.com/news/1-500-scientists-lift-the-lid-on-reproducibility-1.19970?proof=true>

The New York Times



Opinion

# A.I. Is Harder Than You Think

**By Gary Marcus and Ernest Davis**

Mr. Marcus is a professor of psychology and neural science. Mr. Davis is a professor of computer science.

May 18, 2018

# Reproducibility Crisis in ML & AI (2018)

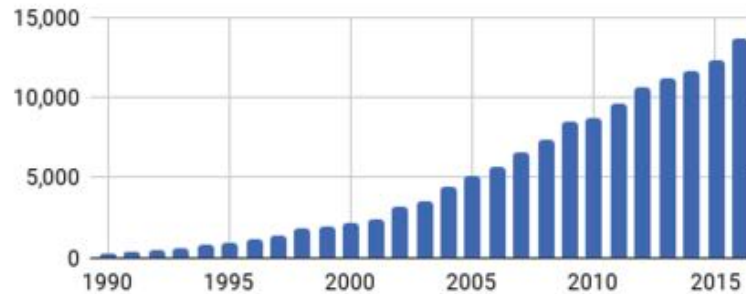


Figure 1: Growth of published reinforcement learning papers. Shown are the number of RL-related publications (y-axis) per year (x-axis) scraped from Google Scholar searches.



**Joelle Pineau**

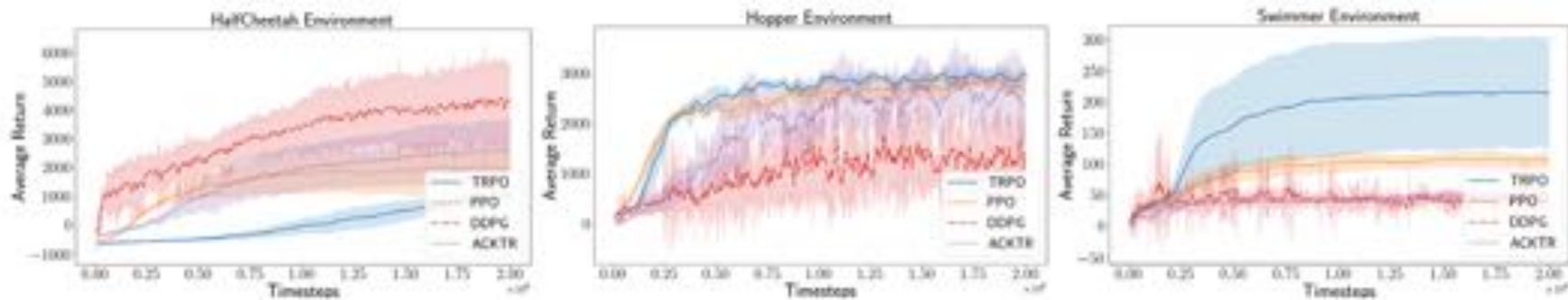
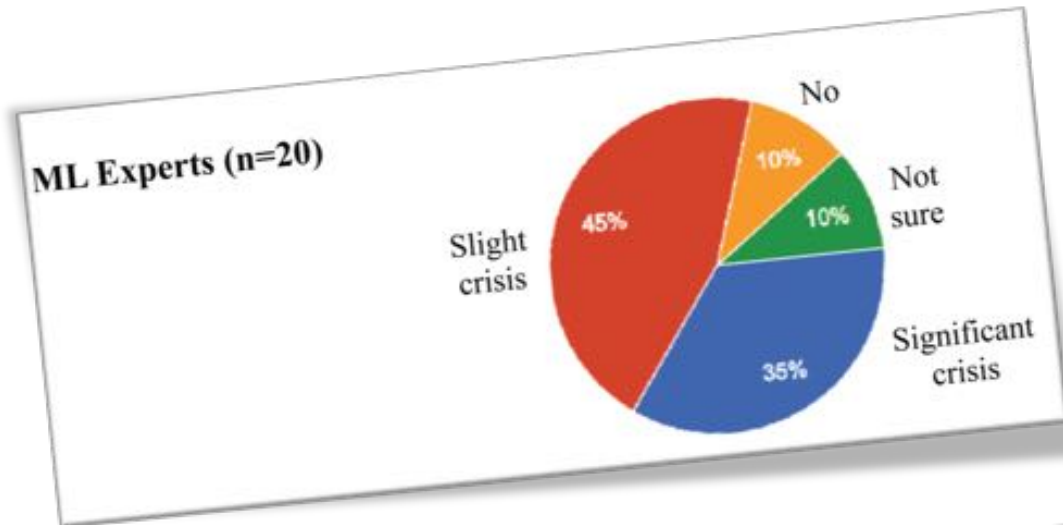


Figure 4: Performance of several policy gradient algorithms across benchmark MuJoCo environment suites



# Reproducibility Crisis in ML & AI (2018)

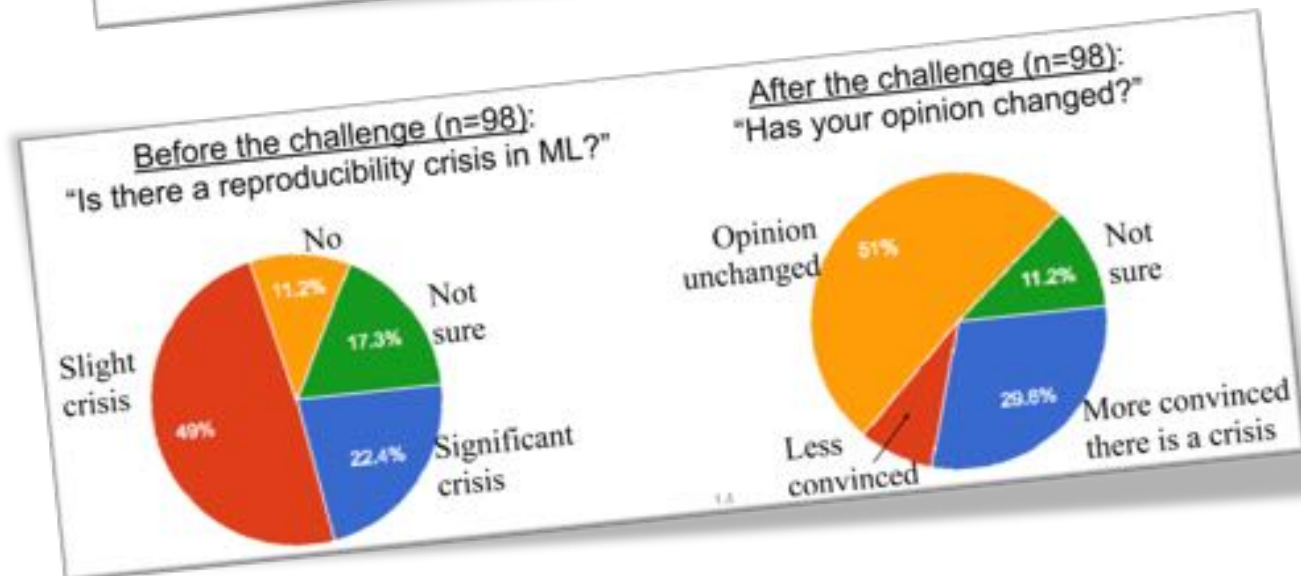


**Joelle Pineau**



Survey participants:

- 54 challenge participants
- 30 authors of ICLR submissions targeted by reproducibility effort
- 14 others (random volunteers, other ICLR authors, ICLR area chair & reviewers, course instructors)



J. Pineau: „The ICLR 2018 Reproducibility Challenge“.  
Talk at the MLTRAIN@RML Workshop at ICML 2018



Nikolaos Vasiloglou



## NIPS HIGHLIGHTS, LEARN HOW TO CODE A PAPER WITH STATE OF THE ART FRAMEWORKS

Dec 09 @ 08:50 AM - 06:05 PM NIPS, Los Angeles, California

## ENABLING REPRODUCIBILITY IN MACHINE LEARNING MLTRAIN@RML (ICML 2018)

Jul 14 @ 08:30 AM - 06:00 PM Stockholmsmässan



Yoshua Bengio (Turing Award 2019)



**frontiers**  
in Big Data

Machine Learning and Artificial Intelligence

First Machine Learning and Artificial Intelligence journal that explicitly welcomes replication studies and code review papers

Srirraam Natarajan



# A lot of systems to support reproducible ML research



Machine learning, better, together



Joaquin Vanschoren



20328  
data sets

Find or add data to analyse

68724  
tasks

Download or create scientific tasks

6994  
flows

Find or add data analysis flows

9749541  
runs

Upload and explore all results online.



Percy Lang



# CodaLab

Accelerating reproducible computational research.

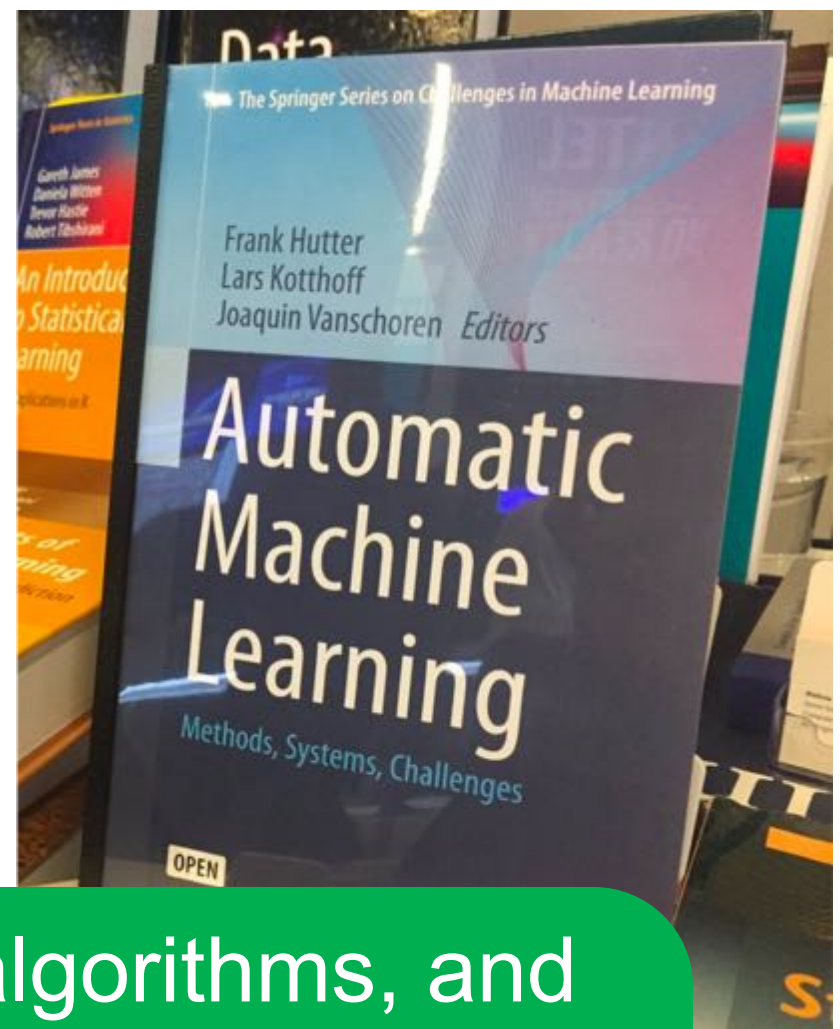
Worksheets

Run reproducible experiments and create executable papers using worksheets.

Competitions

Enter an existing competition to solve challenging data problems, or host your own.

However, there are not enough data scientists, statisticians, machine learning and AI experts

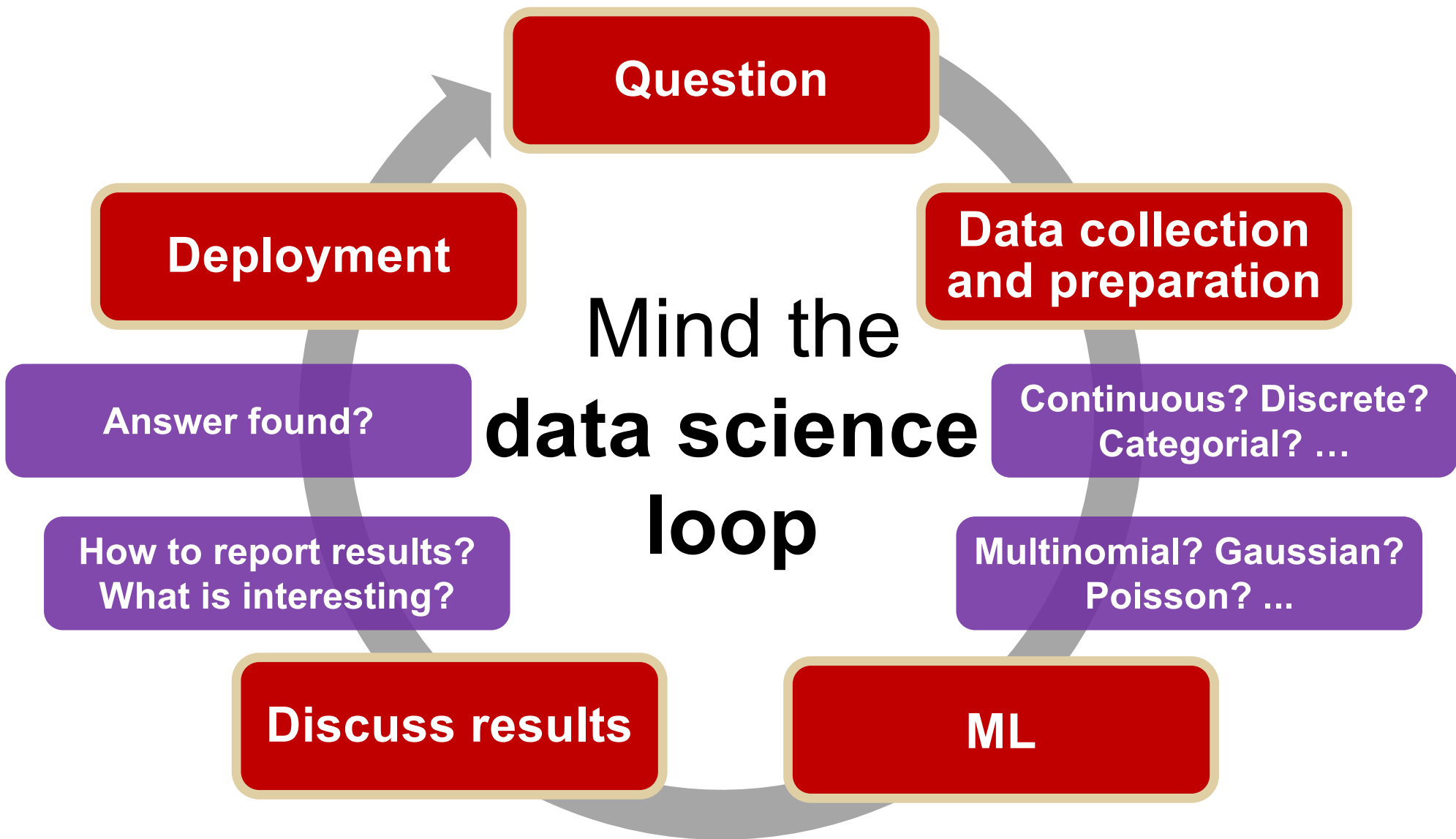


Provide the foundations, algorithms, and tools to develop systems that ease and support building ML/AI models as much as possible and in turn help reproducing and hopefully even justifying our results

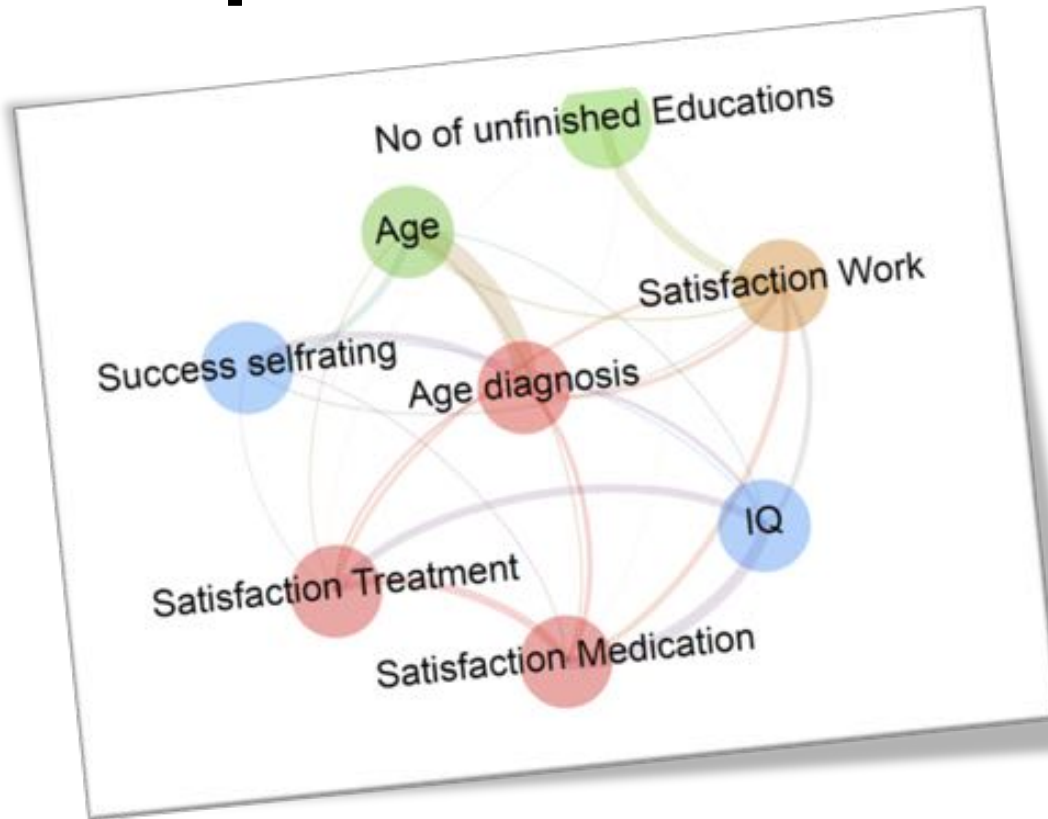
# **Your turn!**

**Do you think AutoML is solving everything?**

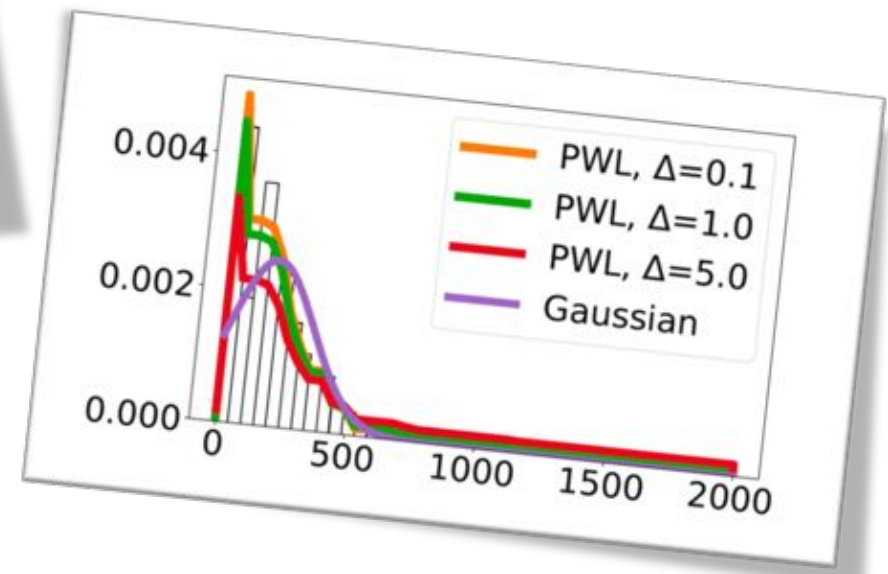
**You have 5 minutes!**



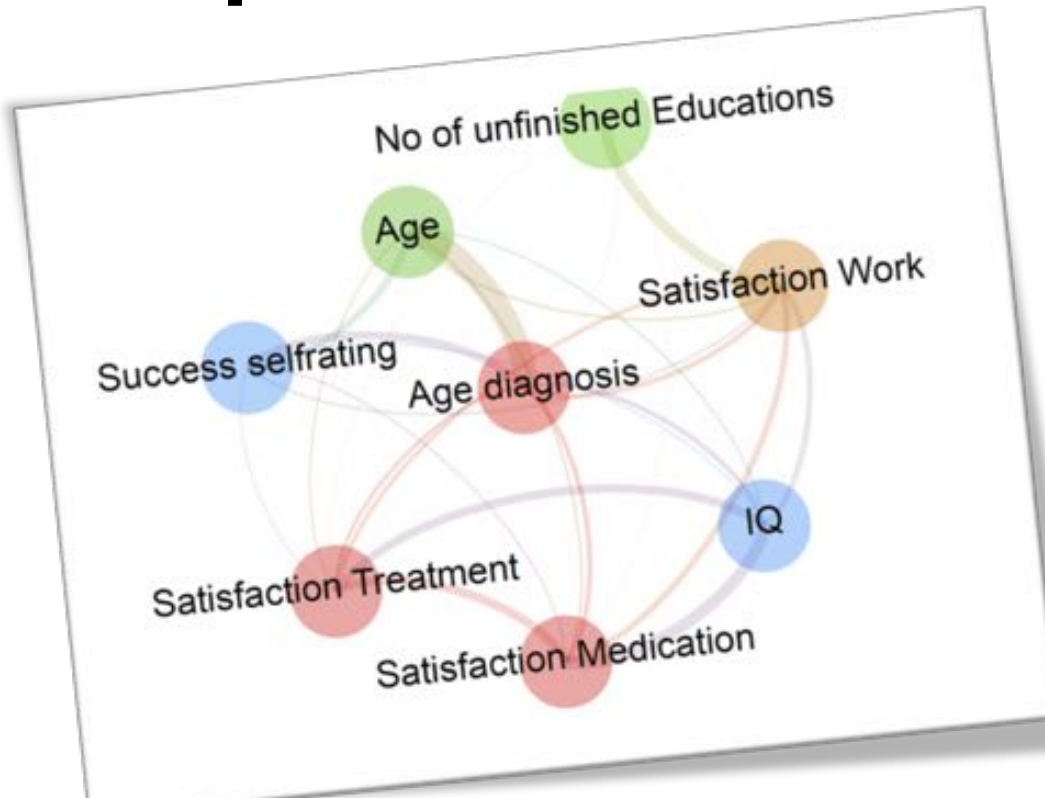
# Distribution-agnostic Deep Probabilistic Learning



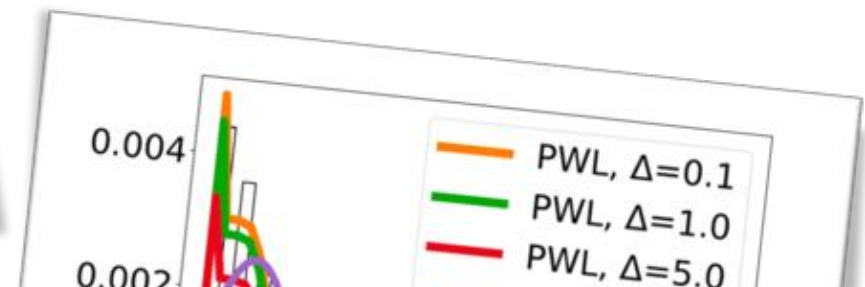
**Use nonparametric  
independency tests  
and piece-wise linear  
approximations**



# Distribution-agnostic Deep Probabilistic Learning



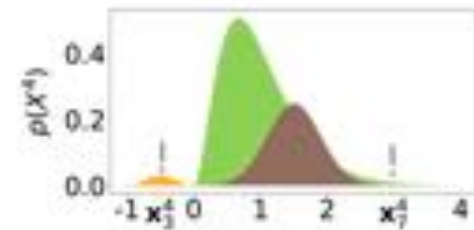
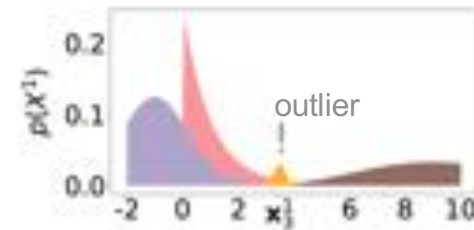
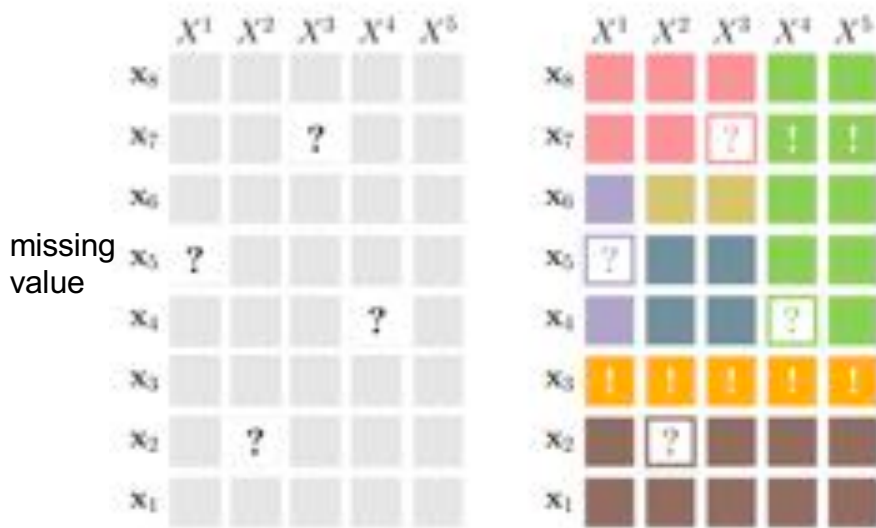
**Use nonparametric  
independency tests  
and piece-wise linear  
approximations**



However, we have to provide the statistical types and do not gain insights into the parametric forms of the variables.  
**Are they Gaussians? Gammas? ...**

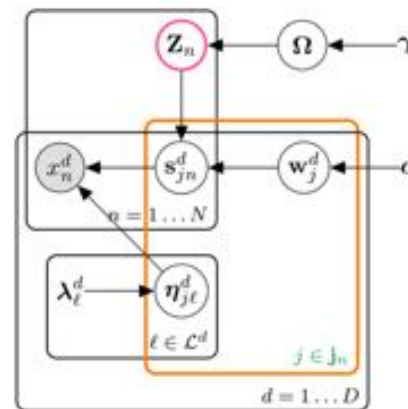


# The Automatic Data Scientist

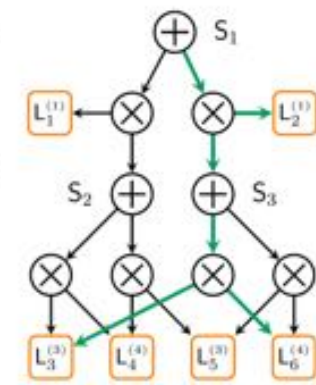


- Exponential (Exp): 25.00%
  - Gaussian ( $\mathcal{N}$ ): 37.50%
  - Gamma ( $\Gamma$ ): 25.00%
  - Gaussian ( $\mathcal{N}$ ): 12.50%
- 
- Gamma ( $\Gamma$ ): 62.50%
  - Gaussian ( $\mathcal{N}$ ): 12.50%
  - Gamma ( $\Gamma$ ): 25.00%

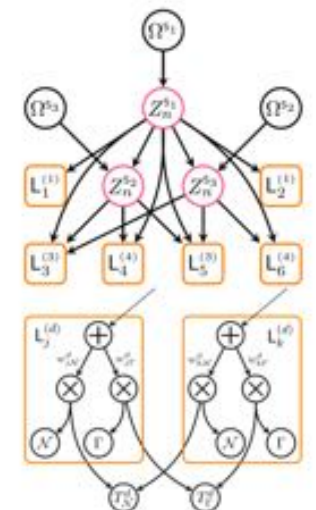
We can even automatically discover the statistical types and parametric forms of the variables



Bayesian Type Discovery



Mixed Sum-Product Network



Automatic Statistician

That is, the machine understands the data with few expert input ...

[Voelcker, Molina, Neumann, Westermann, Kersting ADS 2019]


Toggle Introduction    Toggle explanations    Toggle Code

### Exploring the Titanic dataset

This report describes the dataset Titanic and contains general statistical information and an analysis on the influence different features and subgroups of the data have on each other. The first part of the report contains general statistical information about the dataset and an analysis of the variables and probability distributions. The second part focusses on a subgroup analysis of the data. Different clusters identified by the network are analyzed and compared to give an insight into the structure of the data. Finally the influence different variables have on the predictive capabilities of the model are analyzes.

The whole report is generated by fitting a sum product network to the data and extracting all information from this model.

**ECMLPKDD WORKSHOP  
ON AUTOMATING DATA  
SCIENCE (ADS)**  
Würzburg, Germany, Friday 20 September 2019

 TECHNISCHE  
UNIVERSITÄT  
DARMSTADT  
Report framework created @ TU Darmstadt

...and can compile data reports automatically

**Your turn!**

**But now we have completed our  
mission! Really**

P( heart attack |  )?

The New York Times

Opinion

**A.I. Is Harder Than You Think**  
**and Data Science**

By Gary Marcus and Ernest Davis

Mr. Marcus is a professor of psychology and neural science. Mr. Davis is a professor of computer science.

May 18, 2018



P( heart attack |  )?

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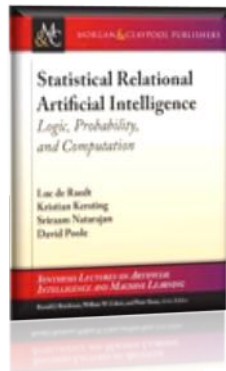
May 18, 2018

Facebook Twitter Email Share Bookmark

P( heart attack |  )?

## Crossover of ML and DS with data & programming abstractions

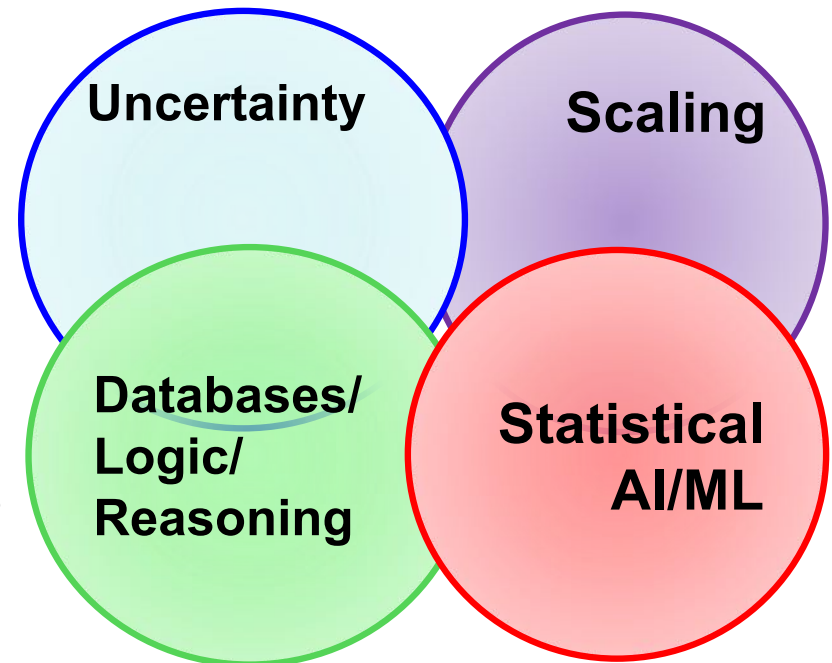
De Raedt, Kersting, Natarajan, Poole: Statistical Relational Artificial Intelligence: Logic, Probability, and Computation. Morgan and Claypool Publishers, ISBN: 9781627058414, 2016.

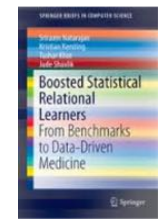


**building general-purpose data science and ML machines**

**make the ML/DS expert more effective**

**increases the number of people who can successfully build ML/DS applications**





# Understanding Electronic Health Records

Atherosclerosis is the cause of the majority of Acute Myocardial Infarctions (heart attacks)



TECHNISCHE UNIVERSITÄT DARMSTADT

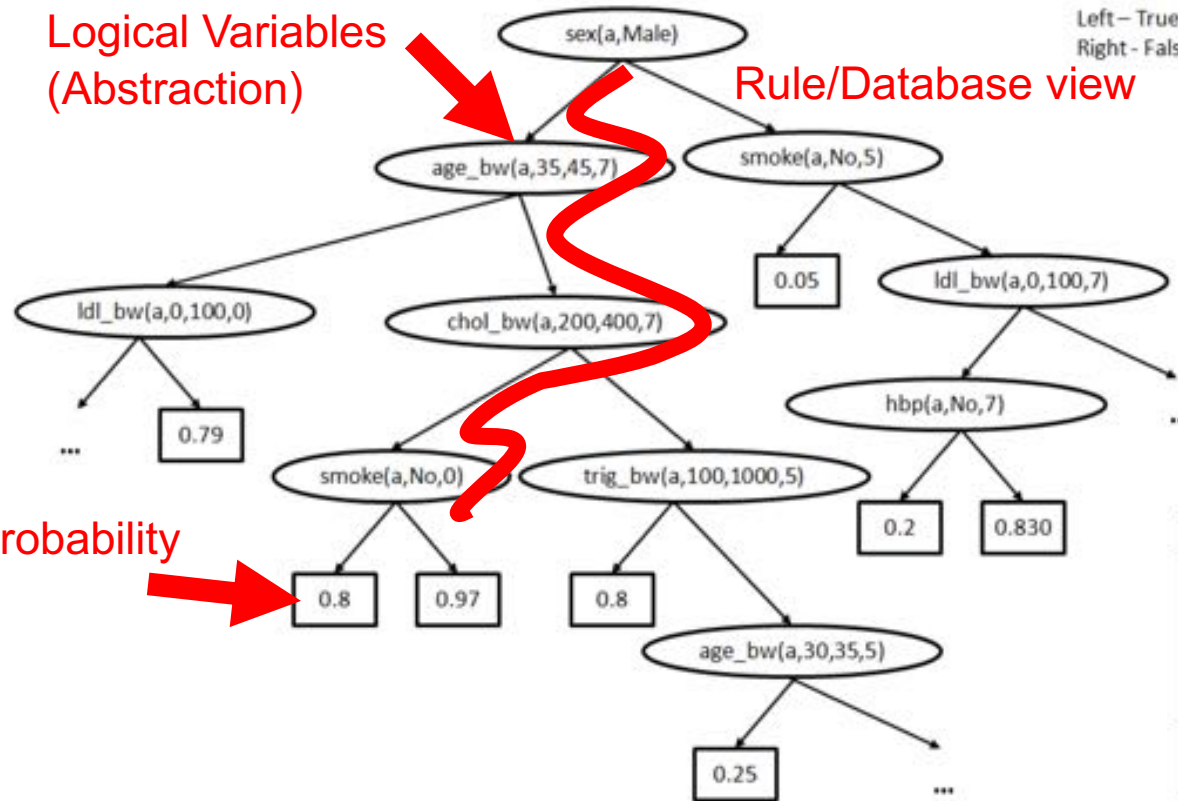


THE UNIVERSITY OF TEXAS AT DALLAS

Logical Variables (Abstraction)

Rule/Database view

Left - True  
Right - False



Plaque in the left coronary artery

[Circulation; 92(8), 2157-62, 1995; JACC; 43, 842-7, 2004]

Probability

Algorithm	Accuracy	AUC-ROC
J48	0.667	0.607
SVM	0.667	0.5
AdaBoost	0.667	0.608
Bagging	0.677	0.613
NB	0.75	0.653
RPT	0.669*	0.778
RFGB	0.667*	0.819

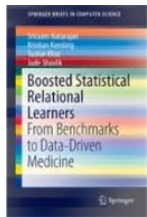
The higher, the better

25%

Algorithm for Mining Markov Logic Networks	Likelihood The higher, the better	AUC-ROC The higher, the better	AUC-PR The higher, the better	Time The lower, the better
<b>Boosting</b>	0.81 ] 11%	0.96 ] 78%	0.93 ] 50%	9s ] 37200x
<b>LSM</b>	0.73 ]	0.54 ]	0.62 ]	93 hrs ] faster

[Kersting, Driessens ICML'08; Karwath, Kersting, Landwehr ICDM'08; Natarajan, Joshi, TadePELLI, Kersting, Shavlik. IJCAI'11; Natarajan, Kersting, Ip, Jacobs, Carr IAAI'13; Yang, Kersting, Terry, Carr, Natarajan AIME'15; Khot, Natarajan, Kersting, Shavlik ICDM'13, MLJ'12, MLJ'15, Yang, Kersting, Natarajan BIBM'17]





<https://starling.utdallas.edu/software/boostsrl/wiki/>



People

Publications

Projects

Software

Datasets

Blog



## BOOSTSRL BASICS

- Getting Started
- File Structure
- Basic Parameters
- Advanced Parameters
- Basic Modes
- Advanced Modes

## ADVANCED BOOSTSRL

- Default (RDN-Boost)
- MLN-Boost
- Regression
- One-Class Classification
- Cost-Sensitive SRL
- Learning with Advice
- Approximate Counting
- Discretization of Continuous-Valued Attributes
- Lifted Relational Random Walks
- Grounded Relational Random Walks

## APPLICATIONS

- Natural Language Processing

## BoostSRL Wiki

**BoostSRL** (Boosting for Statistical Relational Learning) is a gradient-boosting based approach to learning different types of SRL models. As with the standard gradient-boosting approach, our approach turns the model learning problem to learning a sequence of regression models. The key difference to the standard approaches is that we learn relational regression models i.e., regression models that operate on relational data. We assume the data in a predicate logic format and the output are essentially first-order regression trees where the inner nodes contain conjunctions of logical predicates. For more details on the models and the algorithm, we refer to our book on this topic.

Sriraam Natarajan, Tushar Khot, Kristian Kersting and Jude Shavlik, Boosted Statistical Relational Learners: From Benchmarks to Data-Driven Medicine . SpringerBriefs in Computer Science, ISBN: 978-3-319-13643-1, 2015

**Human-in-the-loop learning**

In general, computing the exact posterior is intractable, i.e., inverting the generative process to determine the state of latent variables corresponding to an input is time-consuming and error-prone.

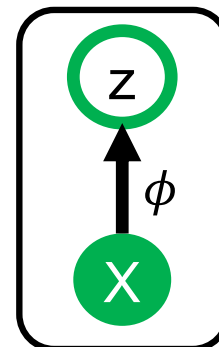
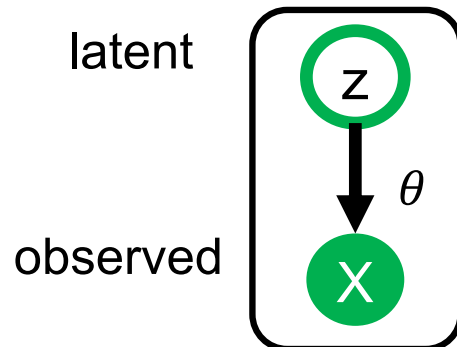
## Deep Probabilistic Programming

```
import pyro.distributions as dist

def model(data):
    # define the hyperparameters that control the beta prior
    alpha_theta = torch.tensor(10.0)
    beta_theta = torch.tensor(10.0)
    # sample f from the beta prior
    f = pyro.sample("latent_fairness", dist.Beta(alpha_theta, beta_theta))
    # loop over the observed data
    for i in range(len(data)):
        # observe datapoint i using the bernoulli
        # likelihood Bernoulli(f)
        pyro.sample("obs_{}".format(i), dist.Bernoulli(f), obs=data[i])
```

```
def guide(data):
    # register the two variational parameters with Pyro.
    alpha_q = pyro.param("alpha_q", torch.tensor(15.0),
                        constraint=constraints.positive)
    beta_q = pyro.param("beta_q", torch.tensor(15.0),
                       constraint=constraints.positive)
    # sample latent_fairness from the distribution Beta(alpha_q, beta_q)
    pyro.sample("latent_fairness", dist.Beta(alpha_q, beta_q))
```

(2) Ease the implementation by some high-level, probabilistic programming language



Deep Neural Network



(1) Instead of optimizing variational parameters for every new data point, use a deep network to predict the posterior given  $X$  [Kingma, Welling 2013, Rezende et al. 2014]

[Stelzner, Molina, Peharz, Vergari, Trapp, Valera, Ghahramani, Kersting ProgProb 2018]

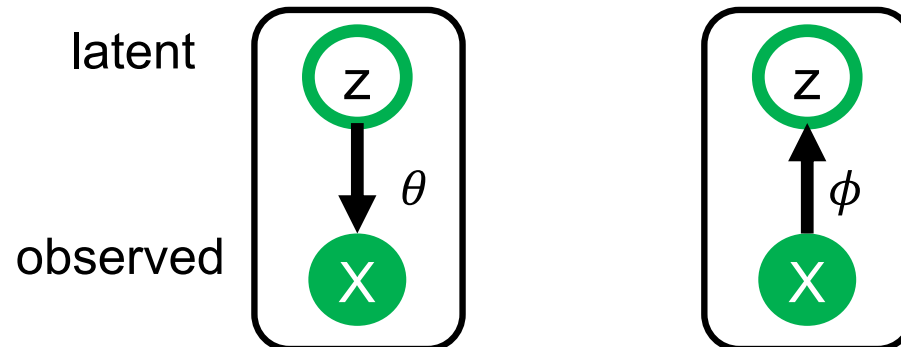
# Sum-Product Probabilistic Programming

```
import pyro.distributions as dist

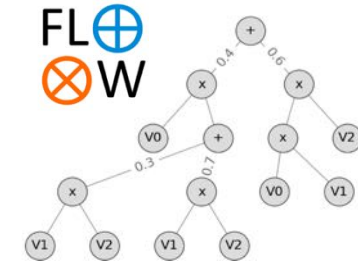
def model(data):
    # define the hyperparameters that control the beta prior
    alpha0 = torch.tensor(10.0)
    beta0 = torch.tensor(10.0)
    # sample f from the beta prior
    f = pyro.sample("latent_fairness", dist.Beta(alpha0, beta0))
    # loop over the observed data
    for i in range(len(data)):
        # observe datapoint i using the bernoulli
        # likelihood Bernoulli(f)
        pyro.sample("obs_{}".format(i), dist.Bernoulli(f), obs=data[i])
```

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```

(2) Ease the implementation by some high-level, probabilistic programming language



Sum-Product Network



Deep Neural Network



(1) Instead of optimizing variational parameters for every new data point, use a deep network to predict the posterior given  $X$  [Kingma, Welling 2013, Rezende et al. 2014]

# Unsupervised scene understanding

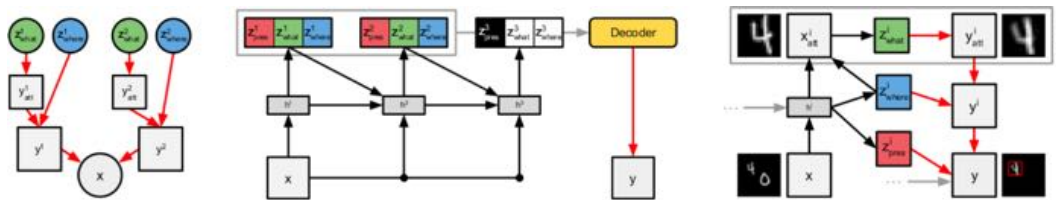
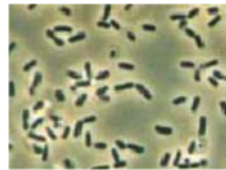
[Stelzner, Peharz, Kersting ICML 2019]



ICML | 2019

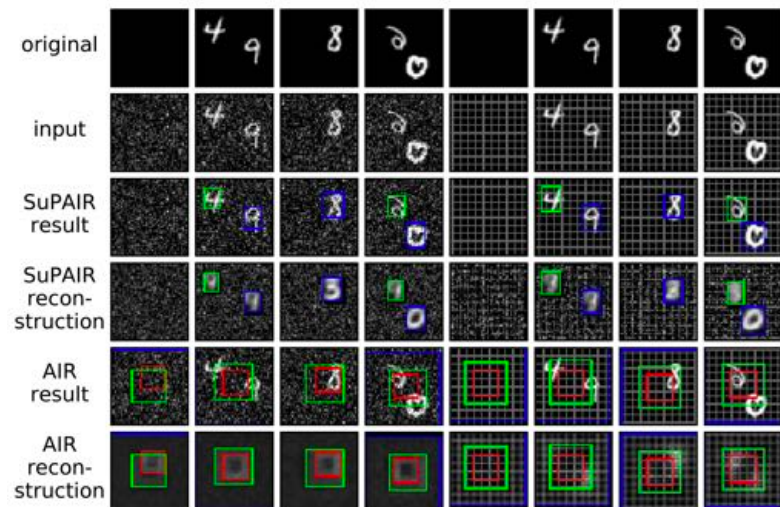
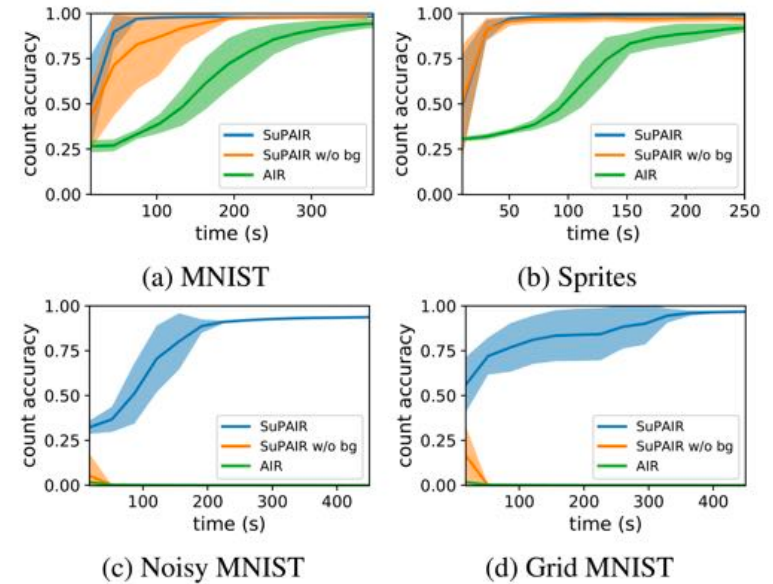
Thirty-sixth International Conference on Machine Learning

Consider e.g. unsupervised scene understanding using a generative model



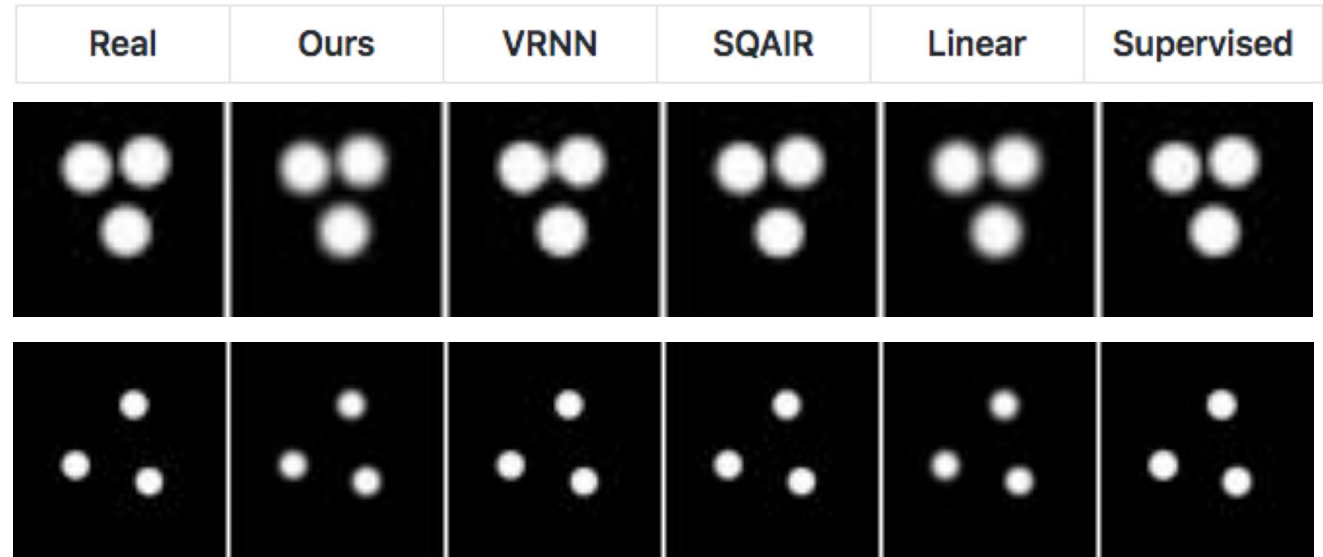
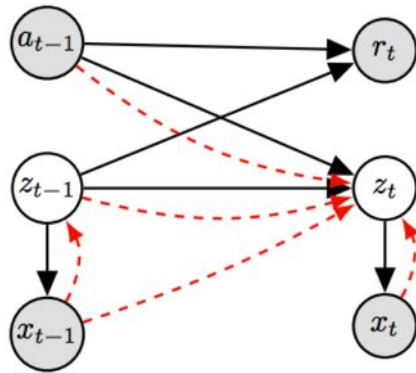
[Attend-Infer-Repeat (AIR) model, Hinton et al. NIPS 2016]

Replace VAE by SPN as object model

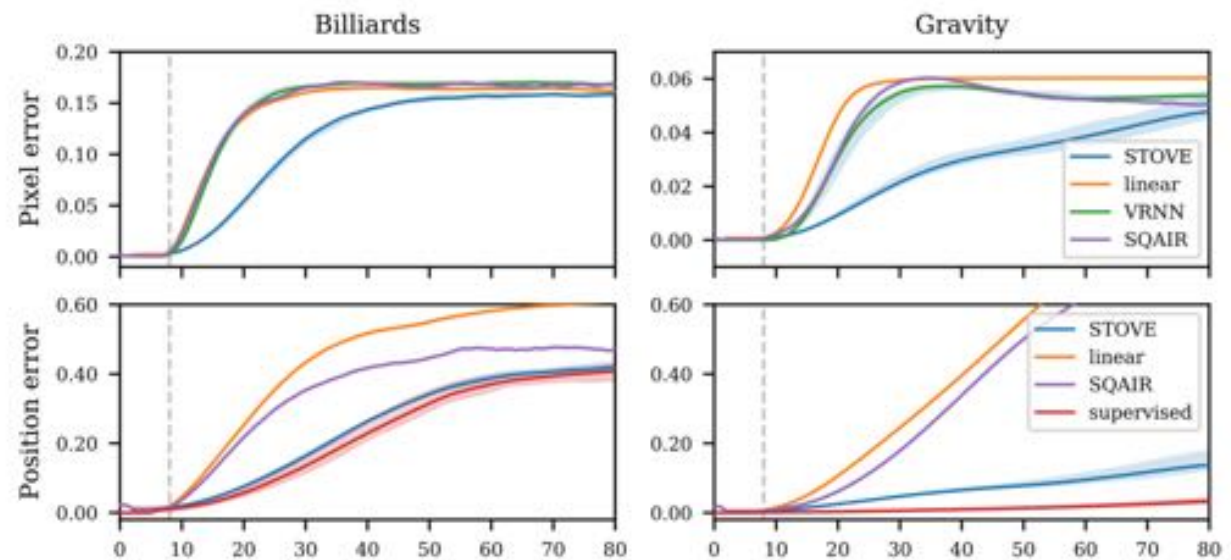


# Unsupervised physics learning

[Kossen, Stelzner, Hussing, Voelcker, Kersting arXiv:1910.02425 2019]



putting  
structure and  
tractable  
inference into  
deep models



# Programming languages for Systems AI,

the computational and mathematical modeling of complex AI systems.

[Laue et al. NeurIPS 2018; Kordjamshidi, Roth, Kersting:  
“Systems AI: A Declarative Learning Based Programming  
Perspective.” IJCAI-ECAI 2018]



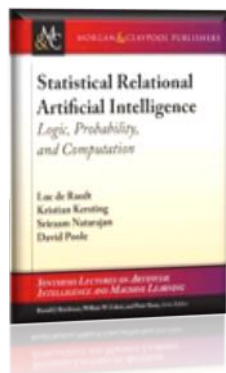
Eric Schmidt, Executive Chairman, Alphabet Inc.: Just Say "Yes", Stanford Graduate School of Business, May 2, 2017. <https://www.youtube.com/watch?v=vbb-AjiXyh0>.

# Since science is more than a single table !

P( heart attack |  )?

## Crossover of ML and AI with data & programming abstractions

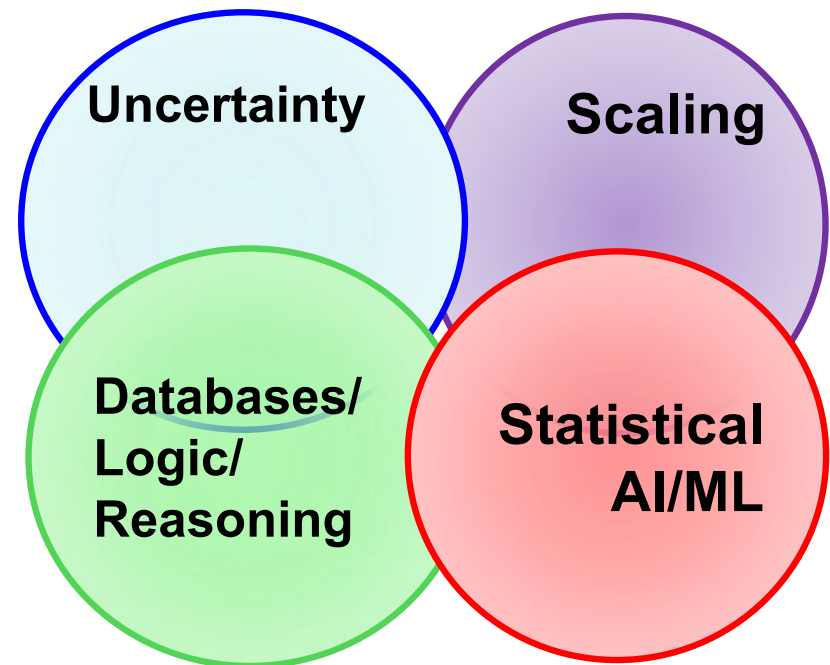
De Raedt, Kersting, Natarajan, Poole: Statistical Relational Artificial Intelligence: Logic, Probability, and Computation. Morgan and Claypool Publishers, ISBN: 9781627058414, 2016.



**building general-purpose AI and ML machines**

**make the ML/AI expert more effective**

**increases the number of people who can successfully build ML/AI applications**

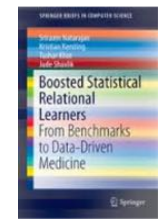


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OF TEXAS AT DALLAS





# Understanding Electronic Health Records

Atherosclerosis is the cause of the majority of Acute Myocardial Infarctions (heart attacks)



TECHNISCHE UNIVERSITÄT DARMSTADT

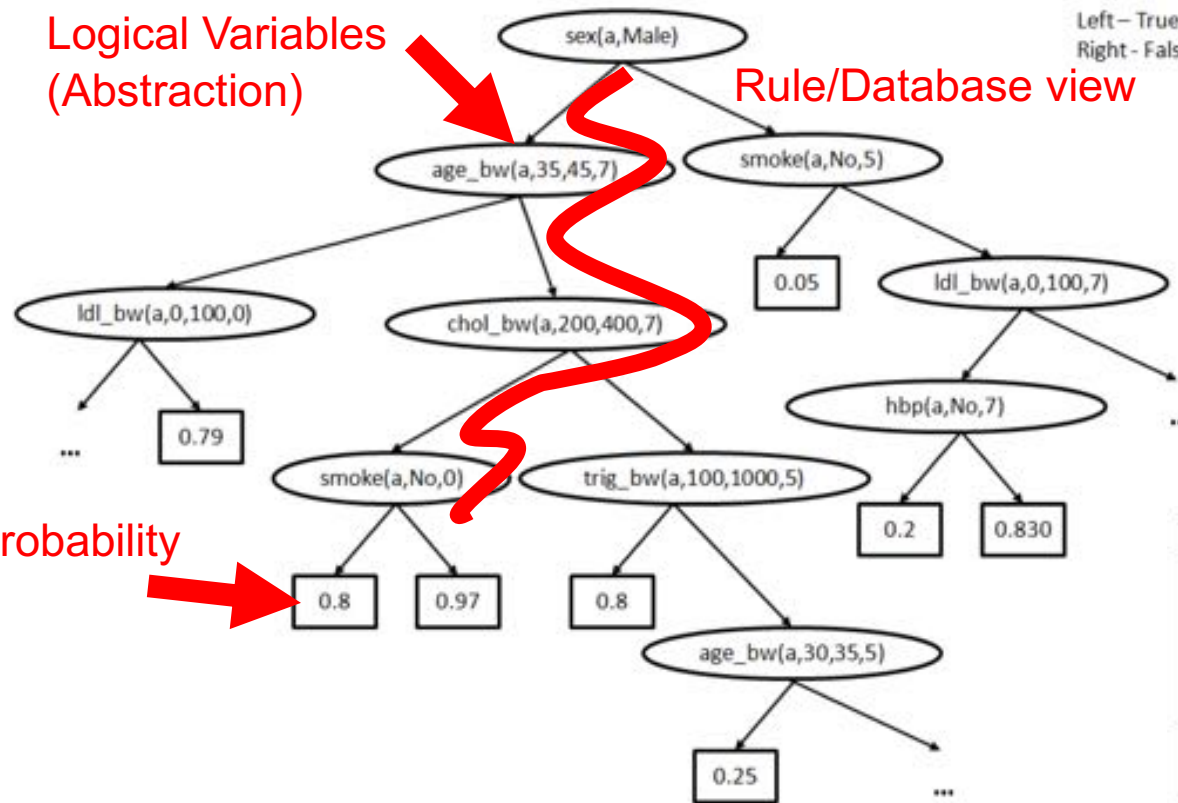


THE UNIVERSITY OF TEXAS AT DALLAS

Logical Variables (Abstraction)

Rule/Database view

Left - True  
Right - False



Plaque in the left coronary artery

[Circulation; 92(8), 2157-62, 1995; JACC; 43, 842-7, 2004]

Probability

Algorithm	Accuracy	AUC-ROC
J48	0.667	0.607
SVM	0.667	0.5
AdaBoost	0.667	0.608
Bagging	0.677	0.613
NB	0.75	0.653
RPT	0.669*	0.778
RFGB	0.667*	0.819

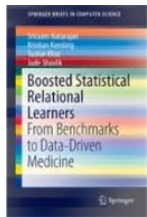
The higher, the better

25%

Algorithm for Mining Markov Logic Networks	Likelihood The higher, the better	AUC-ROC The higher, the better	AUC-PR The higher, the better	Time The lower, the better	state-of-the-art
<b>Boosting</b>	0.81 ] 11%	0.96 ] 78%	0.93 ] 50%	9s ] 37200x	
<b>LSM</b>	0.73 ]	0.54 ]	0.62 ]	93 hrs ] faster	

[Kersting, Driessens ICML'08; Karwath, Kersting, Landwehr ICDM'08; Natarajan, Joshi, TadePELLI, Kersting, Shavlik. IJCAI'11; Natarajan, Kersting, Ip, Jacobs, Carr IAAI '13; Yang, Kersting, Terry, Carr, Natarajan AIME '15; Khot, Natarajan, Kersting, Shavlik ICDM'13, MLJ'12, MLJ'15, Yang, Kersting, Natarajan BIBM'17]





<https://starling.utdallas.edu/software/boostsrl/wiki/>



People

Publications

Projects

Software

Datasets

Blog



## BOOSTSRL BASICS

- Getting Started
- File Structure
- Basic Parameters
- Advanced Parameters
- Basic Modes
- Advanced Modes

## ADVANCED BOOSTSRL

- Default (RDN-Boost)
- MLN-Boost
- Regression
- One-Class Classification
- Cost-Sensitive SRL
- Learning with Advice
- Approximate Counting
- Discretization of Continuous-Valued Attributes
- Lifted Relational Random Walks
- Grounded Relational Random Walks

## APPLICATIONS

- Natural Language Processing

## BoostSRL Wiki

**BoostSRL** (Boosting for Statistical Relational Learning) is a gradient-boosting based approach to learning different types of SRL models. As with the standard gradient-boosting approach, our approach turns the model learning problem to learning a sequence of regression models. The key difference to the standard approaches is that we learn relational regression models i.e., regression models that operate on relational data. We assume the data in a predicate logic format and the output are essentially first-order regression trees where the inner nodes contain conjunctions of logical predicates. For more details on the models and the algorithm, we refer to our book on this topic.

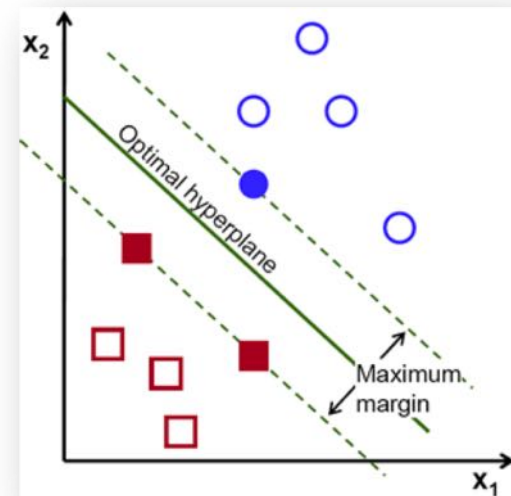
Sriraam Natarajan, Tushar Khot, Kristian Kersting and Jude Shavlik, Boosted Statistical Relational Learners: From Benchmarks to Data-Driven Medicine . SpringerBriefs in Computer Science, ISBN: 978-3-319-13643-1, 2015

**Human-in-the-loop learning**

# Not every scientist likes to turn math into code

$$\min_{\mathbf{w}, b, \xi} \mathcal{P}(\mathbf{w}, b, \xi) = \frac{1}{2} \mathbf{w}^2 + C \sum_{i=1}^n \xi_i$$

subject to  $\begin{cases} \forall i & y_i(\mathbf{w}^\top \Phi(\mathbf{x}_i) + b) \geq 1 - \xi_i \\ \forall i & \xi_i \geq 0 \end{cases}$



Support Vector Machines  
Cortes, Vapnik MLJ 20(3):273-297, 1995

# High-level Languages for Mathematical Programs

Write down SVM in „paper form.“ The machine compiles it into solver form.

```
#QUADRATIC OBJECTIVE
minimize: sum{J in feature(I,J)} weight(J)**2 + c1 * slack + c2 * coslack;

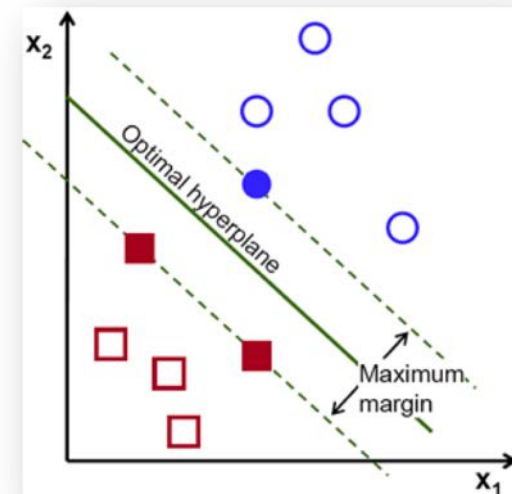
#labeled examples should be on the correct side
subject to forall {I in labeled(I)}: labeled(I)*predict(I) >= 1 - slack(I);

#slacks are positive
subject to forall {I in labeled(I)}: slack(I) >= 0;
```

Embedded within  
Python s.t. loops and  
rules can be used

reloop

RELOOP: A Toolkit for Relational Convex Optimization



Support Vector Machines

Cortes, Vapnik MLJ 20(3):273-297, 1995

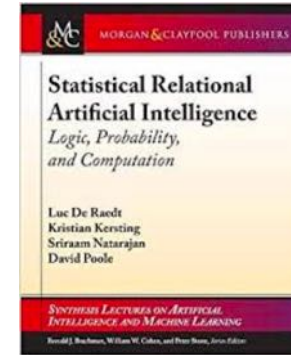
# There are strong invests into high-level programming languages for AI/ML

RelationalAI, Apple, Microsoft and Uber are investing hundreds of millions of US dollars





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Getting deep systems that reason and know when they don't know

Responsible AI systems that explain their decisions and co-evolve with the humans

Open AI systems that are easy to realize and understandable for the domain experts



„Tell the AI when it is right for the wrong reasons and it adapts its behavior“

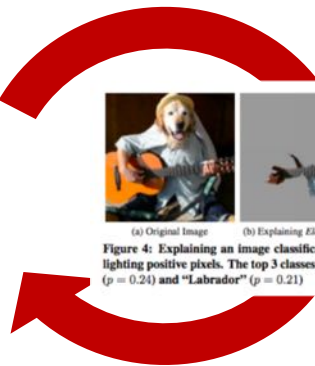


Figure 4: Explaining an image classification prediction made by Google's Inception network, highlighting positive pixels. The top 3 classes predicted are "Electric Guitar" ( $p = 0.32$ ), "Acoustic guitar" ( $p = 0.24$ ) and "Labrador" ( $p = 0.21$ )

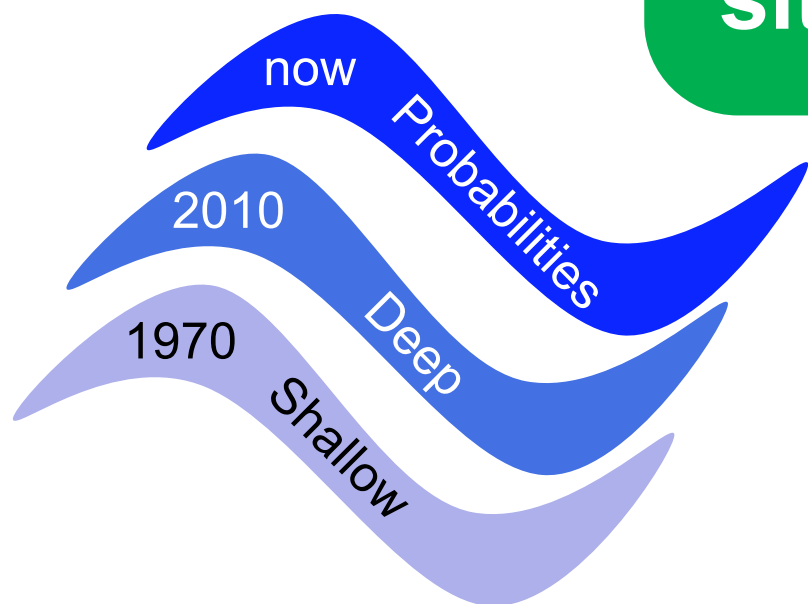
Teso, Kersting AIES 2019



AAAI / ACM conference on  
**ARTIFICIAL INTELLIGENCE,  
ETHICS, AND SOCIETY**

# The third wave of differentiable programming

Getting deep systems that know when they do not know and, hence, recognise new situations and adapt to them



# Overall, AI/ML/DS indeed refine “formal” science, but ...

**AI is more than deep neural networks.** Probabilistic and causal models are whiteboxes that provide insights into applications

**+ AI is more than a single table.** Loops, graphs, different data types, relational DBs, ... are central to ML/AI and high-level programming languages for ML/AI help to capture this complexity and makes using ML/AI simpler

**+ AI is more than just Machine Learners and Statisticians:  
AI is a team sport**

---

**= The Third Wave of AI requires integrative CS, from software engineering and DB systems, over ML and AI to computational CogSci**

**A lot left to be done**

But AI and  
Humans can  
and will be  
partners!



Illustration Nanina Föhr